Real3D

Verification Manual



Computations & Graphics, Inc.

Highlands Ranch, CO 80130, USA Email: <u>info@cg-inc.com</u> Web: <u>www.cg-inc.com</u>

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Table of Contents

END USER LICENSE AGREEMENT FOR CGI SOFTWARE (NON-SDK)	II
Copyright	III
DISCLAIMER	III
NOTICE	III
STATIC - BEAM ELEMENT	1
A-01 (SIMPLE 3D-TRUSS - MODEL TYPE 3D TRUSS)	2
A-01 (SIMPLE 3D-TRUSS - MODEL TYPE 3D FRAME)	4
A-02 (SIMPLE 3D-BEAM)	6
A-03 (BEAM ON GRADE)	8
A-04 (P-delta Beam)	9
A-05 (ROTATIONAL SPRING)	
A-06 (Non-Prismatic Continuous Beam)	
A-07 (2D Steel Frame)	14
A-08 (A SIMPLE SUSPENSION BRIDGE)	16
A-09 (2D Truss with Tension Only Member)	19
A-10 (3D FRAME WITH RIGID DIAPHRAGMS)	21
A-11 (2D FRAME WITH SUPPORT SETTLEMENTS)	23
A-12 (2D FRAME WITH RIGID OFFSETS)	25
A-13 (2D Truss with an Inclined Roller)	27
A-14 (2D Truss with Thermal Load)	29
A-15 (MULTI-DOF CONSTRAINTS - CYCLICALLY SYMMETRIC FRAME)	
A-16 (COUPLED SPRING)	
A-17 (NUMERICALLY CHALLENGING PROBLEM)	
STATIC - SHELL ELEMENT (BENDING)	
B-01 (PLATE PATCH TEST)	38
B-02 (PARAPET)	
B-03 (MORLEY SKEW PLATE)	
B-04 (Fixed Rectangle)	
B-05 (DESIGN STRIP)	
STATIC - SHELL ELEMENT (MEMBRANE)	53
$C \cap 1$ (Memodiane Datch Test)	54
C-01 (MEMBRANE FAICH 1EST)	
C-02 (DLEINDER CANTILEVER)	
C-05 (DATHE MEMBRANE NODAL RESULTANTS)	
STATIC - SHELL FLEMENT	
D-01 ($BATHE MEMBRANE + BEAM$)	03
D-02 (CUKVED DEAM)	03
D-03 (FINCHED C YLINDER)	07
D-04 (SCORDELIS-LU ROOF)	
STATIC RDICK ELEMENT	
	74
E-UI (SLENDER BRICK BEAM)	
E-U2 (UURVED BRICK BEAM)	
E-US (INCOMPATIBLE BRICK)	
E-U4 (DRICK PATCH LEST)	80
E-U3 (NEMISPHERICAL SHELL WITH POINT LOADS)	
DYNAMIC	86
F-01 (SIMPLE 2D FRAME VIBRATION)	
F-02 (2D TRUSS VIBRATION)	89
F-03 (CANTILEVERED TAPERED MEMBRANE VIBRATION)	91
F-04 (CANTILEVER PLATE VIBRATION)	

F-05 (CANTILEVER BRICK VIBRATION)	95
F-06 (2D STEEL FRAME VIBRATION)	97
F-07 (3D FRAME VIBRATION)	99
F-08 (RESPONSE SPECTRUM ANALYSIS OF 4 STORY SHEAR BUILDING)	101
F-09 (RESPONSE SPECTRUM ANALYSIS OF 2D FRAME)	104
F-10 (RESPONSE SPECTRUM ANALYSIS OF 3D FRAME)	106
F-11 (2D FRAME VIBRATION WITH P-DELTA EFFECTS)	108
CONCRETE DESIGN	111
G-01 (FLEXURAL DESIGN OF CONCRETE BEAMS)	112
G-02 (SHEAR DESIGN OF CONCRETE COLUMN)	114
G-02A (SHEAR DESIGN OF CONCRETE BEAMS)	115
G-02B (SHEAR DESIGN OF SAND-LIGHTWEIGHT CONCRETE COLUMN)	11/
G-02C (SHEAR DESIGN OF A COLLECTOR BEAM)	110
G-02D (SHEAR DESIGN OF A COLUMN)	120
G-05 (AXIAL-FLEXURAL DESIGN OF CONCRETE COLUMNS)	120
C 05 (ELEVIDAL DESIGN OF CONCRETE SLENDER COLUMINS)	124
G-05 (FLEXURAL DESIGN OF CANTILEVER CONCRETE SLAB)	124
STEEL DESIGN	126
H-01 (W STEEL BEAM)	127
H-02 (W STEEL DLAM)	127
H-03 (C STEEL COLOMIC)	120
H-04 (HSS STEEL COLUMN)	130
H-05 (ROUND HSS STEEL COLUMN)	131
H-06 (DOUBLE ANGLE STEEL COLUMN)	
H-07 (WT STEEL BEAM).	133
	104
STEP-BY-STEP EXAMPLES	134
EXAMPLE 1: A CANTILEVER BEAM	138
Example 2: A Truss	140
EXAMPLE 3: LINEAR AND NON-LINEAR NODAL SPRINGS	141
EXAMPLE 4: A PORTAL FRAME WITH P-DELTA	143
EXAMPLE 5: RECTANGULAR PLATE	145
EXAMPLE 6: CIRCULAR PLATE ON GRADE	147
EXAMPLE 7: A CANTILEVER PLATE (IN-PLANE)	149
EXAMPLE 8: BRICK PATCH TEST	151
Example 9: Scodelis-Lo Roof	153
Example 10: A Shear Wall	156
EXAMPLE 11: FREQUENCIES OF CANTILEVER BEAM	160
EXAMPLE 12: FREQUENCIES OF RECTANGULAR PLATE	162
EXAMPLE 13: DESIGN OF TWO BRACED CONCRETE COLUMNS	164
EXAMPLE 14: DESIGN OF A CONTINUOUS CONCRETE BEAM	168
EXAMPLE 15: DESIGN OF CONCRETE SLAB.	174
EXAMPLE 10: DESIGN OF STEEL BEAM	185
EXAMPLE 17: DESIGN OF STEEL COLUMN	100
STEEL CALCULATION PROCEDURE	100
General Injo	100
Design Input	100
Design Input	100
Moment Magnification Calculation	200
Major Flexure Capacity Calculation	
Minor Flexure Capacity Calculation	
Flexural and Axial Interaction Calculation	203
Major Shear Capacity Calculation	203
Minor Shear Capacity Calculation	203
Total Load Deflection Check	204
Live Load Deflection Check	204
EXAMPLE 18: RESPONSE SPECTRUM ANALYSIS OF A BEAM	205

REFERENCES

Static - Beam Element

A-01 (Simple 3d-Truss - Model Type 3D Truss)

Objective

To verify the behavior of the 3d truss element.

Problem Description

A simple 3d truss is supported and loaded as shown below. Nodal X, Y, and Z coordinates are given in parenthesis.

Material properties: $E = 200 \text{ KN/mm}^2$, v = 0.3Section properties: $A_{12} = 2e4 \text{ mm}^2$, $A_{13} = 3e4 \text{ mm}^2$, $A_{14} = 4e4 \text{ mm}^2$, $A_{15} = 3e4 \text{ mm}^2$ All members $I_z = 1e10 \text{ mm}^4$, $I_y = 1e10 \text{ mm}^4$, $J = 1e10 \text{ mm}^4$ Nodal forces applied at node 1: $P_x = 200 \text{ KN}$, $P_y = 600 \text{ KN}$, $P_z = -800 \text{ KN}$



Finite Element Model

4 beam elements

Model type: 3D Truss

Results

The displacements and support reactions are given in [Ref 1].

Units: displacement-mm; reaction-KN

		Real3D		[Ref 1]		
	X	Y	Z	Х	Y	Z
Displacement @ N1	0.1779	2.722	-0.4865	0.1783	2.722	-0.4863
Reactions @ N2	-76.39	-152.78	-305.56	-76.4	-152.8	-305.6
Reactions @ N3	170.83	-113.88	-227.77	170.8	-113.8	-227.7
Reactions @ N4	-470.83	-156.94	627.77	-470.7	-156.9	627.8
Reactions @ N5	176.39	-176.39	705.56	176.3	-176.3	705.5

Comments

The results given by Real3D are very close to the referenced values.

The deflection diagram is shown below for illustration purposes.



Reference

[1]. McGuire, Gallagher and Ziemian, "Matrix Structural Analysis" 2nd Edition, pp104, John Wiley & Sons, Inc., 2000

A-01 (Simple 3d-Truss - Model Type 3D Frame)

Objective

To verify the behavior of the 3d frame element with moment releases

Problem Description

A simple 3d truss is supported and loaded as shown below. Nodal X, Y, and Z coordinates are given in parenthesis.

Material properties: $E = 200 \text{ KN/mm}^2$, v = 0.3Section properties: $A_{12} = 2e4 \text{ mm}^2$, $A_{13} = 3e4 \text{ mm}^2$, $A_{14} = 4e4 \text{ mm}^2$, $A_{15} = 3e4 \text{ mm}^2$ All members $I_z = 1e10 \text{ mm}^4$, $I_y = 1e10 \text{ mm}^4$, $J = 1e10 \text{ mm}^4$ Nodal forces applied at node 1: $P_x = 200 \text{ KN}$, $P_y = 600 \text{ KN}$, $P_z = -800 \text{ KN}$



Finite Element Model

4 beam elements

Model type: 3D Frame & Shell

Moment Releases

The following table shows one way to apply moment releases. Please note that we only apply torsional moment release either (not both) end of a member.

Member Id	Start oz	End oz	Start oy	End oy	Start ox	End ox
1	Released	Released	Released	Released	Released	Not Released
2	Released	Released	Released	Released	Released	Not Released
3	Released	Released	Released	Released	Released	Not Released
4	Released	Released	Released	Released	Not Released	Not Released

Results

The displacements and support reactions are given in [Ref 1].

Units: displacement-mm; reaction-KN

		Real3D		[Ref 1]		
	Х	Y	Z	Х	Y	Z
Displacement @ N1	0.1779	2.722	-0.4865	0.1783	2.722	-0.4863
Reactions @ N2	-76.39	-152.78	-305.56	-76.4	-152.8	-305.6
Reactions @ N3	170.83	-113.88	-227.77	170.8	-113.8	-227.7
Reactions @ N4	-470.83	-156.94	627.77	-470.7	-156.9	627.8
Reactions @ N5	176.39	-176.39	705.56	176.3	-176.3	705.5

Comments

The results given by Real3D are very close to the referenced values. The results in this example using 3D Frame & Shell model with moment releases are identical to those in the previous example using 3D Truss model. It is generally easier and more efficient to use 3D Truss model type if your model contains only truss members as the program will automatically suppress global OX, OY and OZ DOFs. On the other hand, 3D Frame and Shell model type (with proper moment releases) should be used if your model contains both truss and frame members.

Reference

[1]. McGuire, Gallagher and Ziemian, "Matrix Structural Analysis" 2nd Edition, pp104, John Wiley & Sons, Inc., 2000

A-02 (Simple 3d-Beam)

Objective

To verify the behavior of the 3d beam element

Problem Description

A simple 3d beam of round section is fixed at one end and loaded at the tip of the other end as shown below.

Lengths: $L_1 = 120$ in, $L_2 = 60$ in Material properties: E = 2.9e7 psi, G = 11.15e6, v = 0.3Section properties: Ix = Iy = 1017.88 in⁴, J = 2023.75 in⁴, Az = 10 in² Tip Force P = 1e4 lb



Finite Element Model

2 beam elements

Model type: 3D Frame & Shell (shear deformation ignored)

Results

The tip vertical displacement Dy at N3 may be calculated as [Ref 1]:

$$D_{y} = \frac{P}{3EI_{x}} (L_{1}^{3} + L_{2}^{3}) + \frac{P}{GL} (L_{1}L_{2}^{2}) = -0.4098$$
 in

	Real3D	Theoretical
Displacement Dy @ N3	-0.4098	-0.4098

Comments

The results given by Real3D are identical to the theoretical values.

The moment, shear and deflection diagrams are shown below for illustration purposes.



Reference

[1]. Long & Bao, "Structural Mechanics", pp146, People's Educational Publishing House, China, 1983.

A-03 (Beam on Grade)

Objective

To verify the behavior of the line spring

Problem Description

A 300 in beam is supported on an elastic foundation and subjected to a point force of -40,000 lb at the middle as shown below [Ref 1]:

Material properties: E = 29,000 ksi, v = 0.3Section properties: $I_z = 125.8 \text{ in4}$, $A = 1 \text{ in}^2$ Elastic line spring constant: $K_y = 1500 \text{ lb} / \text{in}^2$



Finite Element Model

20 beam elements Model type: 2D Frame

Results

The displacement and moment at the middle of the span are given in [Ref 1].

Units: displacement - in; moment - kip-in

@ middle of the span	Real3D	[Ref 1]
Displacement Dy	-0.239	-0.238
Moment Mz	544.44	547

Comments

1. The results given by Real3D are very close to the referenced values.

2. Line springs may be replaced by equivalent nodal springs or even truss elements with appropriate section properties as indicated in [Ref 1].

Reference

[1]. McGuire, Gallagher and Ziemian, "Matrix Structural Analysis" 2nd Edition, pp87, John Wiley & Sons, Inc., 2000

A-04 (P-delta Beam)

Objective

To verify the 2^{nd} -order behavior (P- δ) of beam element

Problem Description

A 12 ft. simply supported beam is subjected to a pair of compressive forces of P = -100 kips at the ends and a transverse point force of Q = -6 kips at the middle as shown below [Ref 1].

Material properties: E = 30e6 psi, v = 0.3Section: 4×4 in ($I_z = 21.3333 \text{ in4}, A = 16 \text{ in}^2$)



Finite Element Model

4 beam elements

Model type: 2D Frame (First order and P-Delta)

Results

The displacement and moment at the middle of the beam may be calculated as follows [Ref 1]:

First order: $M_z = \frac{QL}{4} = 18$ kip-ft; $D_y = \frac{QL^3}{48EI} = 0.583$ in Second order: $u = \frac{L}{2}\sqrt{\frac{P}{EI}} = 0.9$ rad (= 51.57°) $M_z = \frac{QL}{4}\frac{tan(u)}{u} = 25.2$ kip-ft; $D_y = \frac{QL}{4P}\left(\frac{tan(u)-u}{u}\right) = -0.864$ in

Units: displacement - in; moment - kip-in

@ middle of the span	Real3D	[Ref 1]
First-order Displacement Dy	-0.5832	-0.583
First-order Moment Mz	18	18
Second-order Displacement Dy	-0.8643	-0.864
Second-order Moment Mz	25.203	25.2

Comments

1. The results given by Real3D are very close to the referenced values.

2. In order to capture P- δ behavior that is associated with member curvature, the beam must be split into multiple segments. In this example, we used 4 segments and produced satisfactory results. On the other hand, the splitting is not needed to capture P- Δ behavior that is associated with the lateral translation of the frame members.

Reference

[1]. Leet & Bernal, "Reinforced Concrete Design" 3rd Edition, pp294, McGraw-Hill, 1997

A-05 (Rotational Spring)

Objective

To verify the behavior of the rotational spring

Problem Description

A 10-inch-long cantilever beam is subjected to a triangular linear load of q = 2 lb/in. Material properties: E = 2.9e7 psi, v = 0.3Section properties: Ix = 1000 in⁴, Az = 10 in² Boundary condition: rotational spring constant Koz = 1e4 lb-in/rad, Dx and Dy fixed.



Finite Element Model

1 beam element Assign large spring constants to Kx, Ky to represent fixed DOFs Dx, Dy Model type: 2D Frame

Results

The rotational displacement Doz at N1 and vertical displacement Dy at N2 may be calculated as: @N1: $D_{oz} = \frac{(0.5qL)*L/3}{r} = -3.333e^{-3}$ rad

@N2,
$$D_z = D_{oz}L = -3.333e^{-2}$$
 in

Units: displacement – in; rotation - rad

	Real3D	Theoretical
Rotation Doz @ N1	-3.333e-3	-3.333e-3
Displacement Dy @ N2	-3.333e-2	-3.333e-2

Comments

The results given by Real3D are identical to the theoretical values.

The displacements due to beam strains are negligible.

A-06 (Non-Prismatic Continuous Beam)

Objective

To verify the behavior of a non-prismatic beam

Problem Description

A 3-span non-prismatic continuous beam is fixed at the right end as shown below [Ref 1].

Material properties: $E = 1.99948e11 \text{ N/m}^2$, v = 0.3Section properties: width b = 0.1 m, heights as shown (unit: meter)



Finite Element Model

3 beam elements, then use Generate | Non-Prismatic Beams Model type: 2D Frame (do not consider shear deformation)

Results

The moments at supports given by Real3D are compared with those given in [Ref 1].

Unit: moment – KN-m

Real3D				[Ref 1]	
Mz @ B	Mz @ C	Mz @ D	Mz @ B	Mz @ C	Mz @ D
-4.39	-4.24	-9.13	-4.28	-4.21	-9.15

Comments

The results given by Real3D are close to the referenced values.

In Real3D, the non-prismatic beam is approximated by splitting an existing beam into multiple beams (segments) to which different section properties are automatically assigned. The steps to create the model in this problem are as follows:

1. Create 3 (prismatic) beams: AB - 4 m, BC - 6m, CD - 8 m

- 2. Define and assign uniform and point loads on beams
- 3. Assign supports to A, B, C and D
- 4. Define and assign section to beam CD
- 5. Define and assign material to beams AB, BC, and CD.

6. Select the beam AB. Run the command Geometry | Generate | Non-Prismatic Members. Enter the input for "Generate Non-prismatic Members" as follows. The distance list specifies how many beam segments to be used to approximate the non-prismatic beam. In our input, we use one segment for the left 2 m and 10 segments for the right 2 m haunch. More segments could be used to achieve even more accurate result. It should be pointed out that appropriate section properties are assigned to the segmented beams.

Generate Nonprismatic Members							
Enter distance lis these distances:	Enter distance list (e.g. 12, 3@20, 2@15). Selected members with the same length will be exploded at these distances:						
Distance list:	2,10@0.2			m			
Non-Prismatic N	1ember Geometry	/					
Type: Lir	iear 🗸						
Middle depth:	0.5	m	Width:	0.1 m			
Left depth:	0.5	m	Left length ratio:	0.5			
Right depth:	0.7	m	Right length ratio:	0.5			
				OK Cancel			

7. Select the beam BC. Run the command Geometry | Generate | Non-Prismatic Members. Enter the input for "Generate Non-prismatic Members" as follows.

	Generate Nonprismatic Members							
Enter distance list (e.g. 12, 3@20, 2@15). Selected members with the same length will be exploded at these distances:								
Distance list:	Distance list. 10@0.12,3.6,10@0.12 m							
Non-Prismatic M	Non-Prismatic Member Geometry							
Type: Li	near 🗸 🗸							
Middle depth:	0.5	m	Width:	0.1	m			
Left depth:	0.7	m	Left length ratio:	0.2				
Right depth:	0.7	m	Right length ratio:	0.2				
				OK	Cancel			

Reference

[1]. Lin, Liu, Jiang "Structural Statics Calculation Manual", pp. 232, Building Industry Publishing House of China, 1993

A-07 (2D Steel Frame)

Objective

To verify the behavior of the beam element in a large 2D steel frame

Problem Description

A 5-span, 12-story 2D steel frame is subjected to static lateral and vertical loads as shown below. All beams are W24's and all columns are W14's. The lateral loads are in kips and vertical linear loads are in kip/ft (self-weight included).

Material properties: E = 29000 ksi, v = 0.3, density = 483.84 lb/ft³



Floor 1 – 4: W14x90 Floor 5 – 8: W14x68 Floor 9 - 12: W14x48

Beams:

Floor 1 – 4: W24x131 Floor 5 – 8: W24x104 Floor 9 – 12: W24x84

Section	Iz	Iy	J	А	Ay	Az
W14X120	1380	495	9.37	35.3	8.555	23.03
W14X90	999	362	4.06	26.5	6.16	17.1583
W14X68	722	121	3.01	20	5.81	12
W14X48	484	51.4	1.45	14.1	4.692	7.96308
W24X131	4020	340	9.5	38.5	14.8225	20.64
W24X104	3100	259	4.72	30.6	12.05	16
W24X84	2370	94.4	3.7	24.7	11.327	11.5757

Units: Iz, Iy and $J - in^4$, A, Ay and $Az - in^2$

Finite Element Model

132 beam elements

Model type: 2D Frame (shear deformation included)

Results

The displacements and support reactions compared with another program, Frame Analysis & Design (STRAAD) [Ref 1].

	Real3D		Frame Analysis & Design (STRAAD)		
	First order Second order		First order	Second order	
Dx @ node 73	5.981	7.151	5.9762	7.1347	
Rx @ node 3	-36.773	-34.825	-36.7694	-34.8356	
Ry @ node 3	2456.514	2457.846	2456.4503	2457.9036	
Roz @ node 3	303.299	377.605	303.2664	377.6628	

Units: displacement-in; reaction force-kips, reaction moment - kip-ft

Comments

The results given by Real3D are very close to the referenced values.

Reference

[1]. "Frame Analysis & Design", Digital Canal Corporation, Dubuque, Iowa, USA

A-08 (A Simple Suspension Bridge)

Objective

To verify the behavior of the beam element with moment releases

Problem Description

A suspension bridge consists of a 60m long beam fixed on both ends and two 25m long truss members which suspend the beam as shown below.

Lengths: shown in parentheses Material properties: $E = 200 \text{ kN/mm}^2$, v = 0.3Beam Section: $Ix = Iy = J = 0.1 \text{ m}^4$, $Az = 1.0955 \text{ m}^2$ Truss Section: $Ix = Iy = J = 2e-6 \text{ m}^4$, $Az = 0.005 \text{ m}^2$ Uniform load on beam: -10 kN/m



Finite Element Model

5 beam elements (moment release at truss ends connecting the beam)

Model type: 2D Frame (shear deformation ignored)

Results

The displacements and internal forces given by Real3D are compared with the reference [Ref 1].

	Real3D	Ref 1
Displacement Dy @ N2 (m)	-3.970e-003	79400/(EI) = -3.97e-3
Rotation Doz @ N2 (rad)	-2.540e-004	5080/(EI) = -2.540e-004
Maximum (+) Moment in Beam (kN-m)	674.755	675
Maximum (-) Moment in Beam (kN-m)	-682.840	682
Shear at Beam Ends (kN)	42.88	42.8
Shear at Beam Third Point (kN)	100	100
Maximum Axial Force in Trusses (kN)	95.2	95.2

Comments

The results given by Real3D are very close to the referenced values. Since the model contains both truss and beam members, we used 2D Frame model type and applied moment releases to beam elements for truss members.

The reference gives the relationship of section properties as $(EA)_{truss} = (EI)_{beam}/(20m)$. The properties used in the problem were selected based on this assumption. The beam section area is much greater than the truss section area. Therefore, the axial deformation in the beam is practically ignored.

The moment, shear, and axial force diagrams are shown below for illustration purposes.



Shear Diagram (Vy)



Axial Force Diagram (Vx)

Reference

[1]. Long & Bao, "Structural Mechanics", pp279, People's Educational Publishing House, China, 1983.

A-09 (2D Truss with Tension Only Member)

Objective

To verify the behavior of the tension only element

Problem Description

A member connecting node 2 and node 4 is tension only in the 2D truss shown below.

Lengths: shown in parentheses in meters Material properties: $E = 205 \text{ kN/mm}^2$, v = 0.3All Sections: $Az = 1500 \text{ mm}^2$

Loads: as shown



Finite Element Model

8 beam elements, with one member connecting N2-N4 being tension only

Model type: 2D Truss

Results

The displacements and internal forces given by Real3D are compared with the reference [Ref 1].

	Real3D	Ref 1
Displacement Dx @ N3 (mm)	3.469	3.46
Displacement Dy @ N3 (mm)	19.12	19.13
Axial Force in Member connecting N1-N5 (KN)	181.67	181.7

Comments

The results given by Real3D are very close to the referenced values. Since the member connecting N2-N4 is tension only but subjected to compression force, its stiffness is ignored in the 2nd iteration during the solution of this nonlinear model. We can also set the member to be inactive to achieve the same effect. The difference between using tension/compression only members and inactive members is that the former requires non-linear solution while the latter does not (unless other nonlinearities such as non-linear springs or P-Delta analysis exist).

Reference

[1]. William M.C. McKenzie, "Examples in Structural Analysis", pp. 125, Taylor & Francis, 2006.

A-10 (3D Frame with Rigid Diaphragms)

Objective

To verify the behavior of the rigid diaphragms in 3D Frame

Problem Description

A two-story building is subjected two nodal loads in global X direction at two story level nodes. The X-bay and Z-bay distances are both 18 ft. The story height is 12 ft.

Material properties: E = 3155.92 ksi, v = 0.15

All Sections: rectangular 12x12 in.

 $Iyy = Izz = 1728 \text{ in}^4$; $J = 2920.32 \text{ in}^4$;

 $Az = 144 \text{ in}^2$; $Ax = Ay = 120 \text{ in}^2$

Loads: two 20 kips nodal loads in global X direction as shown.



Finite Element Model

Model type: 3D Frame, with rigid diaphragms defined at two story levels. Diaphragm stiffness factor: default value (=10000)

Results

The displacements and support reactions given by Real3D with and without rigid diaphragm actions are shown below.

Displacement	s:
--------------	----

Node Dx (in)		Dy (in)	Dz (in)	Dox	Doy	Doz			
	Diaphragm actions considered								
5	1.01E+00	4.95E-03	6.70E-01	1.01E-03	6.20E-03	-2.01E-03			
6	6 1.01E+00		-6.70E-01	-1.01E-03	6.20E-03	-2.01E-03			
11	11 2.35E+00		6.70E-01	1.01E-03	6.20E-03	-4.03E-03			
12	12 2.35E+00		E-03 -6.70E-01 -1.01E-03		6.20E-03	-4.03E-03			
		Diaphı	ragm actions ig	gnored					
5	8.36E-01	4.17E-03	5.03E-01	8.31E-04	5.99E-03	-1.81E-03			
6	6 8.36E-01 -4.17E-		-5.03E-01	-8.31E-04	5.97E-03	-1.81E-03			
11 2.53E+00 5.72E-03		5.72E-03	5.03E-01	8.31E-04	5.99E-03	-4.23E-03			
12	2.52E+00	-5.72E-03	-5.03E-01	-8.31E-04	5.97E-03	-4.24E-03			

Reactions

Node	Node Rx (kip)		Rz (kip) Rox		Roy	Roz			
	Diaphragm actions considered								
1	-5.42E+00	-1.15E+01	-4.58E+00	-3.37E+01	-7.63E+00	4.30E+01			
2	-5.42E+00	1.15E+01	4.58E+00	3.37E+01	-7.63E+00	4.30E+01			
7	7 -1.46E+01 -1.2		-4.58E+00	-3.37E+01	-7.63E+00	1.10E+02			
8	8 -1.46E+01 1.15E+0		4.58E+00	3.37E+01	-7.63E+00	1.10E+02			
		Diaphı	ragm actions ig	gnored					
1	-3.96E+00	-9.55E+00	-3.12E+00	-2.34E+01	-7.55E+00	3.26E+01			
2	2 -3.96E+00 9.55E+00		3.12E+00	2.34E+01	-7.52E+00	3.26E+01			
7	7 -1.61E+01 -1.34E+01		-3.12E+00	-2.34E+01	-7.55E+00	1.21E+02			
8	-1.60E+01	1.34E+01	3.12E+00	2.34E+01	-7.52E+00	1.21E+02			

Comments

The diaphragm actions are noticeable in this example. Although the model is subjected to unsymmetrical loads, the nodal rotations about global Y axis are the same for nodes on the diaphragms. This means that the diaphragm stiffness factor, which happens to be the default value 10000, is appropriate for this example. The program is also capable of handle slanting diaphragms. For example, you may rotate the model about Z axis by (-30) degrees. Adjust the local angles for horizontal members as well as the nodal forces accordingly. The Dx for the Node 5, 6, 11 and 12 given by the program are 8.769e-001, 8.720e-001, 2.037e+000 and 2.032e+000 in. The correctness can be verified as the following:

Dx @ node 5: 1.01cos30 + 0.00495sin30 = 0.877

A-11 (2D Frame with Support Settlements)

Objective

To verify the behavior of the forced translational and rotational displacements

Problem Description

A frame [Ref 1] is clamped at point A and rolled at points B and C as shown below. The relative flexural stiffness of each element is shown in a circle. No external load is applied to the frame, but the frame is subjected to settlement of fixed support A. Assume that the vertical, horizontal, and angular settlements are a = 2 cm, b = 1 cm, and $\rho = 0.01 \text{ rad}$, respectively.



Finite Element Model

Model type: 2D Frame, without considering frame shear deformation.

The reference does not specify material and section specifically, so we will use steel and rectangular sections (100 mm x 100 mm for vertical members and 200 mm x 100 mm for horizontal member, which satisfy the relative flexural stiffness of members).

 $E = 200 \text{ kN/mm}^2$, $I = 8.33333e + 006 \text{ mm}^4$

Results

The support reactions given by Real3D are shown below.

	Real3D	Ref 1	
Reaction Moz @ A	7.57 kN-m	C1 * EI = $4.5418 * 10^{-3} * (1/m) * 200$ kN/mm ² * $8.333 * 10^{6}$ mm ⁴	
		= 7.5667 kN-m	
Reaction Ry @ B	-0.19 kN	C2 * EI = $-1.119 * 10^{-4} * m^2 * 200$ kN/mm ² * 8.333 * 10 ⁶ mm ⁴	
		= -0.1865 kN	
Reaction Rx @ C	-1.18 kN	C3 * EI = -7.076 * 10^{-4} * m ² * 200 kN/mm ² * 8.333 * 10^{6} mm ⁴	
		= -1.179 kN	

Note: From [Ref 1]

C1 = $4.5418 * 10^{-3}$ (unit: 1/m) C2 = $-1.119 * 10^{-4}$ (unit: 1/m²) C3 = $-7.076 * 10^{-4}$ (unit: 1/m²)

Comments

The results given by Real3D are very close to the referenced values.

Reference

[1]. Igor A. Karnovsky, Olga Lebed, "Advanced Methods of Structural Analysis", pp. 248, Springer Science+Business Media, LLC, 2010.

A-12 (2D Frame with Rigid Offsets)

Objective

To verify the behavior of the rigid offsets

Problem Description

A portal frame [Ref 1] is clamped at point A and D as shown below. The columns are of rectangular size 200mm x 800mm. The beam is of rectangular size 200mm x 1000 mm. The beam is subjected to a uniform load 10 kN/m.



Finite Element Model

Model type: 2D Frame, without considering frame shear deformation.

The reference does not specify material specifically, so we will use concrete with fc = 3ksi.



Results

The following are the moment diagrams for modeling the structure with rigid offsets and without rigid offsets.



	Real3D	Ref 1
	With Rigid Offsets	
Beam Max Negative Moment	11.09 kN-m	11.23 kN-m
Beam Max Positive Moment	16.91 kN-m	16.9 kN-m
Moment Reactions at Supports	5.39 kN-m	5.43 kN-m

Comments

The results given by Real3D are very close to the referenced values. The reference computes moment diagram manually using displacement method. There are noticeable differences between results with rigid offsets and those without.

Reference

[1]. Long & Bao, "Structural Mechanics", pp296, People's Educational Publishing House, China, 1983.

A-13 (2D Truss with an Inclined Roller)

Objective

To verify the behavior of inclined roller using multi-DOF constraint

Problem Description

A truss [Ref 1] is supported by a pinned support at point c and a roller (inclined at 30 degrees from horizontal line) at point b as shown below.

Sections: ab = 20,000 mm², ac = 15,000 mm², bc = 18,000 mm² Material: E = 200 MPa



When creating the inclined roller, we can set any point along the roller angle line as the reference point. For example, if the coordinate at point b is (10.928, 0, 0), then we can set the reference point as $(10.928 + 10 * \cos 30, 10 * \sin 30, 0) = (19.588254, 5, 0)$.

Inclined Roller						
Plane:	XY v					
Referer	ice Point					
×	19.588254 m					
Y:	5					
Z:	0					
Note: An inclined roller can only move along the line between the reference point and the support location						
	Apply to Selected Nodes Cancel					

This effectively creates a multi-DOF constraint as the following:

Multi-DOF Constraint Data							
Constraint equation: factor1 * Q1 = factor2 * Q2 where Q1 and Q2 are displacements in the DOFs at node 1 and 2.							
Node 1 D0E 1 Construint Factor 1 Node 2 D0E 2 Construint Factor 2							
			1	5		1.13203	

Results

The following are the displacements and support reactions given by Real3D and [Ref 1]. The reaction resultant @ b is calculated by hand as following:

 $R = \frac{\frac{383 \times 4 - 321.4 \times \left(\frac{4}{tan(30)}\right)}{10.928 \times cos(30)}}{= -73.4 \text{kN} \text{ (pointing to bottom-right)}.$ $R_x = 73.4 \times sin(30) = 36.7 \text{kN}$ $R_y = -73.4 \times cos(30) = -63.57 \text{kN}$

	Real3D	Ref 1
Displacement Dx @ a	0.9282 mm	0.928 mm
Displacement Dy @ a	1.142 mm	1.143 mm
sqrt(Dx * Dx + Dy * Dy) @ b	0.09416 mm	0.094 mm
Reaction Rx @ c	-419.70 kN	-419.7 kN (by hand)
Reaction Ry @ c	-257.83 kN	-257.83 kN (by hand)
Reaction Rx @ b	36.70 kN (constrained force)	36.70 kN (by hand)
Reaction Ry @ b	-63.57 kN (constrained force)	-63.57 kN (by hand)

Comments

The displacement results given by Real3D are very close to the referenced values. The support reactions are not given in Ref 1 but can be easily calculated by hand, which match exactly with those given by Real3D.

Reference

[1]. W. McGuire & R.H. Gallagher & R.D. Ziemian, "Matrix Structural Analysis" pp. 390, 2nd ed., John Wiley & Sons, Inc., 2000

A-14 (2D Truss with Thermal Load)

Objective

To verify the behavior of thermal load

Problem Description

In the truss [Ref 1] below, all bars are cooled by 20 degrees Celsius. Material: E = 200 MPa, thermal coefficient $\alpha = 1.2e-5$ mm/mm per degree Celsius



Results

The following are the results given by Real3D and [Ref 1].

	Real3D	Ref 1
Displacement Dx @ a	-4.044e-01 mm	-0.4045 mm
Displacement Dy @ a	-6.995e-02 mm	-0.0698 mm
Reaction Rx @ b	0 kN	0 kN
Reaction Ry @ b	-274.01 kN	-274 kN
Reaction Rx @ c	-173.71 kN	-173.8 kN
Reaction Ry @ c	100.29 kN	100.2 kN
Reaction Rx @ d	173.71 kN	173.8 kN
Reaction Ry @ d	173.71 kN	173.8 kN

Comments

The displacement results given by Real3D are very close to the referenced values.

Reference

[1]. W. McGuire & R.H. Gallagher & R.D. Ziemian, "Matrix Structural Analysis" pp. 127, 2nd ed., John Wiley & Sons, Inc., 2000
A-15 (Multi-DOF Constraints - Cyclically Symmetric Frame)

Objective

To verify the multi-DOF constraints to enforce cyclic symmetry

Problem Description

In the frame [Ref 1] below, each of the 16 members is 10 inch long. Material: E = 1.2e7 psi, v = 0.15. Sections: A = 1.0 in², Iyy = Izz = 8.33e-2 in⁴ Four cyclic loads: P = 10 lb Boundary condition: Fixed at the center node (N13)



Finite Element Model

To take advantage of the cyclic symmetry, we are going to model only one quarter of the structure (4-element model) with the following multi-DOF constraints at node 40 and node 30.

$$X_{40} = -Y_{30}$$

 $Y_{40} = X_{30}$
 $Oz_{40} = Oz_{30}$

We can use Geometry->Multi-DOF Constraints->Generic Constraints menu to define these three displacement constraints. Alternatively, we can directly enter the constraints in a spreadsheet from Input Data->Multi-DOF Constraints menu.



Results

To illustrate, the following shows the identical Mz moment diagrams for both 16-element model and 4-element model.



Reference

[1]. ADINA Verification Manual, ADINA R & D Inc., Example A.40, June 2001

A-16 (Coupled Spring)

Objective

To verify the behavior of coupled spring which is useful in modeling bridge foundations.

Problem Description

In the 10 meter column [Ref 1] below, the top is subjected to the loads: Fx = 100.00 (kN), Fy = 200.00 (kN), Fz = -3000.00 (kN), Mx = 400.00 (kN-m), My = 500.00 (kN-m) and Mz = 600.00 (kN-m).

Material: E = 3.25e+07 kN/ m², v = 0.20. Sections: Izz = 0.0104 m⁴, Iyy = 0.0417 m⁴, J = 0.0286 m⁴, A= 0.5 m², Ay = 0.4167 m², Az = 0.4167 m²



The bottom of the column is supported by a coupled spring with the following stiffness matrix terms (see "Calculation of Coupled Spring Stiffness Terms" below)

Kox, Kx x Kox, Ki	,Koy, Kx_Koz, Ky ox Koy, Kox Ko	/_Kox, Ky_Koy, H z, Kov_Kov, Kov	(y_Koz, Ky_Kox, ' Koz, Koz Koz I	Ky_Koy, Ky_Koz Jnit kN-m/rad	Unit kN/rad	
lease en	ter the upper ha	If of the coupled	spring stiffness i	matrix (6 × 6):		
	Kx	Ку	Kz	Kox	Koy	Koz
Kx	20924	3	-397	-146	-61877	-7053
Ку		25392	-99	73496	146	25154
Kz			85866	27722	-75466	-40
Kox				834246	-22675	71093
Koy					1678748	22601
Koz						565518

Calculation of Coupled Spring Stiffness Terms

The stiffness matrix terms of the coupled spring used in this example are calculated based on the following simplified bridge piers below. On the left is the full pier (column + foundation) model A while on the right is the foundation-only model B. In order to compute the stiffness matrix of the coupled spring, 6 loads in separate load cases (1000 kN for Px, Py and Pz; 1000 kN-m for Mx, My and Mz) are applied at the bottom of the column in Model B. We first solve the model B to obtain displacement matrix (displacements for each of these load cases).

	Displacements matrix, m, rad									
Px	0.054200	-0.000621	0.002081	-0.000001	0.002083	0.000621				
Ру	-0.000621	0.054930	0.001592	-0.004734	0.000005	-0.001856				
Pz	0.002081	0.001592	0.012380	-0.000534	0.000626	-0.000002				
Mx	-0.000001	-0.004734	-0.000534	0.001633	-0.000002	0.000005				
My	0.002083	0.000005	0.000626	-0.000002	0.000701	-0.000002				
Mz	0.000621	-0.001856	-0.000002	0.000005	-0.000002	0.001858				

We then invert the displacement matrix to obtain the stiffness matrix. Note the stiffness matrix is multiplied by 1000 so the stiffness terms are in the right units as shown below.

Stiffness matrix, kN/m, kN/rad, kN-m/rad									
Px	20924	3	-397	-146	-61877	-7053			
Ру	3	25392	-99	73496	146	25154			
Pz	-397	-99	85866	27722	-75466	-40			
Mx	-146	73496	27722	834246	-22675	71093			
My	-61877	146	-75466	-22675	1678748	22601			
Mz	-7053	25154	-40	71093	22601	565518			





Results

The nodal displacements in the coupled spring model are very close to those obtained from the full model A. This illustrates that a coupled spring can be used to simplify the modeling of a bridge sub-structures effectively.

	Model v	vith a Couple	d Spring	Full Model A			
	X	X Y Z		X	Y	Z	
Displacement @ Top (m)	3.961e-02	1.706e-01	-3.667e-02	3.961e-02	1.706e-01	-3.668e-02	
Rotation @ Top (rad)	-1.971e-02	6.763e-03	1.629e-02	-1.971e-02	6.763e-03	1.629e-02	
Displacement @ Bottom (m)	2.551e-03	1.261e-02	-3.482e-02	2.554e-03	1.261e-02	-3.483e-02	
Rotation @ Bottom (rad)	-1.957e-03	-6.161e-04	7.998e-04	-1.957e-03	-6.159e-04	7.997e-04	

A-17 (Numerically Challenging Problem)

Objective

To verify the behavior of quad-precision skyline solver.

Problem Description

The following 210 meters continuous bridge is discretized into multiple segments: 0.1, 2.9, 20@3, 0.1, 2.9, 27@3, 0.1, 2.9, 20@3 meters. Each segmented beam is subjected to a uniform load of -12.9368 kN/m.

Material: E = 210 kN/mm², v = 0.25. Sections: Izz = 1.0E12 mm⁴, Iyy = 2.58049E11 mm⁴, J = 1.0E12 mm⁴, A= 164800 mm², Ay = Az = 0.0 mm²

Supports:

@Node 2: restrained in Dx, Dy, Dz, and Dox

@Node 24: restrained in Dy, Dz, and Dox. There is a large support settlement of 368.571 mm in Z direction.

@Node 53: restrained in Dy, Dz, and Dox

Results

The following table lists the support reactions at Node 2, 24, and 53. The total support reaction in Z direction should be 210 m * 12.9368 kN/m = 2716.728 kN. As we can see, both double-precision skyline solver and sparse solver give inaccurate support reaction at node 24. The reason for this inaccuracy is due to the following:

- 1. There is a large stiffness variation between adjacent beams at the support
- 2. The support settlement is large
- 3. Real3D uses penalty approach to enforce support restraints when constructing global stiffness matrix.

This results in large truncation and round off errors with double-precision arithmetic operations during the solution. The quad-precision solver gives accurate support reaction at node 24.

	Double-precision skyline solver	Double-precision sparse solver	Quad-precision skyline solver
Support Reaction Rz @Node 2 (kN)	197.99	197.99	197.99
Support Reaction Rz @Node 24 (kN)	1006.31	972.34	1015.12
Support Reaction Rz @Node 53 (kN)	1503.62	1503.62	1503.62
Sum of Support Reaction Rz (kN)	2707.92	2673.95	2716.73

Static - Shell Element (Bending)

B-01 (Plate Patch Test)

Objective

To verify the plate (MITC4 thick plate formulation) passes the patch test

Problem Description

A plate of size $0.12 \ge 0.24$ in is subjected to forced displacements at the four corners as shown below. The boundary conditions are:

w = 1.0e⁻³(x² + xy + y²) / 2

$$\theta_x = \frac{\partial w}{\partial y} = 1.0e^{-3}(y + x/2)$$
; $\theta_y = -\frac{\partial w}{\partial x} = 1.0e^{-3}(-x - y/2)$
Material properties: E = 1.0e6 psi, v = 0.25

Geometry: nodal coordinates are shown in the parenthesis below, thickness t = 0.001 in



Finite Element Model

5 shell elements

Model type: 2D Plate Bending (MITC4 thick plate formulation) Forced displacements on boundary nodes:

Units: displacement – in; rotation - rad

Boundary Nodes	Displacement Dz	Rotation Dox	Rotation Doy
1	0	0	0
2	2.88e-5	1.20e-4	-2.40e-4
3	7.20e-6	1.20e-4	-6.00e-5
4	5.04e-5	2.40e-4	-3.00e-4

Results

The displacements of internal nodes can be calculated based on the boundary conditions. The generalized strains and stresses may be calculated as follows:

$$\begin{split} \phi_x &= \frac{\partial^2 w}{\partial x^2} = 1.0e^{-3}; \ \phi_y = \frac{\partial^2 w}{\partial y^2} = 1.0e^{-3}; \\ \phi_{xy} &= 2\frac{\partial w}{\partial x}\frac{\partial w}{\partial y} = 1.0e^{-3} \\ \begin{pmatrix} M_{xx} \\ M_{yy} \\ M_{xy} \end{pmatrix} &= \frac{Et^3}{12(1-\nu^2)} \begin{pmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & (1-\nu)/2 \end{pmatrix} \begin{pmatrix} \varphi_x \\ \varphi_y \\ \varphi_{xy} \end{pmatrix} = \begin{pmatrix} 1.11e - 7 \\ 1.11e - 7 \\ 3.33e - 8 \end{pmatrix} \end{split}$$

The constant stresses are also given by [Ref 1].

		Real3D		Theoretical				
Nodes	Dz	Dox	Doy	Dz	Dox	Doy		
5	1.40e-6	4.00e-5	-5.00e-5	1.40e-6	4.00e-5	-5.00e-5		
6	1.935e-5	1.20e-4	-1.95e-4	1.935e-5	1.20e-4	-1.95e-4		
7	2.24e-5	1.60e-4	-2.00e-4	2.24e-5	1.60e-4	-2.00e-4		
8	9.60e-6	1.20e-4	-1.20e-4	9.60e-6	1.20e-4	-1.20e-4		

Units: displacement - in; rotation - rad

Units: moment – lb-in/in

	Real3D			[Ref 1]	
Mxx	Муу	Mxy	Mxx	Муу	Mxy
1.11e-7	1.11e-7	3.33e-8	1.11e-7	1.11e-7	3.33e-8

Comments

The results given by Real3D are identical to the theoretical and referenced values.

A patch test consists of creating a small "patch" of elements and then imposing an assumed displacement field at the boundary nodes. The assumed displacement field is chosen such that it causes a constant stress in the mesh. To pass the patch test, computed displacements at the interior nodes must be consistent with the assumed displacement field and the computed stresses must be constant. Patch tests are important because they ensure solution convergence—so that increasing mesh fineness results in more accurate results.

The MITC4 plate formulation passes the patch test. The Kirchhoff plate formulation passes the patch test if the elements are rectangular. The Kirchhoff plate formulation is not applicable here.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

[2]. Cook, Malkus, Plesha, Witt, "Concept and Applications of Finite Element Analysis" 4th Edition, pp238, John Wiley & Sons, Inc., 2002

B-02 (Parapet)

Objective

To verify the plate (Kirchhoff thin plate formulation) element under constant twist

Problem Description

A plate of size 240 x 240 in is subjected to a transverse point load of -10,000 lb at a corner D as shown below. The boundary lines AB and AC are simply supported. Material properties: E = 2.9e+007 psi, v = 0.30Thickness t = 10 in



Finite Element Model

100 shell elements Model type: 2D Plate Bending (Kirchhoff thin plate formulation)

Results

The displacements, internal forces, and moments may be calculated as follows [Ref 1]:

$$M_{xx} = M_{yy} = 0;$$

$$M_{xy} = -P/2 = -5,000 \text{ lb-in/in}$$

$$V_{xx} = V_{yy} = 0$$

$$w_D = \frac{P_{xy}}{2(1-\nu)} \frac{12(1-\nu^2)}{Et^3} = -0.1549 \text{ in}$$

Units: displacement – in; moment – lb-in/in

Rea	ll3D	[Ref 1]			
Moment Mxy	Displacement Dz @ point D	Moment Mxy	Displacement Dz @ point D		
5,000	-0.1549	5,000	-0.1549		

Comments

The results given by Real3D are identical to the theoretical values.

This is an interesting problem which has practical applications (such as parapet at the corner of a building). It shows that a plate structure may have pure twist Mxy (Mxx = Myy = 0). Generally, for a homogeneous material such as steel, the strength should be checked based on principal stresses. For a non-homogeneous material such as concrete, the strength should be checked based on principal moments (not just Mxx and Myy). In this example, reinforcement should be placed as shown below. The solid lines represent the top reinforcement while the dashed lines do the bottom reinforcement.



In practical applications for concrete slabs, reinforcement placed based on principal moments will be difficult. Alternative methods are available. One of these methods is the so-called Wood-Armer method [Ref 2]. It takes into account Mxy as well as Mxx and Myy for calculating top and bottom reinforcement in two orthogonal directions x and y.

Reference

[1]. Z.L Xu, "Elastic Mechanics" 3rd Ed., pp58, High Education Publishing House, China 1994 ISBN 7-04-002893-X/TB.159

[2]. Park & Gamble "Reinforced Concrete Slab", pp202, John Wiley & Sons, Inc., 1980

B-03 (Morley Skew Plate)

Objective

To verify the behavior of the MTC4 thick plate bending element in a skew shape

Problem Description

A skewed, simply supported plate is loaded with a uniform pressure load of 1 psi. Material properties: E = 1e5 psi, v = 0.3Geometric properties: L = 100 in, h = 1 in



Finite Element Model

16, 64, 256, 1024 shell elements Model type: 2D Plate Bending (MITC4 thick plate formulation)

Results

The displacement at the plate center (C) is given by [Ref 1].

Unit: displacement - in

Displacement Dz	Real3D	[Ref 1]
4 x 4 mesh	3.9182	3.9182
8 x 8 mesh	3.8991	3.8991
16 x 16 mesh	4.1875	4.1875
32 x 32 mesh	4.4098	4.4098

Comments

The displacements given by Real3D are identical to the referenced values. The correct theoretical displacement is given as 4.640 in.

Reference

[1]. Sa, Jorge, Valente and Areias "Development of shear locking-free shell elements using an enhanced assumed strain formulation", International Journal of Numerical Methods in Engineering, 2002; 53: 1721-1750

B-04 (Fixed Rectangle)

Objective

To verify the behavior of the MTC4 thick plate and the Kirchhoff thin plate bending elements

Problem Description

A 3.2 x 2 in rectangular plate is fixed on all edges and subjected to a uniform pressure of q = -1e-4 psi as shown below.

Material properties: E = 1.7472e7 psi, v = 0.3Thickness: t = 1e-4 in



Finite Element Model

100 shell elements Model type: 2D Plate Bending (MITC4 thick plate and Kirchhoff thin plate)

Results

The displacements and stresses are compared with those produced by another program, ADINA. Theoretical results are calculated as follows [Ref 1]:

Displacement @ center: $D_z = \frac{0.0251*qb^4}{Et^3} = 2.299$ in Stress @ center of long edge: $\sigma_y = \frac{0.4680*qb^2}{t^2} = 1.872e4$ psi Stress @ center: $\sigma_y = \frac{0.2286*qb^2}{t^2} = 9.144e3$ psi

	Rea	ll3D			
	MITC4 (thick)	Kirchhoff (thin)	ADINA	Theoretical	
Displacement Dz @ center	-2.274	-2.342	-2.274	-2.299	
Max Rotation Dox	3.653	3.608	3.653	-	
Max Rotation Doy	2.502	2.373	2.502	-	
Stress Sxx @ center of short edge	7507	12927	7507	-	
Stress Sxx @ center	-4880	-4763	-4880	-	
Stress Syy @ center of long edge	13478	18743	13478	18720	
Stress Syy @ center	-9143	-9483	-9143	-9144	
Max Stress Sxy	2556	2459	2556	-	

Units: displacement – in; rotation – rad; stress - psi

Comments

The results given by Real3D using the MITC4 are identical to those given by another reputable finite element program, ADINA. The results also compare well with the theoretical results based on the thin plate theory. The stress prediction of the MITC4 thick plate at the boundary is less accurate than that of the Kirchhoff thin plate. This is because the stresses at element nodes are more representative of element center stresses for MITC4 plate formulation. A much finer meshing would be needed to capture nodal stresses accurately at the boundary.

One way to work around this is to calculate the element nodal stresses at the boundary based on the support reactions. For example, to calculate the stress Sxx at the center of the short edge, we first find the support reaction at the center node of the short edge Roy = -4.467e-06 lb-in, then divide it by the tributary length of 0.2 in which gives linear moment Mxx = 2.234e-5 lb-in/in. Then the Sxx stress is calculated as the following:

Mxx / $(t^2 / 6) = 2.234e-5 / (0.0001^2 / 6) = 13404$ psi.

Similarly, to calculate the stress Syy at the center of the long edge, we first find the support reaction at the center node of the long edge Rox = -9.991e-06 lb-in, then divide it by the tributary length of 0.32 in which gives linear moment Myy = 3.122e-5 lb-in/in. Then the Syy stress is calculated as the following:

Myy / $(t^2 / 6) = 3.122e-5 / (0.0001^2 / 6) = 18732$ psi (very close to the theoretical 18720 psi).

The following illustrates displacement and stress contours (not smoothed) based on the MITC4 thick plate.





Displacement DOX [rad, + and -]



Dox Displacement Contour

Displacement DOY [rad, + and -]

2.502e+000											_
2.190e+000	0.330	0.330	0.296	0.173	0.078	-0.078	-0.173	-0.296	-0.330	-0.330	
1.877e+000	1.067	1.067	0.967	0.595	0.268	-0.268	-0.595	-0.967	-1.067	-1.067	
1.564e+000		_									
1.251e+000	1.807	1.807	1.667	1.062	0.483	-0.483	-1.062	-1.667	1.807	-1.807	
9.384e-001	<mark>- 2.320</mark>	2.320	2.178	1.406	0.649	-0.64 <mark>9</mark>	-1.406	-2.178	-2.320	- <mark>2.</mark> 320	
6.256e-001 🗕											
3.128e-001	2.502	2.502	2.363	1.532	0.710	-0.710	-1.532	-2.363	-2.502	-2.502	
-3.822e-008	2.502	2.502	2.363	1.532	0.7 <mark>1</mark> 0	-0. <mark>710</mark>	-1.532	-2. <mark>363</mark>		-2.502	
-3.128e-001	2.320	2.320	2.178	1.406	0.649	-0.6 <mark>49</mark>	-1.406	-2.178	-2.320	<mark>-2.3</mark> 20	
-6.256e-001											
-9.384e-001	1.807	1.807	1.667	1.062	0.483	-0.483	-1.062	-1.667	-1.807	-1.807	
-1.251e+000	1.067	1.067	0.967	0.595	0.268	-0.268	-0.595	-0.967	-1.067	-1.067	
-1.564e+000 💻											
-1.877e+000	0.330	0.330	0.296	0.173	0.078	-0.078	-0.173	-0.296	-0.330	-0.330	
-2.190e+000											

Doy Displacement Contour

7.507e+003	_										
6.733e+003	1748.96	2201.90	3283.55	3863.05	4043.32	4043.32	3863.05	3283.55	2201.90	1748.96	Γ
5.959e+003	3380.25	437.49	-576.11	855.89	982.05	982.05	855.89	-576.11	437.49	3380.25	
5.184e+003	_										
4.410e+003	5419.74	-878.18	-2454.19	-2461.80	-2190.63	-2190.63	-2461.80	-2454.19	-878.18	5419.74	
3.636e+003	6961.36	-1445.74	-3868 .80	-4140.81	-3913.75	-3913.75	-4140.81	- 38 68.80	-1445.74	6961.36	
2.862e+003 🗕	7500.00	4002.44	4470.40	4070.00	4070.05	4070.05	4070.00	4470.40	4002.44	700.00	-
2.088e+003	7506.86	-1692.14	-4470.40	-4879.92	-4679.85	-4679.85	-4879.92	-4470.40	-1692.14	7506.86	
1.313e+003	7506.86	-1692.14	-4470,40	-4879.92	-4679.85	-4679.85	-4879.92	-4470.40	-1692.14	7506.86	
5.393e+002	6961.36	-1445.74	-3868.80	-4140.81	-3913.75	-3913.75	-4140.81	-3868.80	-1445. <mark>7</mark> 4	6961.36	
-2.349e+002											<u> </u>
-1.009e+003	5419.74	-878.18	-2454.19	-2461.80	-2190.63	-2190.63	-2461.80	-2454.19	-878.18	5419.74	
-1.783e+003	3380.25	437.49	-576.11	855.89	982.05	982.05	855.89	-576.11	437.49	3380.25	
-2.557e+003 🗕	1710.00	0001.00	0000 55	0000.05	10.10.00	10.10.00	0000.05	0000 55	0001 00	1710.00	-
-3.332e+003	1748.96	2201.90	3283.55	3863.05	4043.32	4043.32	3863.06	3283.55	2201.90	1748.96	
-4.106e+003											
-4.880e+003											

Stress Sxx-Top [lb/in^2, + and -]

-2.502e+000

Sxx Stress Contour

Stress Syy-Top [lb/in^2, + and -]

1.348e+004	_									
1.206e+004	<mark>2</mark> 829.20	7339.67	10945.18	12876.82	13477.75	13477.75	12876.82	10945.18	7339.67	2829.20
1.065e+004	1557.68	1763.56	2860.98	3717.69	3985.52	3985.52	3717.69	2860.98	1763.56	1557.68
9.236e+003										
7.823e+003	1625.92	-1655.27	- <mark>2</mark> 677.38	-2939.01	-2904.43	-2904.43	-2939.01	-2677.3 <mark>8</mark>	-1655.27	1625.92
6.409e+003	2088.41	-3519.82	-5877.15	-6907 <mark>.11</mark>	-7143.48	-7143.48	-69 <mark>0</mark> 7.11	-5877.15	-3519. <mark>8</mark> 2	2088.41
4.995e+003 🗕										
3.581e+003	2252.06	-4341.14	-7347.78	-8777.46	-9143.01	-9143.01	-8777.46	-73 47.78	-4341.14	2252.06
2.167e+003	2252.06	-4341.1 <mark>4</mark>	-7347 <mark>.78</mark>					<mark>-73</mark> 47.78	- <mark>4</mark> 341.14	2252.06
7.536e+002	2088.41	-3519.82	-5877.15	-690 <mark>7.11</mark>	-7143.48	-7143.48	-690 <mark>7</mark> .11	-5877.15	-3519. <mark>8</mark> 2	2088.41
-6.602e+002										
-2.074e+003	1625.92	-1655.27	-2677.37	-2939.01	-2904.43	-2904.43	-2939.01	-2677.38	-1655.27	1625.92
-3.488e+003	1557.68	1763.56	2860.98	3717.69	3985.52	3985.52	3717.69	2860.98	1763.56	1557.68
-4.902e+003 🗕				/			<u>\</u>			
-6.315e+003	2829.20	7339.67	10945.18	12876.82	13477.75	13477.75	12876.82	10945.18	7339.67	2829.20
-7.729e+003										

Syy Stress Contour

2.556e+003	_										
2.236e+003	-1107.94	-1605.55	-1286.32	-713.64	-262.91	262.91	713.64	1286.32	1605.55	1107.94	
1.917e+003	-1 <mark>923.26</mark>	-2551.90	-2172.63	-1313.27	-504.93	504. <mark>93</mark>	1313.27	2172.63	2551.90	<mark>192</mark> 3.2 <mark>6</mark>	_
1.597e+003											
1.278e+003	-1927.12	-2555.76	-2222.7 2	-1388.79	-548.97	548.97	1388.79	2222.72	2555.76	1927.12	
9.584e+002	-1421,14	-1968.84	-1772.58	<mark>-112</mark> 0.57	<mark>-45</mark> 3.29	453. <mark>2</mark> 9	1120.57	1772.58	1968.84	1421.14	
6.389e+002 =	610.00	000 50	-022.05	575.00	204.60	204.60	575.00	022.05	000 50	C10.00	_
3.195e+002	-610,96	-926.59	-032.95	-525,90	-204.60	204.60	525.90	032.95	926.59	610.96	
-8.032e-007	610.96	926.59	832.95	525.98	204.60	-204.60	-525.98	-832.95	-926.59	-610.96	
-3.195e+002 -	1/21 1/	1968 84	1772 58	1120.57	453.29	-453 29	-1120.57	1772 58	-1968.84	-1421.14	_
-6.389e+002	1421.14	1000.04	1112.00	1120.01	455.25	400.20	1120.51	1112.30	1000.04	1721.17	
-9.584e+002	1927.12	2555.76	2222,72	1388.79	548.97	-548.97	-1388.79	-22 <mark>72.72</mark>	-2555.76	- <mark>1927.1</mark> 2	
-1.278e+003	<mark>1923.26</mark>	2551.90	2172.63	1313.27	504.93	-50 <mark>4.93</mark>	-1313.27	-2172.63	-2551.90	- <mark>192</mark> 3.26	
-1.597e+003 🕳											
-1.917e+003	1107.94	1605.55	1286.32	713.64	262.91	-262.91	-713.64	-1286.32	-1605.55	-1107.94	
-2.236e+003											
-2.556e+003											

Sxy Stress Contour

Reference

-9.143e+003

Stress Sxy-Top [lb/in^2, + and -]

[1]. Roark & Yong, "Formulas for Stress and Strain" 5th Ed, pp392, McGraw-Hill Inc., 1975

49

B-05 (Design Strip)

Objective

To verify the calculation of shell nodal group resultants and compare them to ACI 318 Equivalent Frame Method.

Problem Description

Determine design moments for the following slab system in the transverse direction for an intermediate floor with a story height of 9 ft. [Ref 1]

Columns: 16 x 16 in., $f_c = 6$ ksi Floor thickness: 7 in., $f_c = 4$ ksi Dead load: -107.5 lb/ft²; Live load: -40 lb/ft² Load combination: 1.4 * Dead + 1.7 * Live Design strip width: 14 ft



Finite Element Model

Model type: 3D Frame and Shell (MITC4 thick plate and Kirchhoff thin plate)

A mesh size of 1 ft x 1 ft is used for all elements except for the edge elements. The upper and lower columns are fixed at the far ends. Shell nodal resultant groups are defined along the transverse direction of a middle design strip with a width of 14 ft (7 ft on each side of the column line). Real3D offers Geometry | Generate Slab Strip Groups command to generate these shell nodal resultant groups automatically.

Results

After performing the analysis, the shell nodal resultants are available in Analysis Results | Shell4 Group Nodal Resultants.

					She	ll4 Group Nodal	Resultant - [Def	ault]				_ 6
Load Co	mbination: 1: Default		✓ #Sho	w selected only	#Print #Save	#Close						
	Group Name	Fx [kip]	Fy [kip]	Fz [kip]	Mx [kip-H]	My [kip-R]	Mz [kip-ft]	Result Location (N)	x vector	y vector	z vector	Message
1	1: DesignStrip_00001_1	0.000	-0.987	0.000	0.010	-0.000	0.205	(42, 9, -0.667)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
2	2 DesignShip 00002 1	-0.000	22,960	-0.000	-41.322	-0.000	0.016	[42, 9, 0]	[1.00.0.00.0.00]	(0.00. 1.00. 0.00)	10.00, 0.00, 1.001	
3	3: DesignShip_00003_1	-0.000	19.915	-0.000	-18.326	0.000	0.031	(42, 9, 1)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
4	4: DesignShip_00003_2	0.000	-22.960	0.000	18.361	-0.000	-0.016	(42, 9, 1)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
5	5: DesignStrip_00004_1	0.000	16.869	-0.000	1.623	0.000	0.048	(42, 9, 2)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
6	6: DesignShip_00004_2	0.000	-19.915	0.000	-1.588	-0.000	-0.031	[42, 9, 2]	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
7	7: DesignShip_00005_1	0.000	13.823	-0.000	18.528	0.000	0.053	(42, 9, 3)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
8	8: DesignStrip_00005_2	-0.000	-16.869	0.000	-18.493	-0.000	-0.048	(42, 9, 3)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
9	9: DesignShip_00006_1	0.000	10.776	-0.000	32.384	0.000	0.043	(42, 9, 4)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
10	10: DesignShip_00006_2	-0.000	-13.823	0.000	-32.351	-0.000	-0.053	(42, 9, 4)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
11	11: DesignShip_00007_1	0.000	7.726	-0.000	43.188	0.000	0.016	(42, 9, 5)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
12	12: DesignShip_00007_2	-0.000	-10.776	0.000	-43.159	-0.000	-0.043	(42, 9, 5)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
13	13. DesignShip_00008_1	0.000	4.676	-0.000	50.936	0.000	-0.028	(42, 9, 6)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
14	14: DesignShip_00008_2	-0.000	-7.726	0.000	-50.914	-0.000	-0.016	(42, 9, 6)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
15	15: DesignShip_00009_1	0.000	1.624	-0.000	55.625	0.000	-0.085	(42, 9, 7)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
16	16: DesignShip_00009_2	-0.000	-4.676	0.000	-55.612	-0.000	0.028	(42, 9, 7)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
17	17: DesignShip_00010_1	0.000	-1.428	-0.000	57.252	0.000	-0.149	(42, 9, 8)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
18	18: DesignShip_00010_2	-0.000	-1.624	0.000	-57.249	-0.000	0.085	(42, 9, 8)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
19	19. DesignShip_00011_1	0.000	-4.479	-0.000	55.816	0.000	-0.212	[42, 9, 9]	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
20	20: DesignStrip_00011_2	-0.000	1.428	0.000	-55.824	-0.000	0.149	[42, 9, 9]	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
21	21: DesignShip_00012_1	0.000	-7.529	-0.000	51.319	0.000	-0.266	(42, 9, 10)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
22	22: DesignShip_00012_2	-0.000	4.479	0.000	-51.337	-0.000	0.212	(42, 9, 10)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
23	23: DesignShip_00013_1	0.000	-10.575	-0.000	43.762	0.000	-0.302	(42, 9, 11)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
24	24: DesignShip_00013_2	-0.000	7.529	0.000	-43.790	-0.000	0.266	(42, 9, 11)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
25	25: DesignShip_00014_1	0.000	-13.619	-0.000	33.151	0.000	-0.312	(42, 9, 12)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
26	26: DesignShip_00014_2	-0.000	10.575	0.000	-33.187	-0.000	0.302	(42, 9, 12)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
27	27: DesignShip_00015_1	0.000	-16.657	-0.000	19.493	0.000	-0.289	(42, 9, 13)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
28	28: DesignShip_00015_2	-0.000	13.619	0.000	-19.533	-0.000	0.312	(42, 9, 13)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
29	29: DesignShip_00016_1	0.000	-19.692	-0.000	2.795	0.000	-0.230	(42, 9, 14)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
30	30: DesignShip_00016_2	-0.000	16.657	0.000	-2.835	-0.000	0.289	(42, 9, 14)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
31	31: DesignShip_00017_1	0.000	-22.721	-0.000	-16.931	0.000	-0.136	(42, 9, 15)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
32	32: DesignShip_00017_2	-0.000	19.692	0.000	16.896	-0.000	0.230	(42, 9, 15)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
33	33: DesignShip_00018_1	0.000	-25.747	-0.000	-39.678	0.000	-0.010	(42, 9, 16)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
34	34: DesignShip_00018_2	-0.000	22.721	0.000	39.653	-0.000	0.136	(42, 9, 16)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
35	35: DesignShip_00019_1	0.000	-28.769	-0.000	-65.435	0.000	0.135	(42. 9. 17)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
36	36: DesignShip_00019_2	-0.000	25.747	0.000	65.424	-0.000	0.010	(42, 9, 17)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
37	37: DesignShip_00020_1	0.000	25.801	-0.000	-86.446	0.000	-0.194	(42, 9, 18)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
38	38: DesignShip_00020_2	-0.000	28.769	0.000	94.204	-0.000	-0.135	(42, 9, 18)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
39	39. DesignShip_00021_1	0.000	22.779	-0.000	-60.623	0.000	-0.051	(42. 9. 19)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
40	40: DesignShip_00021_2	-0.000	-25.801	0.000	60.645	-0.000	0.194	(42, 9, 19)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
41	41: DesignShip_00022_1	0.000	19.754	-0.000	-37.608	0.000	0.070	(42, 9, 20)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
42	42: DesignShip_00022_2	-0.000	-22.779	0.000	37.844	-0.000	0.051	(42, 9, 20)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
43	43: DesignShip_00023_1	0.000	16.726	-0.000	-18.008	0.000	0.157	(42. 9. 21)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
44	44: DesignShip_00023_2	-0.000	-19.754	0.000	18.054	-0.000	-0.070	(42. 9. 21)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
45	45: DesignShip_00024_1	0.000	13.693	-0.000	-1.232	0.000	0.204	[42, 9, 22]	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
46	46: DesignShip_00024_2	-0.000	-16.726	0.000	1.282	-0.000	-0.157	(42, 9, 22)	(1.00, 0.00, 0.00)	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
47	47: DesignShip_00025_1	0.000	10.656	-0.000	12.508	0.000	0.210	(42. 9. 23)	[1.00, 0.00, 0.00]	(0.00, 1.00, 0.00)	(0.00, 0.00, 1.00)	
48	48 DesignShip 00025 2	-0.000	-13.683	0.000	-12.461	-0.000	-0.204	(42.9.23)	11.00.0.00.0.001	(0.00.1.00.0.00)	10.00.0.00.1.001	

We can then copy the moments at all nodal resultant groups to a spreadsheet with some attention to moment signs. The following is the graph generated in Microsoft Excel.



The comparison of results between Real3D and Ref 1 is fairly good. The reference uses ACI 318 Equivalent Frame Method which is an approximate method.

Unit: moments – kip-fts

	Rea	Real3D		
	Thin Plate	Thick Plate		
End Span Exterior Negative	-43.6	-41.3	-52.7	
End Span Positive	56.2	57.3	50.0	
End Span Interior Negative	-93.7	-94.2	-95.2	
Interior Span Negative	-86.1	-86.4	-86.4	
Interior Span Positive	37.4	37.0	37.5	

Reference

[1]. Example 22.1, "Notes on ACI 318-99 Building Code Requirements for Structural Concrete", 7th Edition, Portland Cement Association, 1999

Static - Shell Element (Membrane)

C-01 (Membrane Patch Test)

Objective

To verify membrane formulations passing the patch test

Problem Description

A plate of size 0.24 x 0.12 in is subjected to forced displacements at the four corners as shown below. The boundary conditions are: $u = 10^{-3}(x + y / 2)$; $v = 10^{-3}(y + x / 2)$ Material properties: E = 1.0e6 psi, v = 0.25

Geometry: nodal coordinates are shown in the parenthesis below, thickness t = 0.001 in



Finite Element Model

5 shell elements Model type: 2D Plane Stress Forced displacements on boundary nodes:

Unit: displacement - in

Boundary Nodes	Displacement Dx	Displacement Dy
1	0	0
2	2.4e-4	1.2e-4
3	6.0e-5	1.2e-4
4	3.0e-4	2.4e-4

Results

The displacements of internal nodes can be calculated based on the boundary conditions. The constant strains may be calculated as follows:

$$\varepsilon_{xx} = \frac{\partial u}{\partial x} = 1.0e^{-3}, \ \varepsilon_{yy} = \frac{\partial v}{\partial y} = 1.0e^{-3}$$
$$\varepsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 1.0e^{-3}$$

Constant stresses may be calculated accordingly and are given in [Ref 1].

Unit: displacement - in

	Rea	13D	Theoretical			
Internal Node	Displacement Dx	Displacement Dy	Displacement Dx	Displacement Dy		
5	5.00e-5	4.00e-5	5.00e-5	4.00e-5		
6	1.95e-4	1.20e-4	1.95e-4	1.20e-4		
7	2.00e-4	1.60e-4	2.00e-4	1.60e-4		
8	1.20e-4	1.20e-4	1.20e-4	1.20e-4		

Unit: stress - psi

	Real3D		[Ref 1]			
Stress Sxx	Stress Syy	Stress Sxy	Stress Sxx	Stress Syy	Stress Sxy	
1333	1333	400	1333	1333	400	

Comments

The results given by Real3D are identical to the theoretical and referenced values.

A patch test consists of creating a small "patch" of elements and then imposing an assumed displacement field at the boundary nodes. The assumed displacement field is chosen such that it causes a constant stress in the mesh. To pass the patch test, computed displacements at the interior nodes must be consistent with the assumed displacement field and the computed stresses must be constant. Patch tests are important because they ensure solution convergence—so that increasing mesh fineness results in more accurate results.

Both compatible and incompatible membrane formulations pass the patch test.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

[2]. Cook, Malkus, Plesha, Witt, "Concept and Applications of Finite Element Analysis" 4th Edition, pp238, John Wiley & Sons, Inc., 2002

C-02 (Slender Cantilever)

Objective

To verify membrane formulation of the shell element using regular and irregular element shapes

Problem Description

The slender cantilever beam shown below is modeled with a). regular shape elements; b). trapezoidal shape elements; c). parallelogram shape elements. Trapezoidal and parallelogram shapes take 45^0 angle. All elements have equal volume. Material properties: E = 1.0e7 psi, v = 0.3Section properties: Length = 60 in, height = 0.2 in, thickness t = 0.1 in Loads: a). unit axial force; b). unit in-plane shear



Finite Element Model

6 shell elements Model type: 2D Plane Stress

Results

The tip displacements are given by [Ref 1]. Theoretical stresses at the root are also given here for comparison.

Units: displacement - in; stress - psi

			13D	[Ref 1]		
Element	Load type	Displacements @ tip	Stresses @ root	Displacements @ tip	Stresses @ root	
Compatible	Axial force	3.0e-5	-50	3.0e-5	-50	
Regular	In-plane shear	-0.01009	-846.2	0.1081	-9000	
Incompatible	Axial force	3.0e-5	-50	3.0e-5	-50	
Regular	In-plane shear	-0.1073	-8250.0	0.1081	-9000	
Incompatible	Axial force	3.0e-5	-50	3.0e-5	-50	
Trapezoidal	In-plane shear	-0.02385	-7071.6	0.1081	-9000	
Incompatible	Axial force	3.0e-5	-50	3.0e-5	-50	
Parallelogram	In-plane shear	-0.08608	-6510.1	0.1081	-9000	

Comments

The results given by Real3D are mixed in comparison with the referenced values.

All meshes behave correctly in the axial force loading. For in-plane shear, the regular mesh using incompatible membrane formulation behaves the best. The behavior of the regular mesh using compatible formulation and the irregular mesh using compatible or incompatible formulation can be improved by using more elements. In practice, a rectangular element shape with small aspect ratio should be used whenever possible.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

C-03 (Bathe Membrane Nodal Resultants)

Objective

To verify the calculation of nodal resultants for compatible membrane formulation

Problem Description

The cantilever plate shown below is modeled with 2 x 2 mesh using compatible membrane formulation.

Material properties: E = 2.7e6 psi, v = 0.3Thickness t = 0.1 cm



Finite Element Model

4 shell elements Model type: 2D Plane Stress (using compatible formulation)

Results

The nodal resultants given by Real3D are identical to those given by [Ref 1].

As shown below, the nodal resultants are displayed in two lines at each node of each element. The first line denotes the local x component and the second line does the local y component. The unit is N.

	N7		N8		N 9
	-99.85 35.90	57.99 -6.81	-57.99 6.81	-0.00 -100.00	
	G	3	0	Q4	
	-2.88	44.73	28.03	29.97	
	5.96 N4	-35.04	51.18 N5	42.01	NG
			1		1
	2.58	-60.72	-12.04	-29.97	
	16.79	-35.24	19.10	-42.01	
	G	1	0	22	
	100.15	-42.01	42.01	-0.00	
	41.36	-22.90	22.90	0.00	NB.
2			NZ		IN3

Comments

The results given by Real3D are identical to the referenced values.

The nodal resultants represent forces that hold each element in equilibrium. Finite element solutions must always satisfy nodal point equilibrium and element equilibrium. This is true whether a coarse or fine mesh is employed.

Reference

[1]. Bathe, "Finite Element Procedures", pp. 179, Prentice-Hall, Inc., 1996

C-04 (Cook Membrane Problem)

Objective

To verify compatible and incompatible membrane formulations

Problem Description

The skewed cantilever plate shown below is subjected to a distributed shear of 1 lb at the end. Material properties: E = 1.0 psi, v = 0.333Thickness t = 1 in



Finite Element Model

4 shell elements Model type: 2D Plane Stress (using compatible and incompatible formulations)

Results

The best results are given by [Ref 1] as follows:

Displacement Dy @ C: 23.9 in

Principal stress S1 @ A: 0.236 psi

Principal stress S2 @ B: -0.201 psi

Units: displacement - in; stress - psi

	Compatible formulation			Incompatible formulation			
	Displacement Dy @ C	Principal Stress S1 @ A	Principal Stress S2 @ B	Displacement Dy @ C	Principal Stress S1 @ A	Principal Stress S2 @ B	
2 x 2 mesh	11.85	0.1078	-0.07762	21.05	0.1789	-0.1694	
64x64	23.92	0.2376	-0.2038	23.96	0.2368	-0.2035	
[Ref 1]	23.9	0.236	-0.201	23.9	0.236	-0.201	

Comments

The results given by Real3D are compared with the referenced values. For the 2×2 coarse mesh, the incompatible formulation is superior to the compatible one. For the 64×64 fine mesh, both compatible and incompatible formulations give satisfactory results.

Reference

[1]. Bergan & Filippa, "Triangular membrane element with rotational degrees of freedom", Comput. Meth. Appl. Mech. Engng., 50: 25-69, 1985

Static - Shell Element

D-01 (Bathe Membrane + Beam)

Objective

To verify the combinational behavior of compatible membrane and beam elements

Problem Description

An 8 x 12 cm plate is fixed on three sides. It is reinforced with a bar element in the middle as shown below. The free end of the bar is subjected to a horizontal force of 6000 N.

Material properties: $E = 30e6 \text{ N/cm}^2$, v = 0.30

Plate thickness t = 0.1 cm

Bar cross sectional area = 1 cm^2



Finite Element Model

2 shell elements + 1 beam element Model type: 3D Frame & Shell (use compatible membrane formulation)

Results

The tip displacement of the bar given by Real3D is compared with that given by [Ref 1] as follows:

Unit: displacement - cm

	Real3D	[Ref 1]
Tip displacement Dx @ N4	9.34e-4	9.34e-4

Comments

The result given by Real3D is identical to the referenced value.

Reference

[1]. Bathe, "Finite Element Procedures", pp361, Prentice-Hall, Inc., 1996

D-02 (Curved Beam)

Objective

To verify the shell element using incompatible membrane and the MITC4 thick plate formulations

Problem Description

The curved beam shown below [Ref 1] is fixed at the bottom and loaded with two sets of loads at the tip: 1.0 lbf in-plane shear and 1.0 lbf unit out-of-plane shear.

Material properties: E = 1.0e7 psi, v = 0.25

Plate thickness t = 0.1 in

Curved beam inner radius = 4.12 in, outer radius = 4.32 in, arc = 90°



Finite Element Model

6 shell elements

Model type: 3D Frame & Shell (use incompatible membrane and MITC4 thick plate formulations)

Results

The tip displacements in the direction of loads given by Real3D are compared with that given by [Ref 1] as follows:

Unit: displacement - in

Displacement in load direction	Real3D	[Ref 1]
In-plane shear (in)	0.07751	0.08734 (see Note)
Out-of-plane shear (in)	0.4798	0.5022

Note: The displacement given by [Ref 1] is smaller than the theoretical calculation based on the following [Ref 2]:

$$R_{avg} = \frac{4.32 + 4.12}{2} = 4.22 \text{ in}$$
$$I = \frac{0.1 + 0.2^3}{12} = 6.666667e - 5 \text{ in}^4$$
$$D_y = \frac{\pi/4 + P + R_{avg}^3}{EI} = 0.08853 \text{ in}$$

Comments

The results given by Real3D are very good considering the very coarse mesh employed. We would obtain better results if more elements were used along the beam length.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

[2]. Roark & Yong, "Formulas for Stress and Strain" 5th Ed, pp215, McGraw-Hill Inc., 1975
D-03 (Pinched Cylinder)

Objective

To verify the membrane and bending behavior of the shell element in a curved structure

Problem Description

A thin cylindrical shell with diaphragm boundary conditions at both circular ends is loaded with two opposed point loads at the center of the surface. Material properties: E = 3.0e6 psi, v = 0.3Geometric properties: L = 600 in, R = 300 in, t = 3 inLoad: P = 1.0 lb



Finite Element Model

144 shell elements. Due to symmetry, one eighth of the cylinder is modeled with a12x12 mesh Boundary conditions:

Edge N1-N13: Dz, Dox, Doy fixed Edge N1-N157: Dy, Dox, Doz fixed Edge N13-N169: Dx, Doy, Doz fixed Edge N157-N169: Dx, Dy, Doz fixed Note: N13 is restrained in Dx, Dz, Dox, Doy, Doz.

Model type: 3D Frame and Shell

Results

The deflection under load is given by [Ref 1] as Dy = -1.825e-5 in.

Unit: displacement - in

	[Ref 1]					
Displace						
Compatible						
Kirchhoff	MITC4	Kirchhoff MITC4				
-1.819e-005	-1.595e-005	-1.833e-005	-1.833e-005 -1.605e-005			

Comments

The results given by Real3D are comparable to the referenced values.

It appears that the Kirchhoff thin plate bending formulation yields results close to the referenced values. This is especially true when plate/shell thickness is very thin. Of course, we have to remember that the Kirchhoff plate only applies to rectangular shell elements.

Reference

[1]. Cook, Malkus, Plesha, Witt, "Concept and Applications of Finite Element Analysis" 4th Edition, pp583, John Wiley & Sons, Inc., 2002

D-04 (Scordelis-Lo Roof)

Objective

To verify the membrane and bending behavior of the shell element in a curved structure

Problem Description

The Scordelis-Lo barrel roof below [Ref 1, Ref 2] has a length of 50 ft, a radius of 25 ft, and a sweeping angle of 80 degrees. The roof is supported on rigid diaphragms along its two curved edges (D_x and D_y fixed, but not D_z). The two straight edges are free. A surface load of -90 lb/ft^2 in the global Y direction (self-weight) is applied to the entire roof. Material: E = 4.32e8 lb/ft^2 (3e6 psi); v = 0.0; Thickness: t = 0.25 ft.



Finite Element Model

36 shell elements

Due to symmetry, one quarter of the roof is modeled with a 6x6 mesh. The boundary conditions are specified in the following table.

Nodes	Fixed DOFs
N1 to N6	Z, OX, OY
N7	X, Z, OX, OY, OZ
N14, N21, N26, N35, N42	X, OY, OZ
N43 to N48	X, Y, OZ
N49	X, Y, OY, OZ

Model type: 3D Frame and Shell



Results

The results given by Real3D compare well with benchmark values.

Units: displacement - ft; stress - ksf

	Displacement Dy@ N1	Displacement Dx @ N1	Top Principal Stress S1 @ N7	Bottom Principal Stress S2 @ N7	Top Principal Stress S1 @ N1	Bottom Principal Stress S1 @ N1
MITC4 Compatible	-0.291	-0.153	171.74	-197.69	242.55	349.35
MITC4 Incompatible	-0.307	-0.162	183.97	-210.78	225.09	352.77
Kirchhoff Compatible	-0.290	-0.153	174.88	-200.62	238.73	351.68
Kirchhoff Incompatible	-0.306	-0.161	187.55	-214.41	224.46	352.69
Benchmark Value	-0.302	-0.159	191.23	-218.74	215.57	340.70

Comments

The results given by Real3D are comparable to the referenced values.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

[2]. Scordelis & Lo, "Computer Analysis of Cylindrical Shells", Journal of the American Concrete Institute, Volume 61, May, 1964

D-05 (Hemispherical Shell with Point Loads)

Objective

To verify the membrane and bending behavior of the MITC4 shell element in a doubly-curved, very thin shell structure

Problem Description

The hemispherical shell below [Ref 1] has a radius of 10 ft and a thickness of 0.04 ft. The equator is a free edge and is loaded with four 2-kip point loads alternating in sign at 90 degrees intervals. The edge of the hole at the top (72 degrees from the axis of revolution) is free. Material: $E = 6.825e7 \text{ kip/ft}^2$; v = 0.3; Thickness: t = 0.04 ft; Radius R = 10 ft.



Finite Element Model

8 x 32, 16 x 64 and 32 x 128 shell elements

For simplicity of boundary conditions, symmetry of the structure is not considered. The boundary restraints are applied to prevent instability of the structure.

Model type: 3D Frame and Shell

Results

The results given by Real3D compare well with benchmark values.

Units: displacement – ft

Radial displacement at load point

	8 x 32 mesh	16 x 64 mesh	32 x 128 mesh
MITC4 Compatible	9.272e-2	9.289e-2	9.334e-2
MITC4 Incompatible	9.292e-2	9.313e-2	9.346e-2
Benchmark Value	9.400e-2	9.400e-2	9.400e-2

Comments

The results given by Real3D are comparable to the benchmark values.

This problem is one of the more challenging benchmark tests for shell elements. The reason is that the shell is doubly curved and shell thickness is very small in comparison with its span (radius). Both membrane and bending strains contribute significantly to the radial displacement at the load point. This example shows the superiority of the MITC4 shell element.

We could have taken advantage of the symmetry and only model one quadrant of the structure. The boundary condition requires a little more thinking but is still straightforward in this case. An example is included with the program to illustrate this approach.

Modeling Tips

The most efficient way to construct this model in the program is as follows. First generate arc members using the command Geometry | Generate | Arc Members. Then use Edit | Revolve | Revolve Members to Shells command to generate doubly curved shell elements.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

Static - Brick Element

E-01 (Slender Brick Beam)

Objective

To verify compatible and incompatible brick formulations using regular element shapes

Problem Description

The slender cantilever beam shown below is modeled with 6 rectangular brick elements. Material properties: E = 1.0e7 psi, v = 0.3Section properties: Length = 60 in, height = 0.2 in, thickness t = 0.1 in

Loads: a). unit axial force; b). unit in-plane shear



Finite Element Model

6 brick elements Model type: 3D Brick

Results

The tip displacements are given by [Ref 1]. Theoretical stresses at the root are also given here for comparison.

Units: displacement – in; stress - psi

		Rea	13D	[Ref 1]		
Element	Load type	Displacements @ tip	Stresses @ root	Displacements @ tip	Stresses @ root	
Compatible	Axial force	3.0e-5	-50	3.0e-5	-50	
	In-plane shear	-0.01007	-854.0	0.1081	-9000	
Incompatible	Axial force	3.0e-5	-50	3.0e-5	-50	
	In-plane shear	-0.1072	-8173	0.1081	-9000	

Comments

The results given by Real3D are mixed in comparison with the referenced values.

Compatible and incompatible formulations behave correctly in the axial force loading. For inplane shear, the incompatible brick formulation yields much better results than the compatible one. In practices, finer meshes should be used to achieve satisfactory results, especially for compatible brick elements.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

E-02 (Curved Brick Beam)

Objective

To verify the incompatible brick element in a curved structure

Problem Description

A curved beam as shown below [Ref 1] is fixed at the bottom and loaded with two sets of loads at the tip: 1.0 lbf in-plane shear and 1.0 lbf out-of-plane shear. Material properties: E = 1.0e7 psi, v = 0.25Plate thickness t = 0.1 in Curved beam inner radius = 4.12 in, outer radius = 4.32 in, arc = 90°



Finite Element Model

6 brick elements Model type: 3D Brick (use incompatible formulations)

Results

The tip displacements in the direction of loads given by Real3D are compared with that given by [Ref 1] as follows:

Unit: displacement - in

Displacement in load	Re	[Pof 1]		
direction	6 x 1 mesh	20 x 1 mesh		
In-plane shear (in)	0.07682	0.08814	0.08734 (see Note)	
Out-of-plane shear (in)	0.4116	0.4797	0.5022	

Note: The displacement given by [Ref 1] is smaller than the theoretical calculation based on the following [Ref 2]:

$$R_{avg} = \frac{4.32 + 4.12}{2} = 4.22 \text{ in}$$
$$I = \frac{0.1 \times 0.2^3}{12} = 6.666667e - 5 \text{ in}^4$$
$$D_y = \frac{\pi/4 \times P \times R_{avg}^3}{EI} = 0.08853 \text{ in}$$

Comments

The results given by Real3D are very good considering the relatively coarse meshes employed. We would obtain better results if more elements were used along the beam length.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

[2]. Roark & Yong, "Formulas for Stress and Strain" 5th Ed, pp215, McGraw-Hill Inc., 1975

E-03 (Incompatible Brick)

Objective

To verify the behavior of incompatible brick formulations using irregular meshes

Problem Description

A straight beam with distorted and trapezoidal elements is subjected to two sets of loading: a). end moments; b). end shear. Material properties: E = 1500 psi, v = 0.25Geometric properties: L = 10 in, h = 2 in, t = 1 in Loads: a). F = 1000 lb; b). P = 300 lb



Finite Element Model

Results

The displacements and stresses are given by [Ref 1]. The stresses given for Real3D below are the average values at the top four nodes of each of the elements at the supports.

		Rea	13D	Ref 1 (Theoretical)		
Mesh	Loading	Displacements @ tip	Stresses @ root	Displacements @ tip	Stresses @ root	
Distorted	Moment	95.80	-2471	95.8 (100)	-3015 (3000)	
Distorted	Shear	97.90	-3223	97.9 (102.6)	-4138.5 (-4050)	
Trapezoidal	Moment	76.27	-2503	76.252 (100)	-2883.5 (3000)	
	Shear	80.16	-3309	80.115 (102.6)	-3860 (-4050)	

Unit: displacement – in; stress - psi

Comments

The displacements given by Real3D are almost identical to the referenced values. The stresses are calculated by averaging the top four nodes of each element at the root. The stresses given by Real3D are different from the referenced values due to different methods used in stress calculation. The correct theoretical displacements and stresses are given in parenthesis in the table.

Reference

[1]. Wilson, Ibrahimbegovic, "Use of incompatible displacement modes for the calculation of element stiffness or stresses", Finite Elements in Analysis and Design 7 (1990) 229-241

E-04 (Brick Patch Test)

Problem Description

This is a patch test for a unit cube [Ref 1]. The cube is modeled with 7 eight-node brick elements. Nodal coordinates, element connectivity, and boundary conditions are given in the following tables. Boundary conditions are given as forced displacements. No additional loads are prescribed.

Material: E = 1.e6 psi; v = 0.25Find stresses for each element.



Nodal coordinates (inch)				
Node	Х	Y	Z	
1	0.249	0.342	0.192	
2	0.826	0.288	0.288	
3	0.85	0.649	0.263	
4	0.273	0.75	0.23	
5	0.32	0.186	0.643	
6	0.677	0.305	0.683	
7	0.788	0.693	0.644	
8	0.165	0.745	0.702	
9	0	0	0	
10	1	0	0	
11	1	1	0	
12	0	1	0	
13	0	0	1	
14	1	0	1	
15	1	1	1	
16	0	1	1	

Displacement field
u = 0.001 * (2x + y + z) / 2
v = 0.001 * (x + 2y + z) / 2
w = 0.001 * (x + y + 2z) / 2
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Forced displacements (inch) on boundary

NODE	Dx	Dy	Dz
9	0	0	0
10	0.001	0.0005	0.0005
11	0.0015	0.0015	0.001
12	0.0005	0.001	0.0005
13	0.0005	0.0005	0.001
14	0.0015	0.001	0.0015
15	0.002	0.002	0.002
16	0.001	0.0015	0.0015

All strains are constant. For example $\varepsilon_x =$

$$\frac{\partial u}{\partial x} = 0.001$$
$$\varepsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0.001$$

Element Connectivity

Element	Node1	Node2	Node3	Node4	Node5	Node6	Node7	Node8
1	1	2	3	4	5	6	7	8
2	4	3	11	12	8	7	15	16
3	9	10	2	1	13	14	6	5
4	2	10	11	3	6	14	15	7
5	9	1	4	12	13	5	8	16
6	9	10	11	12	1	2	3	4
7	5	6	7	8	13	14	15	16

Results

The displacements of internal nodes can be calculated based on the boundary conditions. The constant stresses are also given by [Ref 1].

Units: nodal displacement – in

Nodes	Real3D Nodes (compatible and incompatible)			Theoretical		
	Dx	Dy	Dz	Dx	Dy	Dz
1	5.16E-04	5.63E-04	4.88E-04	5.16E-04	5.63E-04	4.88E-04
2	1.11E-03	8.45E-04	8.45E-04	1.11E-03	8.45E-04	8.45E-04
3	1.31E-03	1.21E-03	1.01E-03	1.31E-03	1.21E-03	1.01E-03
4	7.63E-04	1.00E-03	7.42E-04	7.63E-04	1.00E-03	7.42E-04
5	7.35E-04	6.68E-04	8.96E-04	7.35E-04	6.68E-04	8.96E-04
6	1.17E-03	9.85E-04	1.17E-03	1.17E-03	9.85E-04	1.17E-03
7	1.46E-03	1.41E-03	1.38E-03	1.46E-03	1.41E-03	1.38E-03
8	8.89E-04	1.18E-03	1.16E-03	8.89E-04	1.18E-03	1.16E-03

Units: element stress - psi

	Sxx	Syy	Szz	Sxy	Syz	Sxz
Real3D						
(compatible)	1999.982	1999.982	1999.982	399.999	399.999	399.999
Real3D						
(incompatible)	1999.978	1999.978	1999.978	399.998	399.998	399.998
[Ref. 1]	2000	2000	2000	400	400	400

Element nodal resultants are compared against with those from SAP2000. The following table lists the nodal resultants for the inner-most element (brick element id = 1).

Nodes	(compat	Real3D ible and incom	npatible)	SAP2000		
	Fx	Fy	Fz	Fx	Fy	Fz
1	-137.726	-158.484	-178.233	-137.73	-158.49	-178.23
2	46.026	-119.278	-102.478	46.03	-119.28	-102.48
3	102.197	111.746	-54.735	102.2	111.75	-54.74
4	-77.321	87.284	-115.667	-77.32	87.28	-115.67
5	-110.243	-124.015	45.588	-110.24	-124.02	45.59
6	88.898	-63.214	112.401	88.9	-63.22	112.4
7	141.538	156.01	172.556	141.54	156.01	172.56
8	-53.368	109.953	120.567	-53.37	109.95	120.57

Units: nodal resultants (inner-most element) - lb

Comments

Both compatible and incompatible brick elements pass the patch test. Therefore, "the results for any problem solved with the element will converge toward the correct solution as the elements are subdivided." [Ref. 1] The tiny differences in stresses are due to the penalty approach employed in support enforcement during solution.

Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20

E-05 (Hemispherical Shell with Point Loads)

Objective

To verify the behavior of the incompatible brick element in a doubly-curved, very thin shell structure

Problem Description

This problem is the same as problem D-05. Only this time we are using the 3D brick element instead of the MITC4 shell element to model the structure.



Finite Element Model

48 x 48 x 1 incompatible brick elements

Due to symmetry of the structure, we model only a quadrant of the structure. Restraints in the direction of global X and Z are applied to the quadrant lines respectively. A single vertical restraint is applied at the center of the quadrant equator. This is to prevent instability of the structure.

Model type: 3D Brick

Results

The result given by Real3D compares well with benchmark values.

Units: displacement – ft

Radial displacement at load point

	48 x 48 x 1 mesh
Incompatible brick element	9.262e-2
Benchmark Value	9.400e-2

Comments

The result given by Real3D is comparable to the benchmark value.

This problem is one of the more challenging benchmark tests for solid elements. The reason is that the shell is doubly curved and shell thickness is very small in comparison with its span (radius). We used a relatively fine mesh so the element aspect ratio (8:7:1) would not be too large. Also, we used incompatible brick element formulation. Compatible brick element formulation would be too stiff for this mesh model.

Modeling Tips

The most efficient way to construct this model in the program is as follows (see the figures below). First generate two sets of side arc members using the command Geometry | Generate | Arc Members. Then create one shell element at the top using the nodes on the arc members. Delete all generated members. Now use Geometry | Generate | Shells by Nodes to generate 7 more shell elements using the existing nodes on the arcs. Lastly, use Edit | Revolve | Revolve Shells to Bricks command to generate brick elements. This method simplifies the generation procedure.

Concrete Circular Members X	Generate Circular Members
Arc Geometry Radius: 10 ft Start angle: 0 deg End angle: 72 deg Insertion Point Coordinates X 0 ft Y: 0 ft Angle: 0 deg	Arc Geometry 9.96 ft Segments: 8 Start angle: 0 deg End angle: 72 deg Insertion Point Coordinates Rotation X: 0 ft About: Global Z V Y: 0 ft Angle: 0 deg Z: 0 ft Insertion Point Coordinates Insertion Point Coordinates
OK Cancel	OK Cancel

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Reference

[1]. MacNeal & Harder, "A Proposed Standard Set of Problems to Test Finite Element Accuracy", Finite Elements in Analysis and Design, 1 (1985) 3-20 Dynamic

F-01 (Simple 2D Frame Vibration)

Objective

To verify the behavior of beam element vibration

Problem Description

A right-angle frame [Ref 1] vibrates under its own weight as shown below. Material properties: E = 2e11 Pa, v = 0.29, $\rho = 7860$ Kg/m³ Section properties: square section 100 x 100 mm



Finite Element Model

50 beam elements Model type: 2D Frame (shear deformation considered)

Results

The mode frequencies are given by [Ref 1]

Unit: mode frequency - Hz

Mode Frequency	Real3D	[Ref 1]
Mode 1	3.331	3.315
Mode 2	35.07	35.08
Mode 3	70.60	70.77
Mode 4	122.6	122.7
Mode 5	225.7	226.0
Mode 6	269.0	269.4

Mode 7	395.7	396.6
Mode 8	420.7	420.8
Mode 9	552.2	552.3
Mode 10	650.1	649.6

First Four Mode Shapes:



Comments

The vibration frequencies given by Real3D are very close to the referenced values.

Reference

[1]. Cook, Malkus, Plesha, Witt, "Concept and Applications of Finite Element Analysis" 4th Edition, pp436, John Wiley & Sons, Inc., 2002

F-02 (2D Truss Vibration)

Objective

To verify the behavior of truss element vibration

Problem Description

The 2D truss structure [Ref 1] shown below vibrates under its own weight. Nodal coordinates in meters are shown in parenthesis.

Material properties: E = 7.17e10 N/m², ν = 0.30, ρ = 2768 Kg/m³ Section cross-sectional areas

Vertical trusses: 8.0e-5 m² Horizontal trusses: 6.0e-5 m² Diagonal trusses: 4.0e-5 m²



Finite Element Model

15 beam elements Model type: 2D Truss

Results

The mode frequencies are given by [Ref 1]

Unit: mode frequency – Hz

Mode Frequency	Real3D	[Ref 1]
Mode 1	7.9822	7.9832
Mode 2	27.9952	28.0012
Mode 3	44.8770	44.8815
Mode 4	49.5731	49.5859
Mode 5	94.9018	94.925
Mode 6	116.3799	116.3882
Mode 7	125.6432	125.6551
Mode 8	126.1574	126.1727
Mode 9	132.1162	132.1308
Mode 10	152.2912	152.3021

Comments

The vibration frequencies given by Real3D are very close to the referenced values.

Reference

[1]. Stejskal, Dehombreux, Eiber, Gupta, Okrouhlik, "Mechanics with Matlab" April 2001 Web: <u>http://www.geniemeca.fpms.ac.be/mechmatHTML/</u>

F-03 (Cantilevered Tapered Membrane Vibration)

Objective

To verify the behavior of membrane plate vibration

Problem Description

The cantilevered tapered membrane plate [Ref 1] shown below vibrates under its own weight. Material properties: E = 2.0e11 Pa, v = 0.30, $\rho = 8000$ Kg/m³ Plate thickness: t = 0.05 m



Finite Element Model

128 shell elements Model type: 2D Plane Stress

Results

The mode frequencies are given by [Ref 1].

Unit: mode frequency – Hz

	Real3			
Mode Frequency	Compatible Membrane	Incompatible Membrane	[Ref 1]	
Mode 1	44.7076	44.4487	44.623	
Mode 2	130.3669	129.2843	130.03	
Mode 3	162.4766	162.4449	162.70	
Mode 4	246.2847	243.6222	246.05	
Mode 5	378.4229	373.7379	379.90	
Mode 6	389.4256	389.2006	391.44	

Comments

The vibration frequencies given by Real3D are very close to the referenced values.

Reference

[1]. Abbassian, Dawswell, Knowles "Selected Benchmarks for Natural Frequency Analysis", Test No. 32, NAFEMS Finite Element Methods & Standards, Nov. 1987

F-04 (Cantilever Plate Vibration)

Objective

To verify the behavior of plate bending vibration

Problem Description

The 24 x 24 in cantilever plate [Ref 1] shown below vibrates under its own weight. Material properties: E = 2.95e+007 psi, v = 0.20, density = 0.28356 lb/in³ Plate thickness: t =1 in



Finite Element Model

361 shell elements (19 x 19 mesh) Model type: 2D Plate Bending

Results

The mode frequencies are given by [Ref 1].

Unit: mode frequency – Hz

	Real	[Def 1]		
Mode Frequency	MITC4 Thick Plate	Kirchhoff Thin Plate		
Mode 1	0.0176	0.0175	0.01790	
Mode 2	0.0070	0.0069	0.00732	
Mode 3	0.0028	0.0028	0.00292	
Mode 4	0.0023	0.0022	0.00228	
Mode 5	0.0019	0.0019	0.00201	

Comments

The vibration frequencies given by Real3D are very close to the referenced values.

Reference

[1]. Harris, Crede "Shock and Vibration Handbook", McGraw-Hill, Inc, 1976

F-05 (Cantilever Brick Vibration)

Objective

To verify the behavior of brick element vibration

Problem Description

A 1.0 m long cantilever beam fixed at the left end as shown below vibrates under its own weight. Material properties: $E = 2.0e11 \text{ N/m}^2$, v = 0, density = 7800 kg/m³ Beam section: b x h = 0.05 x 0.1 m



Finite Element Model

40 brick elements (20 x 2 x 1 mesh) Model type: 3D Brick Boundary conditions Fixed Dx, Dy and Dz for nodes at left end Fixed Dx for nodes along the middle line Fixed Dz for all nodes

Results

The theoretical mode frequencies may be calculated as follows [Ref 1]:

$$f_n = \frac{K_n}{2\pi L^2} \sqrt{\frac{EI}{m}} = \frac{K_n}{2\pi (1.0)^2} \sqrt{\frac{2.0e^{11} * \frac{1}{12} * 0.05 * 0.1^3}{7800 * 0.05 * 0.1}} = 23.26468652 * K_n$$

Where $K_1 = 3.51602$; $K_2 = 22.0345$; $K_3 = 61.6972$

Unit: mode frequency – Hz

	Real	Theoretical	
Mode Frequency	Compatible Brick Incompatible Brick		
Mode 1	86.0831	81.1984	81.80
Mode 2	517.9047	489.7797	512.6
Mode 3	1370.6341	1300.4777	1435.4

Comments

The first and second vibration frequencies given by Real3D are close to the theoretical ones. More elements need to be used to get accurate third and higher frequencies. The boundary conditions are chosen such that out-of-plane and axial directions are suppressed so we can concentrate on the behavior of in-plane vibration.

Reference

[1]. Chopra, "Dynamics of Structures" 2nd Edition, pp 679, Prentice Hall, Inc., 2001

F-06 (2D Steel Frame Vibration)

Objective

To verify the behavior of the beam element in large 2D steel frame vibration

Problem Description

A 5-span, 12-story 2D steel frame vibrates under its own weight as shown below. All beams are W24's and all columns are W14's

Material properties: E = 29000 ksi, v = 0.3, density = 483.84 lb/ft³



Interior columns:

Floor 1 – 4: W14x120 Floor 5 – 8: W14x90 Floor 9 – 12: W14x68

Exterior columns:

Floor 1 - 4: W14x90 Floor 5 - 8: W14x68 Floor 9 – 12: W14x48

Beams:

Floor 1 - 4: W24x131 Floor 5 - 8: W24x104 Floor 9 - 12: W24x84

Section	Iz	Iy	J	А	Ау	Az
W14X120	1380	495	9.37	35.3	8.555	23.03
W14X90	999	362	4.06	26.5	6.16	17.1583
W14X68	722	121	3.01	20	5.81	12
W14X48	484	51.4	1.45	14.1	4.692	7.96308
W24X131	4020	340	9.5	38.5	14.8225	20.64
W24X104	3100	259	4.72	30.6	12.05	16
W24X84	2370	94.4	3.7	24.7	11.327	11.5757

Units: Iz, Iy and $J - in^4$, A, Ay and $Az - in^2$

Finite Element Model

132 beam elements

Model type: 2D Frame (shear deformation included)

Results

The first three natural frequencies are compared with another program, Frame Analysis & Design (STRAAD) [Ref. 1].

Units: Hz

	Real3D	Frame Analysis & Design (STRAAD)	
Mode 1	1.7508	1.7402386	
Mode 2	4.6904	4.6629050	
Mode 3	7.9692	7.9228372	

Comments

The results given by Real3D are very close to the referenced values.

Reference

[1]. "Frame Analysis & Design", Digital Canal Corporation, Dubuque, Iowa, USA

F-07 (3D Frame Vibration)

Objective

To verify the behavior of the beam element in large 3D frame vibration

Problem Description

A 3D single story frame structure with a length = 27.25 in, width = 17.25 in and height = 18.625 in, is fixed at the bottom. Nodes are inserted at 8.625 in from the top corner nodes along the length, width and height.

Material: $E = 2.79e+007 \text{ lb/in}^2$, v = 0.3

Sections: $A = 1.07453 \text{ in}^2$, $A_y = A_z = 0.537266 \text{ in}^2$, $I_z = I_y = 0.665747 \text{ in}^4$, $J = 1.33149 \text{ in}^4$

Masses: Corner nodes = 0.0253816 lb-sec²/in (X, Y and Z directions)

All other nodes except supports: 0.00894223 lb-sec²/in (X, Y and Z directions)



Finite Element Model

18 beam elements

Model type: 2D Frame (shear deformation included)

Results

The first 10 natural frequencies are compared with another independent program Larsa [Ref. 1]. Units: Hz

Real3D	Larsa
--------	-------

Mode 1	111.2088	111.21
Mode 2 115.7695		115.77
Mode 3	137.1354	137.13
Mode 4	215.7477	215.74
Mode 5	404.1712	404.16
Mode 6	422.5145	422.50
Mode 7	451.4604	451.45
Mode 8	548.8147	548.80
Mode 9 733.3148		733.29
Mode 10	758.2787	758.26

Comments

The results given by Real3D are very close to the referenced values.

F-08 (Response Spectrum Analysis of 4 Story Shear Building)

Objective

To verify the results of response spectrum analysis of a shear building using beam elements.

Problem Description

A 4-story shear building [Ref 1] with corresponding mass and stiffness info shown below.



The response spectrum is defined below (from Loads | Response Spectra Library menu).

Period (sec)	Spectral Acceleration (g)		
0.0	0.15		
0.1	0.18		
0.2	0.25		
0.3	0.38		
0.4	0.50		
0.5	0.50		
0.6	0.40		
0.8	0.32		
1.0	0.25		
1.2	0.19		

We will use four 1m steel beam elements, with sectional area of $A1 = 4 \text{ mm}^2$, $A2 = 8 \text{ mm}^2$, $A3 = 12 \text{ mm}^2$ and $A4 = 16 \text{ mm}^2$. $E = 199.948 \text{ KN/mm}^2$, v = 0.3. The axial stiffness EA/L will match the shear building column stiffness. We will use very large values for other section

properties such as Iz, Iy, J, Ay, Az. This effectively allows us to focus beam element behavior in axial direction only.

We will apply vertical loads F1 = 14.7 KN, F2 = 29.4 KN, F3 = 29.4 KN and F4 = 44.1 at the four free nodes. These forces will be converted to equivalent masses by the program during frequency/response spectrum analysis.



Results

The following lists different results by Real3D against the reference [Ref. 1].

Vibration Periods (sec)

	Real3D	Reference	
Mode 1	0.5788	0.5789	
Mode 2	0.2594	0.2595	
Mode 3	0.1873	0.1873	

Modal Displacements (cm)

Node	Real3D			Reference		
	Mode 1	Mode 2	Mode 3	Mode 1	Mode 2	Mode 3
1	5.1930E+00	-3.9987E-01	5.8228E-02	5.19545e+00	-4.00257e-01	5.82355e-02
2	4.0459E+00	3.9837E-02	-6.4594E-02	4.04779e+00	3.98752e-02	-6.46441e-02
3	2.5786E+00	2.1588E-01	1.0244E-02	2.57982e+00	2.16095e-01	1.03938e-02
4	1.2207E+00	1.7499E-01	4.5731E-02	1.22125e+00	1.75157e-01	4.56209e-02

Inertia Forces (N)

Node	Real3D			Reference		
	Mode 1	Mode 2	Mode 3	Mode 1	Mode 2	Mode 3
1	9.1746E+03	-3.5167E+03	9.8232E+02	9.18127e+03	-3.52106e+03	9.83037e+02
2	1.4296E+04	7.0070E+02	-2.1794E+03	1.43063e+04	7.01546e+02	-2.18364e+03
3	9.1113E+03	3.7973E+03	3.4565E+02	9.11798e+03	3.80201e+03	3.55155e+02
4	6.4698E+03	4.6169E+03	2.3145E+03	6.47450e+03	4.62254e+03	2.30532e+03

Base Shear Forces (N)
	Real3D	Reference
Maximum Likely (SRSS)	3.9478e+004	3.951e+04
Maximum Possible (ABSSUM)	4.6113e+004	4.614e+4

Comments

The results given by Real3D are very close to the referenced values. We did not enter nodal masses directly. Therefore, we need to make sure nodal forces are converted to masses before frequency analysis (Analysis | Frequency Analysis).

Reference

[1]. "Earthquake Response Spectrum Analysis of 4 Story Shear Building", 1996, Mark Austin, Department of Civil Engineering, University of Maryland

F-09 (Response Spectrum Analysis of 2D Frame)

Objective

To verify the results of response spectrum analysis on a 2D frame.

Problem Description

A 2-story concrete frame shown below [Ref 1] fixed at the bottom is subjected to ground motion characterized by the design spectrum specified.

Geometry: bay distance = 20 ft, each story height = 10 ft.

Material: E = 3000 ksi.

Section-1: $Iz = 1000 \text{ in}^4$; Section-2: $Iz = 2000 \text{ in}^4$. Other section properties are set to very large values to simulate bending only actions.

Masses: first floor center = 12.4368 kip-sec²/ft in X direction, second floor center = 6.2184 kip-sec²/ft in X direction.



The design response spectrum is defined below (from Loads | Response Spectra Library menu).

Period (sec)	Spectral Acceleration (g)
0.000	0.500
0.030	0.500
0.125	1.355
0.587	1.355
0.660	1.355
1.562	0.576
4.120	0.218
10.000	0.037

Results

The following lists different results by Real3D against the reference [Ref. 1].

Time	Periods	(sec)
------	---------	-------

	Real3D	Reference
Mode 1	1.5621	1.562
Mode 2	0.5868	0.5868

Modal Displacements SRSS combination (in)

	Real3D	Reference
First story	7.576e+000	7.566
Second story	1.884e+001	18.81

Bending Moment (kip-ft)

Element	Location	Rea	Real3D		Reference	
	Location	Mode 1	Mode 2	Mode 1	Mode 2	
First Floor Beam	Left End	-815.6	-56.54	-814	-57	
Second Floor Beam	Left End	-396.9	178.5	-396	179	
Bottom	Top End	425.9	372.9	425	374	
Column	Bottom End	969.6	410.6	968	412	
Top Column	Top End	396.9	-178.5	396	-179	
	Bottom End	389.7	-316.4	389	-317	

Comments

The results given by Real3D are very close to the referenced values. The bending moments are from load combinations INERTIA_LOADCOMB_X_MODE_1 and INERTIA_LOADCOMB_X_MODE_2 which are generated automatically during the response spectrum analysis process.

Reference

[1]. pp 562, "Dynamics of Structures – Theory and Applications To Earthquake Engineering", 2001, Second Edition, by Anil K. Chopra, Prentice Hall.

F-10 (Response Spectrum Analysis of 3D Frame)

Objective

To verify the results of response spectrum analysis on a 3D frame.

Problem Description

A 2-story 3D frame shown below [Ref 1] fixed at the bottom is subjected to ground motion characterized by constant 0.4g for all modes, with 5% damping.

Geometry: X direction = 2×35 ft; Y direction = 2×13 ft; Z direction = 2×25 ft.

Columns: $E = 350,000 \text{ k/ft}^2$. $A = 4 \text{ ft}^2$, $Iz = 1.25 \text{ ft}^4$, $Iy = 1.25 \text{ ft}^4$, $J = 1.25 \text{ ft}^4$, $Ay = Az = 0 \text{ ft}^2$ Beams: $E = 500,000 \text{ k/ft}^2$. $A = 5 \text{ ft}^2$, $Iz = 2.61 \text{ ft}^4$, $Iy = 1.67 \text{ ft}^4$, $J = 1.25 \text{ ft}^4$, $Ay = Az = 0 \text{ ft}^2$

Two additional nodes 28 (38, 13, 27) and 29 (38, 26, 27) are placed on the first and second floors as they are the center of masses for the respective floors.

Masses: 6.2112 k-sec²/ft at nodes 28 and 29 (X and Z directions).

To prevent nodes 28 and 29 from being orphaned nodes, we will add two additional beams with very small section properties ($Iz = Iy = J = 1e-5 \text{ ft}^4$, $A = 1e-5 \text{ ft}^2$) to connect node 28 with node 14 (or any other node on the first floor) and nodes 29 with node 17 (or any other node on the second floor).



Results

	Real3D	Reference
Mode 1 period (sec)	0.2269	0.2271
Mode 2 period (sec)	0.2152	0.2156
Mode 3 period (sec)	0.0733	0.0733
Mode 4 period (sec)	0.0719	0.0720
X displacement at node 29 ABSSUM modal combination (ft)	0.02045	0.02050
X displacement at node 29 SRSS modal combination (ft)	0.02010	0.02012
X displacement at node 29 CQC modal combination (ft)	0.02011	0.02014

The following lists different results by Real3D against the reference [Ref. 1].

Comments

The results given by Real3D are very close to the referenced values. This verification problem also confirms the robustness of rigid diaphragm implementation. Due to program limitation, we have to add couple of weak beams on the floors to prevent center-of-mass nodes (node 28 and 29) from being orphaned.

Reference

[1]. Example 1-024, Sap2000 Software Verification Manual, 2007, Computers and Structures, Inc., Berkeley, California.

F-11 (2D Frame Vibration with P-Delta Effects)

Objective

To verify the results of frequency analysis on a 2D frame under the following conditions. 1) self-weight only; 2). self-weight + super-imposed loads with and without P-Delta effects.

Problem Description

The following concrete frame is subjected to self-weight and super-imposed nodal loads.

Geometry: X direction = 20 ft; Y direction = 24 ft

Material: E = 3644 ksi, Poisson ratio = 0.15, Density = 145 lb/ft³

Columns: rectangular 20 x 20 inches

Beam: rectangular 20 x 30 inches

Self-weight loads: 0.6 kip/ft on columns, 0.4 kip/ft on beam

Super-imposed loads: Fx = 25 kips, Fy = -1500 kips at the top-left node, Fy = -1200 kips at the top-right node.

Do not consider shear deformation in members.



Results

The following lists the results by Real3D against another FEM program AxisVM.

Mode	Real3D	AxisVM	Difference (%)
1	4.7512	4.7521	-0.01894
2	25.0436	25.0483	-0.01877
3	33.0204	33.0265	-0.01847
4	39.8718	39.879	-0.01806
5	83.1576	83.1721	-0.01744
6	83.7393	83.7536	-0.01708
7	87.9772	87.9898	-0.01432
8	107.1918	107.2054	-0.01269
9	146.3396	146.3641	-0.01674

Vibration frequencies (Hz) under self-weight only:

Vibration frequencies (Hz) under self-weight + super-imposed loads without P-Delta effects:

Mode	Real3D	AxisVM	Difference (%)
1	0.3951	0.3951	0
2	5.7411	5.7418	-0.01219
3	6.4154	6.4162	-0.01247
4	11.5421	11.5440	-0.01646
5	25.3369	25.3411	-0.01658
6	30.0486	30.0535	-0.01631
7	42.5830	42.5901	-0.01667
8	81.9055	81.9188	-0.01624
9	87.0169	87.0309	-0.01609

Vibration frequencies (Hz) under self-weight + super-imposed loads with P-Delta effects:

Mode	Real3D	AxisVM	Difference (%)
1	0.3413	0.3413	0
2	5.7373	5.7380	-0.0122
3	6.4117	6.4125	-0.01248
4	11.5402	11.5422	-0.01733
5	24.5082	24.5122	-0.01632
6	29.1036	29.1084	-0.01649

7	42.1941	42.2013	-0.01706
8	80.6857	80.6986	-0.01599
9	85.8358	85.8498	-0.01631

Comments

The results provided by Real3D are very close to those given by AxisVM.

Generally, compression forces in members decrease their stiffness when the P-Delta effect is taken into account. This, in turn, results in smaller vibration frequencies (or longer vibration periods). In this example, the first mode frequency is about 13.6% smaller when the P-Delta effect is considered.

It is important to subdivide the members in order to capture the vibration modes along the member lengths.

Concrete Design

G-01 (Flexural Design of Concrete Beams)

Objective

To verify the design of the rectangular and Tee concrete beams

Problem Description

The following concrete beams are to be designed according to ACI 318-19 and 318-14 code. The flange width and thickness are given in parenthesis for Tee beams.

Beam	$B x H [B_f x T_f]$ (in)	f _c (ksi)	f _y (ksi)	d _t (in)	d' (in)	M _u (ft- kips)
1	10 x 16	4	60	13.5	2.5	123.2
2	14 x 23	4	60	20.5	2.5	516
3	10 x 21.5 [30 x 2.5]	4	60	19.0	2.5	227
4	10 x 21.5 [30 x 2.5]	4	60	19.0	2.5	400
5	10 x 22.5	3	40	20.0	2.5	129
6	11 x 25	3	60	22.5	2.5	403
7	10 x 20	4	60	16.0	2.5	211

Finite Element Model

7 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The design results of these beams are compared with the references according to ACI 318-19

Beam	Rea	l3D	References				
Dealii	As	As'	As	As'	Reference	Page	
1	2.41	0	2.40	0	Ref [1]	рр. 7-23	
2	6.58	1.48	6.58	1.43	Ref [1]	pp. 6-30	
3	2.77	0	2.77	0	Ref [1]	pp. 7-33	
4	5.10	0	5.10	0	Ref [1]	pp. 7-35	
5	2.37	0	2.37	0	Ref [2]	pp. 133	
6	4.65	1.33	4.74	1.20	Ref [2]	pp. 191	
7	3.48	0.73	3.48	0.70	Ref [3]	pp. 102	

Ream	Rea	13D	References				
Deam	As	As'	As	As'	Reference	Page	
1	2.41	0	2.40	0	Ref [1]	pp. 7-23	
2	6.59	1.44	6.58	1.43	Ref [1]	pp. 6-30	
3	2.77	0	2.77	0	Ref [1]	pp. 7-33	
4	5.10	0	5.10	0	Ref [1]	pp. 7-35	
5	2.37	0	2.37	0	Ref [2]	pp. 133	
6	4.66	1.31	4.74	1.20	Ref [2]	pp. 191	
7	3.48	0.70	3.48	0.70	Ref [3]	pp. 102	

The design results of these beams are compared with the references according to ACI 318-14

Comments

The results given by Real3D are very close to the referenced values. The differences between ACI 318-19 and ACI 319-14 results in doubly reinforced beams are due to the minor differences in tension-controlled strains (fy / E + 0.003 vs. 0.005).

The model consists of multiple simply supported beams. Nodal moments of opposite signs are applied to nodes to achieve uniform moments in each member. The program is very versatile to design multiple isolated beams as well as to design members in integrated frames.

Reference

[1]. "Notes on ACI 318-02 Building Code Requirements for Structural Concrete", 8th Edition, Portland Cement Association, 2002

[2]. James G. MacGregor & James K. Wight, "Reinforced Concrete – Mechanics and Design", 4th Edition, Pearson Prentice Hall, 2005

[3]. Arthur H. Nilson, David Darwin, Charles W. Dolan, "Design of Concrete Structures", 13th Edition, McGraw-Hill Higher Education, 2004

G-02 (Shear Design of Concrete Column)

Objective

To verify the shear design the rectangular concrete column

Problem Description

The following concrete column is to be designed according to ACI 318-19 code [Ref 1]. The concrete cover to stirrup is 1.5 inches.

Beam	Dimension (in)	f _c (ksi)	f _{ys} (ksi)	Longitudinal Bar Size	Stirrup Size	P _u (kips)	V _u (kips)
1	Rectangular 20 x 20	4	60	#9	#3	224.5 (compression)	7.2

Finite Element Model

1 beam element with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The design result is compared with the [Ref 1]. The following table shows φV_c and required stirrup spacing for the column. The program does not round the required stirrup spacing to the practical dimension.

Beam	Rea	13D	Reference		
Dealli	φV_c (kips) s		φV_c (kips)	s (in)	
1	44.915	18.0	44.9	18.0	

Comments

The results given by Real3D are very close to the reference values. The model consists of a simply supported beam. A point load of 47 kips is applied at the middle of the beam to achieve required Vu in the member.

Reference

[1]. Example 7.21, "Design Guide on the ACI 318 Building Code Requirements for Structural Concrete", first edition, CRSI, 2020

G-02a (Shear Design of Concrete Beams)

Objective

To verify the shear design the rectangular and circular concrete beams (columns)

Problem Description

The following concrete beams (columns) are to be designed according to ACI 318-14 code. The concrete cover to stirrup is 1.5 inches.

Beam	Dimension (in)	f _c (ksi)	f _{ys} (ksi)	Longitudinal Bar Size	Stirrup Size	P _u (kips)	V _u (kips)
1	Rectangular 12 x 16	4	40	#6	#3	160 (compression)	20
2	Circular Diameter 14	4	40	#6	#3	10 (compression)	30

Finite Element Model

2 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The design result of the first beam element is compared with the [Ref 1]. The second beam element is a round column subjected to compression and is designed as follows:

$$V_c = 2\left(1 + \frac{P_u}{2000A_g}\right)\sqrt{f_c}b_w d = 2\left(1 + \frac{10000}{2000*\pi*7^2}\right)\sqrt{4000}(14)(0.8)(14) = 20,478 \text{ lbs}$$

 $\varphi V_c = 0.75 * 20.478 = 15.358$ kips

 $s = \frac{\varphi A_{v} f_{ys} d}{(V_{u} - \varphi V_{c})} = \frac{0.75*(0.22)(40000)(0.8*14)}{(30 - 15.358)*1000} = 5.05$ in.

Note: For circular section, $b_w = 2R$, d = 0.8(2R) are used to compute V_c and V_s , according to ACI 318-02 11.3.3 and 11.5.7.3

The following table shows φV_c and required stirrup spacing for the two beam elements. The program does not round the required stirrup spacing to the practical dimension.

Beam	Rea	13D	Reference / Theoretical		
Dealli	φV_c (kips)	s (in)	φV_c (kips)	s (in)	
1	22.175	6.88	22.2	6.9	
2	15.359	5.05	15.358	5.05	

Comments

The results given by Real3D are very close to the reference and theoretical values. The model consists of multiple simply supported beams. Nodal moments of same signs are applied to nodes to achieve uniform shears in each member.

Reference

[1]. "Notes on ACI 318-02 Building Code Requirements for Structural Concrete", 8th Edition, pp. 12-19, Portland Cement Association, 2002

G-02b (Shear Design of Sand-Lightweight Concrete Column)

Objective

To verify the shear design the rectangular sand-lightweight column under tension

Problem Description

The following concrete column is to be designed according to ACI 318-14 code. The clear concrete cover to #3 stirrup is 1.25 inches. The concrete density is 125 lb/ft^3 .

Dimension (in)	f _c (ksi)	f _{ys} (ksi)	Longitudinal Bar Size	Stirrup Size	P _u (kips)	V _u (kips)
Rectangular 10.5 x 18	3.6	40	#6	#3	-26.7 (compression)	29.8

Finite Element Model

1 beam element with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The shear design result of the column is compared with the [Ref 1].

$$\varphi V_c = (0.75)2 \left(1 + \frac{P_u}{500A_g} \right) \lambda \sqrt{f_c} b_w d = (0.75)2 \left(1 + \frac{-26700}{500*18*10.5} \right) (0.85) \sqrt{3600} (10.5) (16) = 9221 \text{ lbs}$$

$$s = \frac{\varphi A_{\nu} f_{\nu s} d}{(V_u - \varphi V_c)} = \frac{0.75*(0.22)(40000)(16)}{(29.8 - 9.221)*1000} = 5.13$$
 in.

The following table shows φV_c and required stirrup spacing for the column. The program does not round the required stirrup spacing to the practical dimension.

Rea	13D	Reference /	Theoretical
φV_c (kips)	s (in)	φV_c (kips)	s (in)
9.221	5.13	9.2	5.1

Comments

The results given by Real3D are very close to the reference values. The model consists of a simply supported beam. Nodal moments of same signs are applied to nodes to achieve uniform shears in the member.

Reference

[1]. "PCA Notes on ACI 318-08 Building Code Requirements for Structural Concrete", pp. 12-16, Portland Cement Association, 2008

G-02c (Shear Design of a Collector Beam)

Objective

To verify the shear design the rectangular concrete collector beam

Problem Description

The following concrete collector beam is to be designed according to ACI 318-19 code [Ref 1]. The concrete cover to stirrup is 1.625 inches. Use 3 stirrup legs.

Beam	Dimension (in)	f _c (ksi)	f _{ys} (ksi)	Longitudinal Bar Size	Stirrup Size	P _u (kips)	V _u (kips)
1	Rectangular 36 x 28.5	4	60	#8	#3	59.3 (tension)	23.5

Finite Element Model

1 beam element with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The design result is compared with the [Ref 1]. The following table shows φV_c and required stirrup spacing for the column. The program does not round the required stirrup spacing to the practical dimension.

Beam	Rea	.13D	Reference		
Dealli	φV_c (kips)		φV_c (kips)	s (in)	
1	82.034	11	82.1	11	

Comments

The results given by Real3D are very close to the reference values. The model consists of a simply supported beam. A point load of 47 kips is applied at the middle of the beam to achieve required Vu in the member.

Reference

[1]. Example 14.13, "Design Guide on the ACI 318 Building Code Requirements for Structural Concrete", first edition, CRSI, 2020

G-02d (Shear Design of a Column)

Objective

To verify the shear design the rectangular concrete collector beam

Problem Description

The following concrete collector beam is to be designed according to ACI 318-19 code [Ref 1]. The concrete cover to stirrup is 4.075 inches. Use 4 stirrup legs.

Beam	Dimension (in)	f _c (ksi)	f _{ys} (ksi)	Longitudinal Bar Size	Stirrup Size	P _u (kips)	V _u (kips)
1	Rectangular 28x28	4	60	#8	#5	715.5 (compression)	215.8

Finite Element Model

1 beam element with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The design result is compared with the [Ref 1]. The following table shows φV_c and required stirrup spacing for the column. The program does not round the required stirrup spacing to the practical dimension.

Beam	Rea	13D	Reference		
φV_c (kips)		s (in)	φV_c (kips)	s (in)	
1	133.392	15.44*	132.3	15.3	

Comments

The results given by Real3D are very close to the reference values. The model consists of a simply supported beam. A point load of 431.6 kips is applied at the middle of the beam to achieve required V_u in the member. The stirrup spacing given here is calculated based on the #5 hoops to resist the ($V_u - \varphi V_c$). The value given by Real3D is not available to user because the minimum spacing requirement governs.

Reference

[1]. Example 14.13, "Design Guide on the ACI 318 Building Code Requirements for Structural Concrete", first edition, CRSI, 2020

G-03 (Axial-Flexural Design of Concrete Columns)

Objective

To verify the axial-flexural design of the rectangular and circular concrete columns

Problem Description

The following concrete columns [Ref 1, 2] are to be designed according to ACI 318-02 code.

Beam	Dimension (in)	f _c (ksi)	f _{ys} (ksi)	P _u (kips)	Mux (ft- kips)	Muy (ft- kips)
1 [Ref.1]	Rectangular 16 x 16	3	60	249 (compression)	55	110
2 [Ref. 2]	Circular 26	4	60	1600 (compression)	150	0
3 [Ref. 3]	Rectangular 20 x 12	4	60	255 (compression)	63.75	127

Finite Element Model

3 beam elements with appropriate material and design criteria assigned

Model type: 3D Frame

Results

The design results are compared with the [Ref 1] and [Ref 2] in the following table.

Beam	Real3D		Reference	
Deam	Bars	Unity Check	Bars	
1	12#7 (4 on each side)	0.976	12#7 (4 on each side) or 8#8 (3 on each side)	
2	13#10	0.982	12#10	
3	8#9 (3 on each side)	0.915	8#9 (3 on each side)	

Comments

The first column is biaxially loaded and therefore a 3D frame model is used. [Ref 1] gives 12#7 (4 on each side) bars or 8#8 (3 on each side) bars based on Equivalent Eccentricity Method and Bresler Reciprocal Load Method respectively. The program gives 12#7 bars (4#7 on each side) if trial bar size starts with #7 and bar layout uses 'equal sides' option. If 8#8 bars (3#8 on each side) are used, the program gives a unity check value of 1.024 (and therefore the design fails). Since the program always tries to find the first section that will pass the unity check (< 1.0), we need to limit the maximum reinforcement ratio (say 3% in this case) in order to see the unity check of the 8#8 bars (3#8 on each side) section. In addition, we also need to set the start

and end bar sizes to be #8 and bar layout to be 'equal sides' in the column design criteria for comparison.

The second column is a circular spiral column. The program gives 13#10 bars while [Ref 2] gives 12#10. If 12#10 bars are used, the program gives a unity check value of 1.008 (and therefore the design fails). Practically speaking, 12#10 should be regarded as ok.

Each column is modeled with one 3D beam element with one support flag of 111100 (fixed in Dx, Dy, Dz and Dox) and the other support flag of 011100 (fixed in Dy, Dz and Dox). Nodal moments and forces are applied in respective directions. Since no slenderness is considered, very small effective length factors are used.

Reference

[1]. James G. MacGregor & James K. Wight, "Reinforced Concrete – Mechanics and Design", 4th Edition, pp.529-532, Pearson Prentice Hall, 2005

[2]. James G. MacGregor & James K. Wight, "Reinforced Concrete – Mechanics and Design", 4th Edition, pp.519, Pearson Prentice Hall, 2005

[3]. Arthur H. Nilson, David Darwin, Charles W. Dolan, "Design of Concrete Structures", 13th Edition, pp. 278, McGraw-Hill Higher Education, 2004

G-04 (Axial-Flexural Design of Concrete Slender Columns)

Objective

To verify the axial-flexural design of the rectangular concrete column (braced)

Problem Description

The following concrete braced column [Ref 1] is to be designed according to ACI 318-02 code. The clear concrete cover to stirrup is 1.5 inches. Use fc = 4 ksi, fy = 60 ksi

Size (in)	18 x 18
Total length (ft)	13
Unbraced length (ft)	13
Effective length factor	0.87
Dead Pu (kips)	230 (compression)
Dead Mu-top (ft-kips)	2
Dead Mu-bottom (ft-kips)	-2
Live Pu (kips)	173 (compression)
Live Mu-top (ft-kips)	108
Live Mu-bottom (ft-kips)	100

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Cm	0.960	0.96
β _{d.}	0.499	0.50
Moment magnification factor	1.145	1.15
Pu (kips)	552.8	553
Mu (ft-kips)	200.6	201
Bars	8 # 9	4 # 10 + 4 # 9

Comments

Since this is a braced column, we do not need to perform the 2nd order analysis for the design.

Reference

[1]. Arthur H. Nilson, David Darwin, Charles W. Dolan, "Design of Concrete Structures", 13th Edition, pp. 304, McGraw-Hill Higher Education, 2004

G-05 (Flexural Design of Cantilever Concrete Slab)

Objective

To verify the flexural design of the concrete slab

Problem Description

The 6 ft cantilever concrete slab shown below has a length of 30 ft and a thickness of 7.5 in. It is subjected to a uniform load of 350 lb/ft^2. Design the flexural reinforcement for the slab according to ACI 318-02 code. The concrete cover (c.c.) is 1.0 inch. Use fc = 4 ksi, fy = 60 ksi

E = 3644 ksi, v = 0.15



Finite Element Model

 12×60 shell elements, each of which has a size of 0.5×0.5 ft.

Model type: 2D Plate Bending, Use Kirchhoff thin plate bending

Results

The maximum design moment (Wood-Armer moment) in top-X direction Top-Mux = -6.381 kip-ft/ft. The program gives the corresponding top-X direction steel Top-Asx = $0.2238 \text{ in}^2/\text{ft}$, which is consistent with the following hand calculation.

$$R_n = \frac{M_u}{\varphi(bd^2)} = \frac{6.381 * 12 * 1000}{0.9 * (12 * 6.5^2)} = 167.8psi$$

$$\rho = \frac{0.85f_c'}{f_y} \left(1 - \sqrt{1 - \frac{2R_n}{0.85f_c'}} \right) = \frac{0.85 * 4000}{60000} \left(1 - \sqrt{1 - \frac{2 * 167.8}{0.85 * 4000}} \right) = 0.00287$$

$$A_s = \rho(bd) = 0.00287 * 12 * 6.5 = 0.22386 \text{ in}^2/\text{ft}$$

The contour (rotated) of the top steel required in X-direction is shown below.



Comments

No minimum top or bottom reinforcement is considered in this example. The Kirchhoff thin plate (instead of the MITC4 thick plate) formulation is used for analysis. This is generally recommended for models that contain only rectangular elements of thin or moderately thick plates (shells).

Reference

None

Steel Design

H-01 (W Steel Beam)

Objective

To verify the steel W-shaped beam design in flexure

Problem Description

Select the lightest W section for the simply supported beam of L = 50ft, Lb = 25 ft. The superimposed load is 0.4 kip/ft dead load and 1.0 kip/ft live load. Use A992 steel. [Ref 1, pp 435-437]. Use AISC 360-22 (16th edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Designed Section	W18x97	W18x97
Cb	1.30073	1.30
Lp (ft)	9.3603	9.36
Lr (ft)	30.359	30.3
Mu (ft-kips)	686.295	688
Phi-Mnx (ft-kips)	740.75	740

Reference

[1]. Charles Salmon, John Johnson and Faris Malhas, "Steel Structures" 5th Edition, Pearson Prentice Hall, 2009

H-02 (W Steel Column)

Objective

To verify the steel W-shape column design in combined axial and flexures

Problem Description [Ref .1, Example H.4]

Select an ASTM A992 W-shape with a 10-in nominal depth to carry the following load effects: Pu = 30 kips, Mux = 90 kip-ft, Muy = 12 kip-ft. The unbraced length is 14 ft and the ends are pinned. Cb = 1.14. The member is non-sway. Use AISC 360-22 (16th edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 3D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Designed Section	W10x33	W10x33
B1x	1.0176	1.02
B1y	1.0879	1.09
Lp (ft)	6.8525	6.85
Lr (ft)	21.776	21.8
Phi-Pn (kips)	252.52	253
Phi-Mnx (ft-kips)	136.59	137
Phi-Mny (ft-kips)	52.5	52.5
Critical Ratio	0.97858	0.979

Reference

H-03 (C Steel Beam)

Objective

To verify the steel channel beam capacity check in flexural and deflection

Problem Description [Ref .1, Example F.2-1A]

Check the capacity of the channel section C15x33.9 for the following beam Simply supported L = 25 ft. Limit the live load deflection to L/360. Fy = 50 ksi.

The nominal loads are a uniform dead load of 0.23 kip/ft and a uniform live load of 0.69 kip/ft. The beam is continuously braced.

Use AISC 360-22 (16th edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Mu (kips-ft)	107.813	108
Phi-Mnx (ft-kips)	190.5	137
Max live load deflection (in)	0.663206	0.664
Live load deflection limit (in)	0.833333	0.833

Reference

H-04 (HSS Steel Column)

Objective

To verify the steel HSS column capacity check in axial direction

Problem Description [Ref .1, Example E.10]

Check the capacity of HSS12x8x3/16 column in axial compression. Fy = 50 ksi, L = 30 ft, Kx = Ky = 0.8, Kz = 1.0, Lu = 30 ft, Cb = 1.0. Use AISC 360-22 (16^{th} edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 3D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Phi-Pn (kips)	151.33	151

Reference

H-05 (Round HSS Steel Column)

Objective

To verify the steel round HSS column capacity check in shear

Problem Description [Ref .1, Example G.5]

Check the capacity of HSS16.000X0.375 column in shear. Fy = 50 ksi, L = 32 ft Use AISC 360-22 (16^{th} edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 3D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Phi-Vnx (kips)	232.2	232

Reference

H-06 (Double Angle Steel Column)

Objective

To verify the steel double angle column axial capacity

Problem Description [Ref .1, Example E.6]

Check the capacity of 2L5x3x1/4x3/4LLBB column in axial compression. Fy = 50 ksi, L = 8 ft, Kx = Ky = Kz = 1.0, Lux = Luy = Luz = 8 ft. Connector distance = 32 in = 2.66667 ft. Use AISC 360-22 (16th edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 3D Frame

Results

The following table shows some intermediate and final results during the design. The program gives comparable results with the reference [Ref 1].

	Real3D	[Ref 1]
Phi-Pn (kips)	73.787	73.8

Reference

H-07 (WT Steel Beam)

Objective

To verify the steel WT beam flexural capacity

Problem Description [Ref .1, Example F.10]

Check the capacity of WT6x5 in flexure for the simply supported beam of L = 6 ft. The load is 0.08 kip/ft dead load and 0.24 kip/ft live load. Use A992 steel. The beam is continuously braced.

Use AISC 360-22 (16th edition) LRFD.

Finite Element Model

1 beam elements with appropriate material and design criteria assigned

Model type: 2D Frame

Results

The following table shows some intermediate and final results during the design. The program gives identical results with the reference [Ref 1]. In the next few pages, we will include the stepby-step calculation procedures output by the program.

	Real3D	[Ref 1]
Mu (kip-ft)	2.16	2.16
Phi-Mnx (kip-ft)	7.32	7.32

Reference

Step-By-Step Examples

This part of the documentation contains example problems solved by Real3D. They are used to demonstrate the capabilities and reliabilities of the program. They may also serve as simple tutorials for the program.

Each example contains:

- ➤ A brief description of the problem.
- Suggested steps to create the model in the program.
- > Comparison of program results with theoretical or published results.
- \succ Comments.

Many of the example problems are simple and may even be verified by hand calculations. This is deliberate because simple models are easy to construct and hand calculation is the most reliable verification method. The data files for all of the example problems are provided in the "Verifications" subdirectory under the program directory. They have the file extensions of "r3a". You may open these files, perform the analyses, and review the results. However, in order to get yourself familiar with the program, you are strongly encouraged to create these models from scratch.

Suggested modeling steps list the major steps to create each model. These steps serve only as a guide and not an exact step-by-step procedure in the creation of the model. We trust you as an engineer to be creative in using the many different model-creation methods in the program. The General Modeling Guide on the following page is a good starting point. All examples use the default settings in the program unless specified. For example, if no load case or load combination is defined, the "Default" load case or "Default" combination will be used. No stress averaging is used for finite elements unless explicitly specified.

Result checking for each problem usually starts with displacements. The reason for this is simple. The program uses the stiffness method and therefore is displacement-based. If the displacements were wrong, nothing else would be right. Other results such as forces and moments may be more relevant or important to you as an engineer. However, they are not the primary verification parameters and are provided where applicable.

Important comments are summarized at the end of each example. They explain the modeling techniques and results.

Activity	Menus
Set up units.	Settings Units
Define materials, sections, and thicknesses	Geometry Materials, Sections, Thicknesses
Construct geometry.	
Start with generating commands whenever	Geometry Generate Frames, Rectangular
possible; draw individual nodes and elements	Shell4s etc.; Geometry Draw Node,
whenever you have to; use DXF file if you are	Member, Shell4; File Import from DXF;
CAD proficient; use Revit Link if you have	File Append File
Autodesk Revit Structure.	
	View Window/Point Select, Line Select,
Select nodes or elements	Select by ID, Select by Properties, Flip
	selection etc.
Freeze or thaw	View Freeze Selected, Thaw
	Geometry Materials, Sections, Thicknesses.
Assign materials, sections, and thicknesses	Assign Member Properties, Shell Properties
Assign materials, sections, and uncknesses	Assign Member Properties, Shell Properties
	etc.
Define boundary conditions	Geometry Supports, Springs
Define load cases and load combinations	Loads Load Cases, Load Combinations
Assign loads	Loads Nodal Loads, Point Loads, Line
Assign loads	Loads, Surface Loads, etc.
Assign massas	Loads Additional Masses, Analysis
Assign masses	Frequency Analysis
Modify input data	Input Data, Edit
Define response spectra	Loads Response Spectra Library
Review Input	View Annotate, Loading Diagrams, Render
Set analysis options	Analysis Analysis Options
Perform analysis	Analysis Static Analysis, Frequency
	Analysis, Response Spectrum Analysis
	Analysis Result, View Shear & Moment
Review analysis results	Diagram, Contour Diagram, Deflection
	Diagram, Mode Shape
View or print reports	File Text Report, Print Current View,
	Capture Images

Tips:

1. Use Edit / Undo when you make a mistake.

2. Use spreadsheet input when you want to combine it with graphical input, or when you are not comfortable with graphical input.

3. *Try to remember some useful keyboard shortcuts* UP or DOWN or LEFT or RIGHT for panning [CTRL] + UP or DOWN or LEFT or RIGHT for zooming [SHIFT] + UP or DOWN or LEFT or RIGHT for rotating F8 for quick rendering ESC to clear selection or get out of troubles. Press twice if you have to.

4. Views and selections may be saved and recalled.

5. Commands under Assign menu allow you to assign properties, boundary conditions and loads continuously.

6. Use quad-precision skyline solver for numerically sensitive structures such as one with rigid diaphragms.

Example 1: A Cantilever Beam

Problem Description

A 100-inch long cantilever beam is subjected to a tip load of -10,000 lbs.

Material properties: E = 2.9e7 psi, v = 0.3

Section properties: $I_x = 200 \text{ in}^4$, $A_y = 8.33333 \text{ in}^2$

Analyze the beam for the following two cases:

a). Model the beam with one frame element. Verify the vertical displacement and rotation at the tip of the beam, with/without the shear deformation considered.

b). Model the beam with 1,000; 10,000; 20,000; and 50,000 members. Analyze each model with the double-precision and quad-precision solver. Compare the vertical displacements without shear deformation considered.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the beam geometry by Geometry | Generate | Rectangular Frames. For example, to generate 1,000 members (each with 0.1 inch in length), enter a distance list of "1000@0.1" in the X direction. Do not enter anything for the Y and Z directions.
- Select all members, define and assign the material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all members, define and assign the section properties by Geometry | Sections. Make sure "Assign active section to currently selected members" is checked in the dialog box.
- Press ESC key to unselect all nodes and elements. Select the first node by View | Select by IDs, and assign it a fixed support by Geometry | Supports.
- Select the last node by View | Select by IDs, and assign it a nodal load of -10,000 lb in the global Y direction. The load is assigned to the built-in load case called "Default". Real3D also provides a load combination called "Default" which is 1.0 * "Default" load case by default.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Check or uncheck "Consider shear deformation on members". Select the double-precision or quad-precision skyline solver.

Results

The displacement at the tip of the beam may be calculated by hand as follows: $G = \frac{E}{2(1+\nu)} = 11,153,846$ psi
$\Delta = \frac{PL^3}{3EI} = -0.5747 \text{ in (shear deformation ignored)}$ $\Delta = \frac{PL^3}{3EI} + \frac{PL}{A_yG} = -0.5855 \text{ in (shear deformation considered)}$ $\theta = \frac{PL^2}{2EI} = -0.00862 \text{ radian}$

The following table shows the tip displacement and rotation of the beam modeled with one element. The comparison between the program and theoretical results is excellent.

	Without shear	r deformation	With shear deformation		
	Real3D	Theoretical	Real3D	Theoretical	
Displacement	-0.5747	-0.5747	-0.5855	-0.5855	
Rotation	-0.00862	-0.00862	-0.00862	-0.00862	

The following table shows the tip displacements of the beam modeled with 1000; 10,000; 20,000; and 50,000 elements. Shear deformations are ignored. The four models are solved with the double-precision and the quad-precision solvers of the program.

Colver	Number of elements					
Solver	1,000	10,000	20,000	50,000		
Double-						
precision	-0.5748	-0.6522	-0.1534	No solution		
Skyline						
Quad-precision Skyline	-0.5747	-0.5747	-0.5747	-0.5747		

Comments

This is probably the simplest structural model that can be solved by either hand or an analysis program. However it could be turned into a very challenging numerical problem as shown in the example. The standard double-precision solver, which is the predominant and only solver in almost all other analysis programs, tends to deteriorate in solution accuracy as the number of elements increases. In the example, the double-precision solver becomes unstable after 10,000 elements. For the model with 50,000 elements, some diagonal terms in the global stiffness matrix even become negative during factorization process. The solver has to terminate and the solution is not obtainable anymore. No results is better than wrong results. Try this model on your familiar structural analysis software!

Real3D implements a unique quad-precision solver that is extremely accurate and stable in solution. Its superiority is demonstrated in that it gives consistent and correct results up to 50,000 elements. You are encouraged to try even more elements to solve this problem. Just make sure you have enough computer memory to handle large models. If you generate a large model by splitting existing members, make sure you renumber the nodes after splitting to minimize the bandwidth in the model.

Example 2: A Truss

Problem Description

A truss with a span of 30 ft and a height of 7.5 ft is loaded with six concentrated loads at joints [Ref. 9, pp355]. Default material and section properties in the program are used. Determine the axial forces of the truss members and the support reactions



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the drawing grid by Geometry | Drawing Grid. Enter a distance list of "4@7.5" for the X direction and a distance list of "2@3.75" for the Y direction.
- Draw the truss members by Geometry | Draw Member. Point to the intersections of the drawing grid and left-click the mouse from point to point. The drawing action is continuous. Right click the mouse to start drawing from a new location.
- Assign the nodal loads to the joints by Loads | Nodal Loads.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Truss".

Results

The comparison between the program and the referenced results is excellent.

	Real3D	[Ref. 9]
Chord B1 – Axial force (kips)	4.44	4.44
Chord B8 – Axial force (kips)	-4.964	-4.96
Support Reaction (kips)	3.12	3.12

Comments

No displacements are given in the reference and therefore not compared. Default material and section properties are used because the truss is determinant and the displacements are not desired.

Example 3: Linear and Non-linear Nodal Springs

Problem Description

A 2-span continuous beam is supported by three springs. Each span is 10 inches long. A concentrated moment M = 100 lb-in is applied at the middle spring. Default material and section properties in the program are used.

Spring constants: $K_y = 10$ lb/in

The left and middle springs are linear.

Analyze the model for the following two cases.

- a). The right spring is linear
- b). The right spring is compression only



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Input nodal coordinates for Nodes 1, 2, 3 by Input Data | Nodes
- Input the two members by Input Data | Members. Use default material (=1), section (=1), and local angle (=0) for both members.
- Input the three nodal springs by Input Data | Springs | Nodal Springs. Spring flags for the left and middle springs are "000000". Spring flag for the right spring is "000000" for case a) and "010000" for case b). Enter the spring constant K_y = 10 for all springs.
- Input a support at the N1 by Input Data | Supports. The support has the flag of "100000" and 0s for all forced displacements.
- Input the nodal moment for N2 by Input Data | Nodal Loads. Enter "5" for the load direction (OZ) and "100" for the load value.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Set the maximum nonlinear iterations to be "10".

Results

In case a), a force couple is developed in the left and right springs. The middle spring has a zero force. $F_{couple} = M / (20 \text{ in}) = 5 \text{ lb.}$ $\Delta_{3y} = F_{couple} / Ky = 0.5 \text{ in.}$

In case b), a force couple is developed in the left and middle springs. The right spring is eliminated because it is compression-only and a positive displacement occurs at N3. $F_{couple} = M / (10 \text{ in}) = 10 \text{ lb.}$ $\Delta_{2y} = F_{couple} / \text{Ky} = 1 \text{ in.}$

Displacements and spring reactions from Real3D are shown in the following table. They are identical to the theoretical results.

	Displacements (in)			Spring reactions (lb)		
	N1	N2	N3	N1	N2	N3
Case a	-0.5	0	0.5	5	0	-5
Case b	-1	1	3	10	-10	0

Comments

The problem is linear for case a) and nonlinear for case b). The program performs 3 iterations for case b). The first iteration includes all three springs. The second iteration eliminates the compression spring. The third iteration checks for convergence.

This is a very simple problem that involves nodal springs only. More complicated problems may be solved just as easily. The program supports line and surface springs that may be applied to members and shells. Line springs may be used in modeling beams on grade and surface springs may be used in modeling mat (Winkler) foundations. Both line and surface springs may be linear or nonlinear (compression-only or tension only).

Default material and section properties are used because they do not affect the results in the example.

Example 4: A Portal Frame With P-Delta

Problem Description

The following portal frame [Ref. 7, pp252] has a span of 60 ft and a column height of 24 ft. The beam is vertically loaded with 60 kips placed at 20 ft from the left end of the beam. The right column is vertically loaded with 120 kips. A horizontal load of 6 kips is applied at the joint of the beam and the left column. Each column is modeled with 2 members. The beam is modeled with a single frame element.

Columns: W10x45, A = 13.3 in², I_z = 248 in⁴ Beam: W27x84, A = 24.8 in², I_z = 2850 in⁴ Material: E = 2.9e7 psi, v = 0.3Perform analysis for the following two cases:

a). First order (Linear) elastic analysis

b). Second order (P-Delta) elastic analysis



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the 2D frame by Geometry | Generate | Rectangular Frames. Enter a distance list of "60" for the X direction and a distance list of "24" for the Y direction. Do not enter anything for the Z direction. Select "Pinned" supports at the bottom of the dialog.
- Select the lower horizontal beam generated and delete it by Edit | Delete.
- Select the two columns and split each into 2 members by Edit | Split Members.
- Select all members, define and assign the material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select the four columns, define and assign the column section properties by Geometry | Sections. Make sure "Assign active section to currently selected members" is checked in the dialog box.

- Select the horizontal beam, define and assign the member section properties by Geometry | Sections. Make sure "Assign active section to currently selected members" is checked in the dialog box.
- Assign the nodal loads and point loads of "Default" load case by Loads | Nodal Loads, Point Loads. Make sure you select the nodes or member beforehand.
- Create two load combinations by Loads | Combinations. Set a load factor of 1.0 for the "Default" load case for each combination. Set the second combination to perform the P-Delta analysis.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Uncheck "Consider shear deformation on members".

Results

The comparison between the program and the referenced results is good.

		Real3D	[Ref. 7]
	Maximum Displacement (in)	4.387	4.4
Linear	Max + moment in beam (in-kips)	8707.7	8708
	Max – moment in beam (in-kips)	2044.3	2044
P-Delta	Maximum Displacement (in)	8.26	8.1
	Max + moment in beam (in-kips)	9079.4	9078
	Max – moment in beam (in-kips)	2663.3	2661

Comments

The portal frame is analyzed by first order and second order elastic methods. Significant stress stiffening effect is observed. Although each physical column is modeled by 2 members, the program accounts for the P-Delta (P- Δ) effect very well even without splitting columns. However, you must split each column into more segments to account for p-delta (P- δ) effect. The same is also true when buckling analysis is desired.

The program does not perform buckling analysis directly. You may estimate the buckling load through trial-and-error with different load factors in the P-Delta load combination. The buckling load factor (λ) given by the reference [Ref. 7] is 2.2.

Example 5: Rectangular Plate

Problem Description

Two 2 x 2 inch square plates [Ref. 4, pp3-20] are clamped and simply supported along their edges respectively. Each plate is loaded with two sets of loads in two different load cases. The first set load is a point load applied at the center of the plate. The second set load is a uniform pressure applied to the entire plate. Use a 10x10 mesh.

Material: E = 1.7472e7 psi; v = 0.3

Thicknesses: t = 1.0e-4 inch.

Point load P = 4e-4 lb

Uniform pressure $p = 1e-4 lb/in^2$

Determine the deflections at the center of plates, using both the thin Kirchhoff and the thick MITC4 plate formulations.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the first plate by Geometry | Generate | Rectangular Shell4s. Enter a distance list of "10@0.2" for the X direction and a distance list of "10@0.2" for the Y direction.
- Select all shell elements generated and copy them to a new location by Edit | Duplicate. Enter valid copy distances so the new plates will not overlap with the existing shells. For example, DeltaX=3, DeltaY=0, and DeltaZ = 0.
- Select all shell elements, define and assign material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all shell elements, define and assign the shell thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Press ESC key to unselect all. Select the nodes along all edges of the first plate model and assign them pinned supports by Geometry | Supports. Select the nodes along all edges of the second plate model and assign them fixed supports by Geometry | Supports.

- Define two load cases named "Point" and "Uniform".
- Define two load combinations. In the first load combination, set the load factor of 1.0 for load case "Point" and 0s for other load cases. In the second load combination, set the load factor of 1.0 for load case "Uniform" and 0s for other load cases.
- Select center nodes of the two plate models, assign them the point loads of load case "Point" by Loads | Nodal Loads.
- Select all shell elements, assign them the uniform loads of case "Uniform" by Loads | Surface Loads.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plate Bending". Check or uncheck "Use Kirchhoff thin plate bending formulation for rectangular shells".

Results

The comparison of the deflections (inches) at the center of each plate between the program and the referenced results is excellent.

Boundary	Loading	Real3	$[\mathbf{D}_{\mathbf{a}}\mathbf{f}_{-4}]$	
	Loading	MITC4	Kirchhoff	[Kel. 4]
Simple	Point	11.555	11.762	11.60
Simple	Uniform	4.049	4.044	4.062
Clampad	Point	5.475	5.750	5.60
Clamped	Uniform	1.256	1.29	1.26

Comments

This is one of the standard test problems proposed to test the effectiveness of plate elements in bending [Ref. 4]. Closed form solutions exist for both plates under point and uniform loading [Ref. 5, 6]. The problem is solved using both thick (MITC4) and thin (Kirchhoff) plate bending formulations. The results from both formulations are very close and compared well with those given by the reference.

It is important to point out that the MITC4 thick plate element can be used to model both a thick plate where shear deformation may be significant and a thin plate where shear deformation is negligible. When it is used to model a very thin plate as in this example, the MITC4 produces results close to those produced by the Kirchhoff thin plate element. The MITC4 plate element is free from shear locking, and is insensitive to distortion of element geometry. It is arguably the best plate bending element currently available.

Example 6: Circular Plate On Grade

Problem Description

A circular steel plate with a thickness of 0.2 inch and a diameter of 20 inches is simply supported along its edge [Ref. 6 pp326-327 & pp 380-381]. The plate is loaded with a uniform load of 3 lb/in^2 .

Material: E = 3e7 psi; v = 0.285

Thicknesses: t = 0.2 inch.

Determine the deflection and moment at the center for the following two cases:

a). No elastic foundation.

b). An elastic foundation with a modulus of 20 lb/in³.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the circular plate by Geometry | Generate | Circular Shell4s. Enter a radius of 10 and segments of 80. Select "Pinned" supports along the edge.
- Select all shell elements, define and assign material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all plate elements, define and assign the shell thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Select all shell elements, assign them the surface load by Loads | Surface Loads.
- *For case b) only*, Select all shell elements, assign them surface springs by Geometry | Springs.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plate Bending". Uncheck "Use Kirchhoff thin plate bending formulation for rectangular shells".

Results

The comparison of deflections and moments (absolute values) at the center of each plate between the program and the referenced results is excellent. Moments are the same in all directions at the center.

	@ center	Real3D	[Ref. 6]
Case a	Deflection (in)	0.089	0.0883
without elastic foundation	Moment (in-lb/in)	61.54	61.5
Case b	Deflection (in)	0.064	0.0637
with elastic foundation	Moment (in-lb/in)	43.21	43.3

Comments

This example problem tests the reliability of the MITC4 plate bending element. It also shows how surface springs may be used to model an elastic (Winkler) foundation. Two separate models are used for case a) and case b). The generated shell elements are mostly rectangular. Some non-rectangular shell elements exist along the edge.

A relatively fine mesh is employed in order to minimize the discretization error along the edge. The default MITC4 thick plate element is used. *It is important to point out that Kirchhoff thin plate elements should not be used here due to the existence of non-rectangular elements.*

Example 7: A Cantilever Plate (In-Plane)

Problem Description

A 6 x 0.2 inch cantilever plate is loaded with two separate sets of loads [Ref. 4, pp3-20].

a). An in-plane shear of 1 lb at the tip.

b). An axial load of 1 lb at the tip.

Material: E = 1.0e7 psi; v = 0.3

Thicknesses: t = 0.1 inch.

Determine the tip displacements in the directions of applied loads, using a 6 x 1 mesh as suggested by the reference.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the first plate by Geometry | Generate | Rectangular Shells. Enter a distance list of "6@1" for the X direction and a distance list of "0.2" for the Y direction.
- Select all shell elements, define and assign material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all shell elements, define and assign the shell thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Press ESC key to unselect all. Select the bottom-left node and assign it a fixed support.
 Select the top-left node and assign it a support restrained in Dx.
- Define two load cases named "InPlaneShear" and "Axial".
- Define two load combinations. In the first load combination, set the load factor of 1.0 for load case "InPlaneShear" and 0s for other load cases. In the second load combination, set the load factor of 1.0 for load case "Axial" and 0s for other load cases.
- Select two nodes at the tip, assign each node a 0.5 lb, Y-direction nodal loads of load case "InPlaneShear" by Loads | Nodal Loads. Select two nodes at the tip, assign each node a 0.5 lb, X-direction nodal loads of load case "Axial" by Loads | Nodal Loads.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plane Stress". Check or uncheck "Use incompatible formulation for shell membrane actions or bricks".

Results

The comparison of the displacements (inches) in the directions of loads between the program and the referenced results is mixed.

	Membrane formulation	Real3D	[Ref. 4]
	Compatible	-0.0101	0.1081
Case a)	Incompatible	-0.1073	0.1081
Case b)	Compatible or Incompatible	3.0e-5	3.0e-5

Comments

The example problem tests the in-plane (membrane) component of the shell element. Two separate analyses are performed for case a) and case b). The incompatible membrane formulation models in-plane bending very well. The compatible membrane formulation is too stiff to model in-plane bending when a coarse mesh is used. However, both formulations work well when fine element meshes are used.

Example 8: Brick Patch Test

Problem Description

This is a patch test for a unit cube [Ref. 4 pp3-20]. The cube is modeled with 7 eight-node brick elements. Nodal coordinates, element connectivity and boundary conditions are given in the following tables. Boundary conditions are given as forced displacements. No additional loads are prescribed.

Material: E = 1.e6 psi; v = 0.25Find stresses for each element.



Nodal coordinates (inch)					
Node	Х	Y	Z		
1	0.249	0.342	0.192		
2	0.826	0.288	0.288		
3	0.85	0.649	0.263		
4	0.273	0.75	0.23		
5	0.32	0.186	0.643		
6	0.677	0.305	0.683		
7	0.788	0.693	0.644		
8	0.165	0.745	0.702		
9	0	0	0		
10	1	0	0		
11	1	1	0		
12	0	1	0		
13	0	0	1		
14	1	0	1		
15	1	1	1		
16	0	1	1		

Displacement field u = 0.001 * (2x + y + z) / 2 v = 0.001 * (x + 2y + z) / 2 w = 0.001 * (x + y + 2z) / 2Forced displacements (inch) on boundary

NODE	Dx	Dy	Dz
9	0	0	0
10	0.001	0.0005	0.0005
11	0.0015	0.0015	0.001
12	0.0005	0.001	0.0005
13	0.0005	0.0005	0.001
14	0.0015	0.001	0.0015
15	0.002	0.002	0.002
16	0.001	0.0015	0.0015

All strains are constant. For example $\varepsilon_x = \frac{\partial u}{\partial x}$

$$\frac{\partial u}{\partial x} = 0.001$$
$$\varepsilon_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0.001$$

Element Connectivity

Element	Node1	Node2	Node3	Node4	Node5	Node6	Node7	Node8
1	1	2	3	4	5	6	7	8
2	4	3	11	12	8	7	15	16
3	9	10	2	1	13	14	6	5
4	2	10	11	3	6	14	15	7
5	9	1	4	12	13	5	8	16
6	9	10	11	12	1	2	3	4
7	5	6	7	8	13	14	15	16

Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Input the nodal coordinates by Input Data | Nodes.
- Modify the default material by Input Data | Materials.
- Input the bricks by Input Data | Bricks. Use the default material (=1).
- Input the boundary conditions by Input Data | Supports. Enter the support flag "111000" for each support. Enter the forced displacements according to the table above.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "3D Brick".

Results

The comparison of stresses (psi) between the program and the referenced results is excellent. Each stress component is uniform in all seven elements.

	Sxx	Syy	Szz	Sxy	Syz	Sxz
Real3D	1999.982	1999.982	1999.982	399.999	399.999	399.999
[Ref. 4]	2000	2000	2000	400	400	400

Comments

The brick element passes the patch test. Therefore, "the results for any problem solved with the element will converge toward the correct solution as the elements are subdivided." [Ref. 4] The tiny differences in stresses are due to the penalty approach employed in support enforcement.

Example 9: Scodelis-Lo Roof

Problem Description

The Scodelis-Lo barrel roof [Ref. 4 pp3-20, Ref. 2] has a length of 50 ft, a radius of 25 ft, and a sweeping angle of 80 degrees. The roof is supported on rigid diaphragms along its two curved edges (D_x and D_y fixed, but not D_z). The two straight edges are free. A surface load of -90 lb/ft^2 in the global Y direction (self-weight) is applied to the entire roof.

Material: $E = 4.32e8 \text{ lb/ft}^2$ (3e6 psi); v = 0.0;

Thickness: t = 0.25 ft.

Find the maximum deflection and moments.



Suggested Modeling Steps

Due to the symmetry, only a quarter of the roof is modeled. A 6×6 mesh is used. The boundary conditions are specified in the following table.

Nodes	Fixed DOFs
N1 to N6	Z, OX, OY
N7	X, Z, OX, OY, OZ
N14, N21, N26, N35, N42	X, OY, OZ
N43 to N48	X, Y, OZ
N49	X, Y, OY, OZ

- Set proper units from Settings | Units & Precisions.
- Generate members along an arc by Geometry | Generate | Arc Members. Enter a radius of 25, segments of 6, start angle 50, end angle 90.
- Select all nodes and members, extrude members to shells by Edit | Extrude | Extrude Members to Shell4s. Enter a distance list of "6@4.1666" and direction of the global Z. Check both "Merge nodes and elements" and "Delete selected members after extrusion".



- Select all shell elements, define and assign the shell thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Select the boundary nodes and apply proper supports as specified above by Geometry | Supports. You need to select and apply multiple times.
- Select all shell elements, assign surface load by Loads | Surface Loads
- Set the analysis options by Analysis | Analysis Options. Choose the model type "3D Frame & Shell". Check or uncheck "Use Kirchhoff thin plate bending formulation for rectangular shells". Check or uncheck "Use incompatible formulation for shell membrane actions or bricks".

Results

The comparison of displacements and moments between the program and the referenced results is excellent. Theoretical maximum vertical displacement is given by MacNeal & Harder [Ref. 4, pp3-20]. Other theoretical values are approximate readings (with different sign convention for moments) from graphs given by Zienkiewicz [Ref. 2 pp350-351]. The maximum D_y and M_{yy} occur at the mid-point along the free edges. The maximum M_{xx} occurs at the center of the longitudinal middle section. The maximum D_z and M_{xy} occur at the corner points at supports.

Membrane	Comp	oatible	Incom	patible	Deferences
Bending	Kirchhoff	MITC4	Kirchhoff	MITC4	References
Displacement	2 175	3 480	3 677	3 687	-3.629
Vertical (in)	-3.475	-3.469	-3.072	-3.087	[Ref. 4]
Displacement	0 1317	0 1317	0.1414	0.1414	app. 0.144
Longitudinal (in)	0.1517	0.1317	0.1414	0.1414	[Ref. 2]
M (ft 1b/ft)	1054	1023	2003	2056	app. 2100
WI_{XX} (II-IU/II)	-1934	-1923	-2093	-2030	[Ref. 2]
M (ft 1b/ft)	636 0	622.0	667.0	666	app650
WIyy (11-10/11)	030.0	033.9	007.9	000	[Ref. 2]
M (ft 1b/ft)	1204	1100	1264	1260	app. 1300
$1VI_{XY}(11-10/11)$	-1204	-1199	-1204	-1200	[Ref. 2]



Displacement contour (MITC4-bending, compatible formulation)

N <u>4</u> 9				- 1		NZ
-484.9	-943.6	-1345.2	-1657.7	-1855.5	-1923.0	-
-457.4	-878.4	-1230.7	-1492.3	-1652.1	-1705.8	
-389.7	-725.2	-978.6	-1149.6	-1248.1	-1280.3	-
-265.8	-466.3	-591.1	-664.5	-704.3	-716.9	-
-97.5	-153.5	-177.1	-189.3	-195.4	-196.9	-
-3.5 N43	-3.5	6.6	8.7	10.2	10.8	N1
	N49 -484.9 -457.4 -389.7 -265.8 -97.5 -3.5 N43	N49 -943.6 -484.9 -943.6 -457.4 -878.4 -389.7 -725.2 -265.8 -466.3 -97.5 -153.5 -3.5 -3.5 N49 -3.5	N49 -943.6 -1345.2 -484.9 -943.6 -1345.2 -457.4 -878.4 -1230.7 -389.7 -725.2 -978.6 -265.8 -466.3 -591.1 -97.5 -153.5 -177.1 -3.5 -3.5 6.6	N49 - - - -484.9 -943.6 -1345.2 -1657.7 -457.4 -878.4 -1230.7 -1492.3 -389.7 -725.2 -978.6 -1149.6 -265.8 -466.3 -591.1 -664.5 -97.5 -153.5 -1777.1 -189.3 -3.5 -3.5 -6.6 8.7	N49 - - - - -484.9 -943.6 -1345.2 -1657.7 -1855.5 -457.4 -878.4 -1230.7 -1492.3 -1652.1 -389.7 -725.2 -978.6 -1149.6 -1248.1 -265.8 -466.3 -591.1 -664.5 -704.3 -97.5 -153.5 -177.1 -189.3 -195.4 -3.5 -3.5 6.6 8.7 10.2	N49 -

M_{xx} contour (MITC4-bending, compatible formulation)

Comments

The example is the de-facto standard test problem for shells due to the strong coupling of the bending and membrane actions. The problem is solved using the shell element with different membrane and bending formulations from which excellent results are obtained. The incompatible membrane formulation yields results closer to the referenced values.

The use of symmetry saves computing time and memory, but requires careful thinking with regard to the boundary conditions. You may model the entire roof by simply fixing D_x , D_y along the curved edges and D_z at the longitudinal central section.

Example 10: A Shear Wall

Problem Description

A two-story concrete shear wall is subjected to two horizontal point forces at the floor levels. To account for the floor diaphragm action, each point load is distributed evenly to all nodes at the floor. The wall is 37.5 ft long and 21 ft high, with six openings of 7.5 x 4.5 ft. Material: E = 4e6 psi; v = 0.15Thicknesses: t = 12 inch

Thicknesses: t = 12 inch.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the plate by Geometry | Generate | Rectangular Shells. Enter a distance list of "3@1, 21@1.5, 3@1" for the X direction and a distance list of "3@1, 10@1.5, 3@1" for the Y direction.
- Select the middle eight nodes at each opening and delete them. The shells that are connected to these nodes are deleted automatically.
- Select all shell elements, define and assign material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all shell elements, define and assign the shell thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Press ESC key to unselect all. Select the nodes at the bottom and assign them fixed supports.
- Select the all nodes at each story level and assign them nodal loads by Loads | Nodal Loads.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plane Stress". Check "Use incompatible formulation for shell membrane actions or bricks".

Results

No comparison of results is available. Displacement D_x contour and Stress S_{yy} contour is provided in the following.



Displacement D_x contour on deflected shape



Stress Syy contour

To verify the results, the horizontal shear is checked at the middle elevation of the second story openings. The following table shows the "Membrane nodal resultants" of four piers by View | Annotate (annotation mode = "Annotate selected entities" to avoid congestion of texts). You may also view the same nodal resultants in a spreadsheet by Result Data | Shell4 Nodal Resultants. You can then copy and paste selected data to your preferred spreadsheet program to perform summation or other computations. *It is important to point out that nodal resultants are expressed in the element local coordinate systems.*

D' 0		-3.005	-0.231	-1.512 -3.815	-1.919 - 1.488 -	-0.766 -0. -1.410 0.	157 181	
Pier 2 $\Sigma F_x =$ 1.786 + 2.511 + 5.079 + 5.219 +2.445 + 1.830 = 18.87 kips	1.786 -1.017 -1.891 -3.280	2.51 2.92 -2.40 1.36	1 29 · 36 · 58 ·	5.079 -4.978 -5.048 -5.319	5.219 5.071 -5.249 5.226	2.445 -2.596 -2.479 -1.679	1.830 1.542 -1.796 2.733	
Pier 3 $\Sigma F_x =$ 18.87 kips	1.830 -1.542 -1.790 -2.733) 2.44 2 2.59 6 -2.4 3 1.65	45 96 79 79	5.219 -5.071 -5.249 -5.226	5.079 4.978 -5.048 5.319	2.511 -2.929 -2.408 -1.368	1.786 9 1.017 6 -1.891 3 3.280	
Pier 4 $\Sigma F_x = 6.131 \text{ kips}$		0.172 -1.204 -0.157 -0.181	0.751 -0.026 -0.766 1.410	2.025 -3.659 -1.919 -1.488	1.406 1.331 -1.512 3.815	1.058 -2.896 -1.022 0.231	0.719 -0.401 -0.754 3.065	

Membrane nodal resultants of four piers at the middle elevation of the second story

Comments

The example problem shows how to perform structural analysis on a shear wall. Although no comparison of results is available, we demonstrate the reliability of the program by checking the horizontal shear.

In designing concrete sections, we generally need forces and moments instead of stresses. We may acquire axial forces and moments in the same manner as in shears. For example, to determine the moment at the second pier above, we may sum the moments by nodal resultants F_y about the center of the pier.



F _{yi} (kips)	X _i (ft)	F _{yi} * X _i (ft-kips)
-1.017	-2.25	2.28825
2.929	-0.75	-2.19675
-4.978	-0.75	3.7335
5.071	0.75	3.80325
-2.596	0.75	-1.947
1.542	2.25	3.4695
$\Sigma F_{y} = 0.951$		sum = 9.15075

Internal Forces and Moment at middle of the second pier: Axial Force = 0.951 kips, Shear Force = 18.87 kips, Moment = 9.15075 ft-kips

It is pretty tedious to perform the nodal resultant summation above. Real3D allows you to define shell nodal resultant group (Geometry | Shell4 Nodal Resultant Group) and then automatically perform such calculations (Analysis Results | Shell4 Group Nodal Resultants) as shown below.

					Shell	Nodal Resu	ultant Grou	ib 🔽			
				A shell no selected	ıdal resultant ç shells and no	group will be cre des on the shell	eated based or I side below.	n the currently			
				Group Ne	ime:	g1					
				Shell Side	e:	Side 3 (third an	nd fourth shell n	odes) 🗸 🗸			
				Referenc	e Shell Id:	0					
				Result Loc	cation X:	18.75	ft				
				Result Lor	cation Y:	16.5	ft				
				Devilt							
				Result Loc	sation 2:	0	ft				
							OK	Cancel			
				S	hell4 Grou	up Nodal R	esultant - [Default]			_ □
'Load Co	mbination: 1:	Default		S	hell4 Grou ✓ □#st	up Nodal R	esultant - [ily #F	Default] rint #Save	#Clo	DSB	_ □
Load Co	Imbination: 1: Group Name	Default Fx [kip]	Fy [kip]	Fz [kip]	ihell4 Grou ✓ □#st Mx [kip-ft]	up Nodal R how selected or My [kip-ft]	esultant - [hly #F Mz [kip-ft]	Default] rint #Seve Result Location [ft]	#Cla x vector	ose y vector	□
Load Co	Group Name	Default Fx [kip] 6.130	Fy [kip] 6.853	Fz [kip] 0.000	Shell4 Grou Shell4 Grou Mx [kip-ft] 0.000	how selected or My [kip-ft] 0.000	esultant - [nly #F Mz [kip-ft] 2.264	Default] rint #Save Result Location [it] (1.5, 16.5, 0)	#Clt x vector (1.00, 0.00, 0.00)	y vector (0.00, 1.00, 0.00)	z vector (0.00, 0.00, 1.00)
Load Co	Group Name 1: g1 2: g2	Default Fx [kip] 6.130 18.870	Fy [kip] 6.853 0.951	Fz [kip] 0.000	Shell4 Grov	how selected or My [kip-ft] 0.000 0.000	esultant - [hly #F Mz (kip-ft] 2.264 9.150	Default] rint #Save Result Location [It] (1.5, 16.5, 0) (12.8, 16.5, 0)	#Clo x vector (1.00, 0.00, 0.00) (1.00, 0.00, 0.00)	y vector (0.00, 1.00, 0.00) (0.00, 1.00, 0.00)	z vector (0.00, 0.00, 1.00) (0.00, 0.00, 1.00)
Load Co	Imbination: 1: Group Name 1: g1 2: g2 3: g3	Default Fx [kip] 6.130 18.870 18.870	Fy (kip) 6.853 0.951 -0.951	Fz [kip] 0.000 0.000	Shell4 Grov	up Nodal R how selected or My [kip-ft] 0.000 0.000	esultant - [//y #F Mz [kip-ft] 2.264 9.150 9.150	Default] rint #Save Result Location [N] (1.5, 16.5, 0) (128, 165, 0) (248, 165, 0)	#Cla x vector (1.00, 0.00, 0.00) (1.00, 0.00, 0.00) (1.00, 0.00, 0.00)	y vector (0.00, 1.00, 0.00) (0.00, 1.00, 0.00) (0.00, 1.00, 0.00)	z vector (0.00, 0.00, 1.00) (0.00, 0.00, 1.00) (0.00, 0.00, 1.00)

You are encouraged to model this wall with members and compare the results with those in this example. Care should be exercised in segmenting the members and assigning them appropriate section properties. Since the sections of the members are relatively deep, shear deformations must be considered.

Example 11: Frequencies of Cantilever Beam

Problem Description

Analyze the vibration frequencies for the following cantilever beam (L = 6m) under its own weight.

Material properties: $E = 20600 \text{ KN/cm}^2$, v = 0.3, weight density = 7850 Kgf/m³ Section properties: $I_x = 4079.07 \text{ cm}^4$, $A_x = 53.1612 \text{ cm}^2$, $A_y = A_z = 0$ The beam is optionally subjected to a compressive horizontal tip load of P = 500 KN Analyze the beam for the following two cases:

a). Find the lowest 3 frequencies without the effect of axial load

b). Find the lowest 3 frequencies with the effect of axial load



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the beam geometry by Geometry | Generate | Rectangular Frames. For example, to generate 8 members (each with 0.75 m), enter a distance list of "8@0.75" in the X direction. Do not enter anything for the Y and Z directions.
- Select all members, define and assign the material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all members, define and assign the section properties by Geometry | Sections. Make sure "Assign active section to currently selected members" is checked in the dialog box.
- Press ESC key to unselect all nodes and elements. Select the first node by View | Select by IDs, and assign it a fixed support by Geometry | Supports.
- Apply self-weight by running Loads | Self Weight. Set self-weight direction to be global Y and self-weight multiplier -1.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Uncheck "Consider shear deformation on members".
- From Analysis | Frequency Analysis, check "Convert loads to masses", set number of modes 3, number of iteration vectors 8, tolerance of eigenvalue 1e-6 and maximum number of subspace iterations 18.

For Case a), do the following steps

Run Frequency Analysis from Analysis | Frequency Analysis

For Case b) do the following steps

- From Input Data | Calculated Masses, click on "Convert to Additional Masses". This is to avoid converting the external load to mass (although it is not necessary in this case because the load is not in the gravity direction).
- Select the last node by View | Select by IDs, and assign it a nodal load of -500 KN in the global X direction.

- From Loads | Load Combinations, set the default load combination to "Perform P-Delta Analysis on this load combination".
- From Analysis | Frequency Analysis, make sure "Convert loads to masses" is unchecked. Then click on Run Frequency Analysis.

Results

The frequencies without considering axial load can be calculated based with the following formulae [Ref. 14]:

$$\varpi_n = \alpha_n \sqrt{\frac{EI}{mL^4}} \text{ and } f_n = 2\pi \varpi_n$$

where m is the linear mass density
m = 7850 * 53.1612 = 41.731542 kg/m
I = 4.07907 10⁻⁵ m^4
L = 6 m
E = 2.06 10⁻¹¹ N/m^2
 $\alpha_1 = 3.51602; \quad \alpha_2 = 22.0345; \quad \alpha_3 = 61.6972$
 $\varpi_n = \alpha_n \sqrt{\frac{2.06 * 10^{11} * 4.07807 * 10^{-5}}{41.731542 * 6^4}} = 12.4646\alpha_n$

There are no closed form formulae for calculating frequencies when axial load influence is considered. The results are therefore compared with another finite element program, AxisVM 6.0

The following table shows the first three frequencies modeled with 8 elements. The comparison between the program and theoretical results is excellent. The comparison between the program and AxisVM 6.0 is identical.

	Without axial l	oad considered	With axial lo	ad considered
Frequency	Real3D	Theoretical (exact)	Real3D	AxisVM 6.0
f_1 (Hz)	6.9255	6.98	2.6005	2.60
f_2 (Hz)	42.6551	43.71	39.4754	39.48
f_3 (Hz)	117.5983	122.39	115.0347	115.03

Comments

The comparison between the program and theoretical results is deemed excellent because we used only 8 elements for the discretization. The frequencies given by the program are lower than the exact ones. Notice the mass allocated to the support is lost in the computation. If we employed more elements, the finite element frequencies would definitely be closer to the exact continuous ones.

When axial load is considered, as in Case b, the stress-stiffness concept used by Real3D to determine P-Delta effects is applied. In this approach, compressive axial load effectively reduces the flexural stiffness of a member (axial tension increases the flexural stiffness). With a lower stiffness, and equal mass, the frequencies are reduced.

Example 12: Frequencies of Rectangular Plate

Problem Description

A 9 x 6 inch plate is simply supported along its edges. Material: E = 3e7 psi; v = 0.3, weight density = 0.282938 lb/in^3 Thicknesses: t = 0.15 inch. Use a 30x20 mesh. Determine the first three circular frequencies of the plate, using both the thin Kirchhoff and the thick MITC4 plate formulations.



Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate the plate by Geometry | Generate | Rectangular Plates. Enter a distance list of "30@0.3" for the X direction and a distance list of "20@0.3" for the Y direction.
- Select all shell elements, define and assign material properties by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog box.
- Select all shell elements, define and assign the plate thickness properties by Geometry | Thicknesses. Make sure "Assign active thickness to currently selected shells" is checked in the dialog box.
- Press ESC key to unselect all. Select the nodes along all edges of the model and assign them pinned supports by Geometry | Supports.
- Apply self-weight by running Loads | Self Weight. Set self-weight direction to be global Z and self-weight multiplier 1.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plate Bending". Check or uncheck "Use Kirchhoff thin plate bending formulation for rectangular shells".

 From Analysis | Frequency Analysis, check "Convert loads to masses", set number of modes 3, number of iteration vectors 8, tolerance of eigenvalue 1e-6, and maximum number of subspace iterations 18. Click on Run Frequency Analysis.

Results

The circular frequencies of a simply supported rectangular plate are calculated according to the following [Ref. 6]:

$$\varpi_n = \pi^2 \left(\frac{m^2}{a^2} + \frac{n^2}{b^2}\right) \sqrt{\frac{Et^3}{12(1-\nu^2)\rho}}$$

where E = 3e7 psi; t = 0.15 in; v = 0.3; a = 9 in; b = 6 in; $\rho = 0.282938 / 386 * 0.15 = 1.0995e-4$ lb-sec^2/in^3

For m = 1, n = 1: $\varpi_1 = \pi^2 \left(\frac{1^2}{9^2} + \frac{1^2}{6^2}\right) \sqrt{\frac{3e7*0.15^3}{12(1-0.3^2)1.0995e-4}} = 3636 \text{ rad/sec}$ For m = 2, n = 1: $\varpi_2 = \pi^2 \left(\frac{2^2}{9^2} + \frac{1^2}{6^2}\right) \sqrt{\frac{3e7*0.15^3}{12(1-0.3^2)1.0995e-4}} = 6993 \text{ rad/sec}$ For m = 1, n = 2: $\varpi_3 = \pi^2 \left(\frac{1^2}{9^2} + \frac{2^2}{6^2}\right) \sqrt{\frac{3e7*0.15^3}{12(1-0.3^2)1.0995e-4}} = 11189 \text{ rad/sec}$

The comparison of the circular frequencies between the program and the theoretical results is excellent.

CircularThin PlatefrequenciesFormulation		Thick Plate Formulation	Theoretical
ϖ_1 (rad/sec)	3633	3616	3636
ϖ_2 (rad/sec)	6982	6938	6993
ϖ_3 (rad/sec)	11179	11150	11189

Comments

A relatively fine mesh is employed in this example. The thin plate finite element frequencies are closer to the theoretical results based on classical thin plate theory. The frequencies given by thick plate formulation are a little smaller than those given by thin plate formulation. This is expected because thick plate formulation accounts for shear deformation and the plate is therefore modeled with less stiffness.

Example 13: Design of Two Braced Concrete Columns

Problem Description

Two concrete columns A and B are part of a braced frame [Ref 16, pp568]. The frame is analyzed and the results of the two columns are listed below.

	Column A	Column B
Size (in)	14 x14	14 x14
Total length (ft)	20	24
Unbraced length (ft)	18	22
Effective length factor	0.77	0.86
Dead Pu (kips)	80	50
Dead Mu-top (ft-kips)	-60	42.4
Dead Mu-bottom (ft-kips)	-21	-32
Live Pu (kips)	24	14
Live Mu-top (ft-kips)	-14	11
Live Mu-bottom (ft-kips)	-8	-8

Design the columns according to ACI 318-02/05 . Use fc = 3 ksi, fy = 60 ksi

Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Create two beam elements: element 1 20 ft, element 2-24 ft.
- Select element 1 and 2, define and assign the standard material (Concrete fc = 3.0 ksi) by Geometry | Materials. Make sure "Assign active material to currently selected elements" is checked in the dialog.
- Select element 1 and 2, define and assign the standard section (Rectangle 14 x 14 inch) by Geometry | Sections. Make sure "Assign active section to currently selected members" is checked in the dialog.
- Select and assign pinned support to the start node of each member by Geometry | Supports. Select and assign roller support to the end node of each member by Geometry | Supports.
- Define Dead and Live load cases by Loads | Load Cases.
- Define two load combinations: one with 1.0Dead and the other with 1.2Dead + 1.6Live. The former combination contains only the sustained load cases and will be used to calculate β_d . Combination two will be used to perform the actual design. Make sure "Perform Concrete Design using this Load Combination" is checked. Also enter sustained load factor (1.2 in this case).
- Define and apply nodal loads and moments for Dead and Live cases by Loads | Nodal Loads.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Uncheck "Consider shear deformation on members".
- Select ASTM_615 (English) rebar database by Concrete Design | RC Tools | Rebar Database.

	Load Combination	×	Analysis Options		×
Label:	Combination_1		Structural Model:	2D Frame (X, Y, OZ)	~
	Case	Factor	Non-Linear Converge	nce Control	
1	Default	0	Maximum iterations (P-Delta or nonlinear elements): 10	
2	dead	1.2	Axial force tolerance	between P-Delta iterations: 0.5	%
3	live	1.6		0.0	~
			Consider shear defo	rmation on members	
			Number of segments for	or member output: 20	
 Perfo Perfo Perfo Perfo 	rm P-Delta Analysis on this Load Combination rm Steel Design using this Load Combination rm Concrete Design using this Load Combina	tion	 Use cracked section Stress averaging mode nodes of finite element Use Kirchhoff thin pl (Uncheck this box to Use incompatible for Use incompatible for Use incompatible for Solver Type Double-precision Quad-precision S 	n properties (Icr) for members and finite elements e at Stress averaging for all adjacent elem s: Stress averaging for all adjacent elem late bending formulation for rectangular shells. o use MITC4 thick plate bending forumlation for rmulation for shell membrane actions or bricks. o use standard compatible formulation for shells is Skyline solver (standard) Skyline solver (for numerically sensitive models)	s ents v shells) or bricks)
S	Sustained load factor: 1.2			Sparse solver (for large models)	
Chec	k Total Load Deflection k Live Load Deflection nt Save	DK Cancel	Use Dut-of Use hard-o	-core solver drive space when there is not enough RAM) magm actions	
			Run Static Analysis	ОК С	ancel

 Define and assign two column design criteria by Concrete Design | Design Criteria | Column Design Criteria. Make sure "Assign active criteria to selected members" is checked in the dialog box.

1	1					200 [14]	15.6	NY	THE LEYS	THE SIZE	[in]	Size		Dar Layout	Commenterio
	1	Default	No	No	18	0	0.86	0.86	2	#3	2.5	#8	#8	Major Sides	Tie
2	2	CD	No	No	18	0	0.77	1	2	#3	1.5	#8	#8	Major Sides	Tie
3	3	DE	No 🗸	No 🗸	22	0	0.86	1	2	#3 🗸	1.5	#8 🗸	#8 ~	1ajor Sides 🗸	Tied 🗸

- Set model concrete design criteria by Concrete Design | Design Criteria | Model Design Criteria. Make sure the sustained load combination is selected for computing $\beta_{d.}$
- Perform the static analysis by Analysis | Static Analysis.
- Perform concrete design by Concrete Design | Perform Design. Concrete sections will be generated automatically based on column design criteria. Exact 3D P-Mx-My

capacity surfaces will be generated and are used to check against the column internal forces and moments.

 View column design results by Concrete Design | Design Output | RC Column Results. Detailed column section results such as interaction diagrams may be viewed or printed by Concrete Design | Design Output | Flexural/Axial Interaction.

					Concrete	Column	Design	Result				_	
.oad Com	nbination:	1: Default				✓ □s	how select	ted only	Pr	int	Save		Close
	Member Id	Section	Unity Check	Comb	Distance (%L)	P [kip]	Mz [kip-ft]	My [kip-ft^2]	Mz-Factor	My-Factor	Beta-d	Cmx	Cmy
1	1	Y003_cc2.375	0.835	2	0.00	134.400	-94.400	0.000	1.000	2.019	0.714	0.439	0.439
2	2	Y002_cc2.375	0.792	2	0.00	82.400	-68.480	0.000	1.191	1.453	0.728	0.899	0.899

Results

The following table shows some intermediate results during the design. The program gives comparable results with the reference [Ref 16].

	Colu	mn A	Column B		
	Real3D	[Ref 16]	Real3D	[Ref 16]	
Cm	0.439	0.438	0.899	0.900	
β _{d.}	0.714	0.714	0.728	0.728	
Moment magnification factor	1.000	1.000	1.191	1.200	

The program chooses 6#8 bars for column A and 4#8 bars for column B. The reference gives 4#8 bars for both column A and column B. The program gives the unit check of 1.038 for column A if 4#8 bars were used. For practical applications, a unit check of slightly over 1.0 is probably acceptable.

Comments

This example shows the program can be used to design multiple concrete columns in a fast fashion. The loads are applied as nodal forces and moments. These loads are usually obtained from analysis results. For columns that are part of an unbraced frame, second-order analysis must be used, with consideration to stiffness adjustment according to ACI 318-02/05.

Example 14: Design of a Continuous Concrete Beam

Problem Description

The following sub-frame [Ref 17, pp 7-43], which consists of one continuous beam plus top and bottom columns framing into the beam, is used to perform flexural and shear design of the continuous beam under vertical loads.

Member sizes: beam = 36×19.5 in; exterior columns = 16×16 in; interior columns = 18×18 in. Story height = 13 ft.

Service Loads: Dead = 3.9 kips/ft (including self-weight); Live = 1.8 kips/ft



Design the continuous beam according to ACI 318-02/05. Use fc = 4 ksi, fy = 60 ksi

Suggested Modeling Steps

- Set proper units from Settings | Units & Precisions.
- Generate rectangular frame by Geometry | Generate | Frames as follows:

Generate Rectangular Frame ×								
Enter distance lists for each direction (e.g. 12, 3@20, 2@15). Leave appropriate box(s) blank to generate on a plane or along a line.								
X Direction:	28.58,28.5,28.58	ft						
Y Direction:	Y Direction: 13.13							
Z Direction:		ft						
Insertion Po	int Coordinates	Rotation						
X: 0	ft	About: Global Z 🗸						
Y: 0	ft	Angle: 0 deg						
Z: 0	ft							
Suppports at bottom: No Supports								
		OK Cancel						

- Select and delete top and bottom beam elements (element 1, 2, 3, 7, 8 and 9 that were generated).
- Select far end nodes of columns and assign fixed supports to them.
- Select all members and renumber each selected member by running Edit | Re-Number | Re-Number Members, as shown below

	Renumber Nodes ×								
 Increment e Renumber e 	ach selected no each selected n	ode number: iode							
By:	1								
Start from:	1	Step by:	1						
		OK	Cancel						

- Define three rectangular sections 36 x 19.5 in, 18 x 18 in and 16 x 16 in using Regular Section in Geometry | Sections. Assign each of these sections to appropriate elements
- Define 4.0 ksi material using Std Material in Geometry | Materials. Assign this material to all.
- Define five load cases: Dead, Live1, Live2, Live3 and Live4 by Loads | Load Cases. Note Live1, 2, 3 and 4 cases are used for live load patterning. Live1 loading is applied to element 1 and 2. Live2 loading is applied to elements 1 and 3. Live3 is applied to element 2 only. Live4 is applied to elements 2 and 3.
- Define four new load combinations: a). 1.2Dead + 1.6Live1, b). 1.2Dead + 1.6Live2 and c). 1.2Dead + 1.6Live3. d). 1.2Dead + 1.6Live4. Make sure "Perform Concrete Design using this Load Combination" is checked. Also enter sustained load factor (1.2 in this case).
- Define and apply line loads for Dead, Live1, 2, 3 and 4 cases Loads | Line Loads. Use View | Loading Diagram to check that the loads are applied correctly.

- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Frame". Uncheck "Consider shear deformation on members". Run Static Analysis to make sure the model is correct before we proceed to the concrete design.
- Select ASTM_615 (English) rebar database by Concrete Design | RC Tools | Rebar Database.
- Define and assign beam design criteria by Concrete Design | Design Criteria | Beam Design Criteria.

Concrete Beam Design Criteria						
	Beam RC Id	Label	Stirrup Legs	Stirrup Size	Bottom Cover [in]	Top Cover (in)
1	1	Default	2	#3 🗸	2.5	2.5
2	2	leftBeam	2	#3	2.5	2.5
3	3	middleBeam	2	#3	2.5	2.5
4	4	rightBeam	2	#3	2.5	2.5
•						

 Set model concrete design criteria by Concrete Design | Design Criteria | Model Design Criteria. Make sure to select the checkbox "Automatically compute support widths".

Model Concrete Design Options		×
Design code: ACI-318 2002 Column Design Parameters Min reinf ratio (%): Min reinf ratio (%): 1 Max reinf ratio (%): 1 Maxiel angle steps for accuracy (must be >= 20): 3 Biaxial angle steps (must be of multiple of 4): 4 Axial capacity steps for display (must be >= 5): 2 Exclude concrete displaced by steel 4 Always use 1.0 for Cm (lipsback this box to compute au	8 50 16 20	Beam Design Parameters ✓ Automatically compute support widths. Select this option so that flexural design starts at support faces and shear design starts at a distance of 'd' from face of support Slab/Plate Design Parameters Min reinf ratio for slab top steel (%): Min reinf ratio for slab bottom steel (%):
Sustained load combination for computing Beta-d in columns: 1: Default Ignore compressive force in concrete shear capacity. Check capacity at column ends only Compute minimum moment Pu * (0.6 + 0.03h)	Consider lightweight concrete reduction factor Use maximum flexural reinforcement in a member to calculate concrete shear capacity (Vc) OK Cancel	

 Select all columns and exclude them from concrete design by Concrete Design | Design Criteria | Exclude Elements.

Exclude Elements from Concrete Design						
 Include selected elements for concrete design Exclude selected elements from concrete design 						
 Apply to selected members. Apply to selected shells 						
OK Cancel						

- Perform concrete design by Concrete Design | Perform Design.
 To view the beam design results in tabulated form, run Concrete Design | Design Output | RC Beam Result for flexural design and Concrete Design | Design Output | RC Shear Result for shear design.

Concrete Beam Design Result — 🗖								
				Sho	ow selected only	Print	Save	Close
4	Member Id	Distance (%L)	fc [kip/in^2]	fy [kip/in^2]	Bot-Mu [kip-ft]	Bot-As [in^2] (-1.0 means section too small)	Top-Mu [kip-ft]	Top-As [in^2] (-1.0 means section too small)
1	1							
2	Rect36x19.5	0.000	4.0	60.0	0.000	2.04	-232.028	3.18
3		0.050	4.0	60.0	0.000	2.04	-160.513	2.17
4		0.100	4.0	60.0	0.000	2.04	-41.896	0.55
5		0.110	4.0	60.0	0.000	2.04	-21.096	0.28
6		0.111	4.0	60.0	1.145	2.04	-18.968	0.25
7		0.115	4.0	60.0	6.608	2.04	-8.817	0.12
8		0.120	4.0	60.0	11.352	2.04	0.000	0.00
9		0.150	4.0	60.0	67.309	2.04	0.000	0.00
10		0.200	4.0	60.0	151.011	2.04	0.000	0.00
11		0.250	4.0	60.0	221.329	3.03	0.000	0.00
12		0.300	4.0	60.0	278.195	3.85	0.000	0.00
13		0.350	4.0	60.0	319.623	4.47	0.000	0.00
14		0.400	4.0	60.0	345.613	4.86	0.000	0.00
15		0.425	4.0	60.0	350.890	4.94	0.000	0.00
15		0.429	4.0	60.0	351.815	4.95	0.000	0.00
17		0.432	4.0	60.0	352.392	4.96	0.000	0.00
18		0.446	4.0	60.0	355.341	5.01	0.000	0.00
19		0.450	4.0	60.0	356.166	5.02	0.000	0.00
20		0.459	4.0	60.0	355.977	5.02	0.000	0.00
21		0.475	4.0	60.0	355.653	5.01	0.000	0.00

d Cor	nbination: 1	: Default			✓ Show	v selected only	Print	S	ave	Close
4	Member Id	Distance (%L)	fc [kip/in^2]	fys [kip/in^2]	Stirrup/tie-size	Stirrup/tie-legs	Shear [kip]	Axial [kip]	Stirrup/tie-spaci ng [in] (blank means stirrup	phi-Vc [kip]
1	1									
2	Rect36x19.5	0.000	4.0	60.0	#3	2	83.462	0.000	6.63	58.059
3		0.050	4.0	60.0	#3	2	83.462	0.000	6.63	58.059
4		0.100	4.0	60.0	#3	2	77.606	0.000	7.33	58.059
5		0.110	4.0	60.0	#3	2	75.506	0.000	7.33	58.059
6		0.111	4.0	60.0	#3	2	75.292	0.000	7.33	58.059
7		0.115	4.0	60.0	#3	2	74.267	0.000	7.33	58.059
8		0.120	4.0	60.0	#3	2	73.377	0.000	7.33	58.059
9		0.150	4.0	60.0	#3	2	66.802	0.000	7.33	58.059
10		0.200	4.0	60.0	#3	2	55.999	0.000	7.33	58.059
11		0.250	4.0	60.0	#3	2	45.196	0.000	7.33	58.059
12		0.300	4.0	60.0	#3	2	34.393	0.000	7.33	58.059
13		0.350	4.0	60.0	#3	2	34.393	0.000	7.33	58.059
14		0.350	4.0	60.0	#3	2	23.589	0.000		58.059
15		0.400	4.0	60.0	#3	2	12.786	0.000		58.059
16		0.425	4.0	60.0	#3	2	7.385	0.000		58.059
17		0.429	4.0	60.0	#3	2	6.437	0.000		58.059
18		0.432	4.0	60.0	#3	2	5.847	0.000		58.059
19		0.446	4.0	60.0	#3	2	2.827	0.000		58.059
20		0.450	4.0	60.0	#3	2	2.758	0.000		58.059

• To view the beam design result in graphics, run Concrete Design | Diagrams | RC Member Envelope Diagram. The following shows the member moment envelope diagram.

Concrete Member	Envelope & Reinf.	Diagram 🚅
Select diagrams to displ	ay:	
Concrete Member Mom	ent Envelope	~
Diagram mode:		
Diagrams on selected n	nembers	~
Show values	Show units	
Center diagram value	es at member ends	
	ОК	Cancel



Results

The following table compares the design moments between the program and the reference [Ref 17, pp 7-43]:

	Moment (ft-kips)	Real3D	[Ref 17, pp 7-43]
	Ext (-) moment	-232.0	-385.9
End Span	(+) moment	356.1	441.1
	Int (-) moment	-523.6	-615.8
Interior Span	(+) moment	274.9	383.8

Comments

The reference [Ref 17, pp 7-43] uses the approximate coefficients method while the program uses the exact stiffness method. It is apparent the former method is quite conservative.

Example 15: Design of Concrete Slab

Problem Description

The following 34×34 ft flat plate is supported by two fixed edges and two simply supported edges as well as a 16×16 in column in the middle. [Ref 20, pp 536-540].



Factored load = 170 psf (including self-weight) fc = 4 ksi, fy = 60 ksi Slab thickness h = 6.5 in Concrete cover: d = 1.25 in over the central column and near the intersection of the two fixed edges, d = 1.0 in for the rest of the area.

Suggested Modeling Steps

• Set proper units from Settings | Units & Precisions. In particular, set the length unit to be inch for easy mesh generation.
heck the box to the	e right of each u	nit to	convert existi	ng da	ata asso	ociated with that unit.	C	heck /	All CI	ear/	411
Geometry:						Properties					
Length:	ĺn	\	#.00	~	✓	Modulus (E, Fy, etc.):	kip/in^2	\sim	#.000E+00	~	✓
Dimension:	in	~	#.00	~	✓	Weight density:	lb/ft^3	\sim	#.0	~	✓
Loads						Reinforcement. area:	in^2	~	#.00	~	✓
Force:	kip	\sim	#.000	\sim	✓	Stress:	lb/in^2	~	#.000E+00	~	✓
Linear force:	kip/ft	\sim	#.000	\sim	✓	- Spring constants					
Moment:	kip-ft	\sim	#.000	\sim	✓	Node Kx, Ky, Kz:	lb/in	\sim	#.000	\checkmark	✓
Linear moment:	lb-ft/ft	\sim	#.000	\sim	✓	Node Kox, Koy, Koz.:	lb-in/rad	~	#.000	~	✓
Surface force:	lb/ft^2	\sim	#.000	\sim	✓	Line Kx, Ky, Kz:	kip/in^2	~	#.000	~	✓
Displacement	in	\sim	#.000E+00	~	✓	Area Kx, Ky, Kz:	kip/in^3	~	#.000	~	✓
Rotation	rad	\sim	#.000E+00	\sim	✓						
Temperature:	Fahrenheit	~	#.0	~	~	Save as defaults fo	r future use				

• Generate rectangular shells by Geometry | Generate | Rectangular Shell4s as follows:

Ge	enerate Shell	Element	s in a Rectan	gle ×
Enter distance I	ists for each direc	tion (e.g. 12,	3@20, 2@15).	
×Direction:	14@14,2@8,140	@14		in
Y Direction:	14@14,2@8,140	@14		in
Insertion Point	t Coordinates	Rotation		
×: 0	in	About:	Global Z 🗸 🗸	
Y: 0	in	Angle:	0	deg
Z: 0	in			
			01	
			UK	Cancel

• Define 4.0 ksi concrete material using Std Material in Geometry | Materials. Assign this material to all plates.

			Materials				
_	Material Id	Label	E [kip/in^2]	Poisson Ratio	Density [lb/ft^3]	Tc [1/F]	
1	1	Default	29000	0.3	489.024	6.5e-006	
2	2	Concrete40	3644.15	0.15	145	5.5e-006	
4						•	•
↓	New	Rows Std Material]		Print	Save	

• Define a thicknesses of 6 inches using Geometry | Thicknesses. Assign this thickness to all plates.

		Thicknesses			x
	Thickness Id	Label		Thickness [in]	
1	1	Default		6	.5
					-
•					
1	New Rows]	Print.	Save.	
Assign	active thickness to	currently selected shells	Appl	/ Cance	el

- Using Geometry | Supports, assign fixed supports to nodes along the left and bottom edges. Assign pinned supports to nodes along the right and top edges as well as to the column node.
- Assign normal surface load of 170 lb/ft^2 to all plates by Loads | Surface Loads.

	S	urface Lo	ad
Load Case:	1: Defau	lt	· · · · · · · · · · · · · · · · · · ·
Direction			Coordinate System
Ox	ОY	• Z	 Local
			Global
Value: -1	70	lb/ft^2	
	Apply to S	Selected She	ells Cancel

• You may turn off the display of surface loads by View | Load Diagram.

	Load Diagram	×
Load Case:	Load Type: VNodal Loads VMember Point Loads VMember Linear Loads VAdditional Masses Area Loads	Show load values Show load units Line load intervals: Area load rendering (% of size): Transparency Non-area loads: Area loads:
Select All Clear All		OK Cancel

- Use the default load combination for concrete design from Loads | Load Combinations.
- Set the analysis options by Analysis | Analysis Options. Choose the model type "2D Plate Bending". Uncheck "Consider shear deformation on members". Check "Use Kirchhoff thin plate bending formulation for rectangular shells". *The Kirchhoff element formulation is recommended over the MITC4 bending formulation for thin plate models that contain only rectangular elements*. Run Static Analysis to make sure the model is correct before we proceed to the concrete design.

Analysis Options			×
Structural Model:	2D Plate Bending (Z, OX, OY)	~
-Non-Linear Converge	nce Control		
Maximum iterations (P-Delta or nonlinear elements):	10	
Axial force tolerance	e between P-Delta iterations:	0.5	%
Consider shear defo	rmation on members		
Number of segments for	or member output:	20	
Stress averaging mode nodes of finite element Use Kirchhoff thin p (Uncheck this box to Use incompatible fo (Uncheck this box to Solver Tupe	e at Stress averaging for s: Stress averaging for late bending formulation for rec o use MITC4 thick plate bendin rmulation for shell membrane ar o use standard compatible form	all adjacent eler tangular shells. ig forumlation fo stions or bricks. ulation for shells	nents v r shells) s or bricks)
O Double-precision	n Skyline solver (standard)		
O Quad-precision S	Skyline solver (for numerically s	ensitive models)	
O Double-precision	Sparse solver (for large model	s)	
Use Out-of (Use hard-	-core solver drive space when there is not e	enough RAM)	
Consider rigid diaph	nragm actions		
Run Static Analysis		ок	Cancel

 Various analysis results may be viewed by View | Contour Diagram. The following are Dz displacement, plate Mxx and Mxy contours.



Dz Displacement Contour



- Select ASTM_615 (English) rebar database by Concrete Design | RC Tools | Rebar Database.
- Define two plate design criteria by Concrete Design | Design Criteria | Plate Design Criteria as follows. Assign the stackArea criteria to area where bar stacking occurs – that is, over the central column and near the intersection of the two fixed edges.

		Concrete	Plate Design C	riteria		
	Plate RC Id	Label	Bottom Cover_x [in]	Bottom Cover_y [in]	Top Cover_x [in]	Top Cover_y [in]
1	1	Default	1	1	1	1
2	2	stackArea	1.25	1.25	1.25	1.25
1						C N
1	New Row	s Print Save	Assign act	ive criteria to selecte	ed shells App	oly Cancel

• Select the four plates over the column node and exclude these plates from concrete design by Concrete Design | Design Criteria | Exclude Elements.



- Perform concrete design by Concrete Design | Perform Design.
- To view the plate flexural design results in tabulated form, run Concrete Design | Design Output | RC Plate Result.

					Concret	te Plate E	Design R	Result				_	
						S	now selecti	ed only	Pri	nt	Save		Close
4	Shell Id	Node Id	Design-H [in]	fc [kip/in^2]	fy [kip/in^2]	Bot-Mux [lb-ft/ft]	Bot-Muy [Ib-ft/ft]	Top-Mux [lb-ft/ft]	Top-Muy [lb-ft/ft]	Bot-Asx [in^2]/in	Bot-Asy [in^2]/in	Top-Asx [in^2]/in	Top-Asy [in^2]/in
1	1	Center	6.50	4.0	60.0	0.000	0.000	-142.359	-142.359	0.000	0.000	0.001	0.001
2		1	6.50	4.0	60.0	70.562	70.562	-70.562	-70.562	0.000	0.000	0.000	0.000
3		2	6.50	4.0	60.0	0.000	0.000	-37.226	-182.156	0.000	0.000	0.000	0.001
4		33	6.50	4.0	60.0	87.841	87.841	-420.614	-420.614	0.000	0.000	0.001	0.001
5		32	6.50	4.0	60.0	0.000	0.000	-182.156	-37.226	0.000	0.000	0.001	0.000
6													
7	2	Center	6.50	4.0	60.0	0.000	0.000	-268.337	-528.902	0.000	0.000	0.001	0.002
8		2	6.50	4.0	60.0	0.000	0.000	-37.226	-182.156	0.000	0.000	0.000	0.001
9		3	6.50	4.0	60.0	0.000	0.000	-114.790	-703.897	0.000	0.000	0.000	0.002
10		34	6.50	4.0	60.0	249.798	0.000	-500.717	-808.940	0.001	0.000	0.002	0.003
11		33	6.50	4.0	60.0	87.841	87.841	-420.614	-420.614	0.000	0.000	0.001	0.001
12													
13	3	Center	6.50	4.0	60.0	0.000	0.000	-341.516	-1011.072	0.000	0.000	0.001	0.004
14		3	6.50	4.0	60.0	0.000	0.000	-114.790	-703.897	0.000	0.000	0.000	0.002
15		4	6.50	4.0	60.0	0.000	0.000	-208.090	-1351.617	0.000	0.000	0.001	0.005
16		35	6.50	4.0	60.0	138.523	0.000	-542.469	-1179.834	0.000	0.000	0.002	0.004
17		34	6.50	4.0	60.0	249.798	0.000	-500.717	-808.940	0.001	0.000	0.002	0.003
18													
19	4	Center	6.50	4.0	60.0	0.000	0.000	-400.991	-1510.952	0.000	0.000	0.001	0.005
20		4	6.50	4.0	60.0	0.000	0.000	-208.090	-1351.617	0.000	0.000	0.001	0.005
21		5	6.50	4.0	60.0	0.000	0.000	-301.780	-1993.390	0.000	0.000	0.001	0.007
•													•

 To view the plate design result in graphics, run Concrete Design | Diagrams | RC Plate Envelope Contour. For illustration purposes, the X-top and X-bottom design (Wood-Armer) moment and the corresponding required steel contours are shown below. Based on reinforcement contours and some commonsense, the actual reinforcement can be provided for final design.



Wood-Armer Top-Mux



Required Top-Asx



Required Bottom-Asx

Results

	Real3D	Ref 20
Negative moment over column (lb-ft/ft)	-11,510	-10,528
Negative steel over column (in^2/ft)	0.5259	0.48
Negative moment along fixed edges (lb-ft/ft)	-4,412	-3,509
Negative steel along the fixed edges (in^2/ft)	0.183	0.15
Positive moment in outer spans (lb-ft/ft)	4,234	3,789
Positive steel in outer spans (in^2/ft)	0.1752	0.16

Comments

The reference used Advanced Strip Method to compute the design moments and therefore is approximate in nature. The program computes the design (Wood-Armer) moments based on the plate element Mxx, Myy and Mxy. Although the two methods are fundamentally different, comparable results are obtained.

One of the difficulties in using finite element results to perform concrete plate (or slab) design is stress singularity. In this example, the slab stress around the column is theoretically infinite. This is reflected in stress and reinforcement spikes at the slab/column interface area. Finer finite element mesh will generally exacerbate the problem. We alleviated the problem by excluding the four finite elements over the column from design. Appropriate averaging or redistribution of reinforcement should also be applied before the actual reinforcement is provided.

Example 16: Design of Steel Beam

Problem Description

Select the lightest W section for the simply supported beam of L = 50 ft, Lb = 25 ft. The superimposed load is 0.4 kip/ft dead load and 1.0 kip/ft live load. Use A992 steel. [Ref 22, pp 435-437].

Suggested Modeling Steps

• Set proper units from Settings | Units & Precisions.

neck the box to the	angin oreach u	meto	convertexisti	ng ua	iia assi	Johaleu Willi Inal unit.		пески		eal A	NII
Geometry:						Properties					
Length:	ft	\sim	#.00	~	✓	Modulus (E, Fy, etc.):	kip/in^2	\sim	#.000E+00	\sim	✓
Dimension:	in	\sim	#.00	~	✓	Weight density:	lb/ft^3	\sim	#.0	\sim	✓
_oads						Reinforcement. area:	in^2	~	#.00	~	✓
Force:	kip	\sim	#.000	\sim	✓	Stress:	lb/in^2	~	#.000E+00	~	✓
Linear force:	kip/ft	\sim	#.000	~	✓	-Spring constants					
Moment:	kip-ft	\sim	#.000	\sim	✓	Node Kx, Ky, Kz:	lb/in	~	#.000	\sim	✓
Linear moment:	kip-ft/ft	\sim	#.000	~	✓	Node Kox, Koy, Koz.:	lb-in/rad	~	#.000	~	✓
Surface force:	lb/ft^2	\sim	#.000	\sim	✓	Line Kx, Ky, Kz:	kip/in^2	~	#.000	\sim	✓
Displacement:	in	\sim	#.000E+00	\sim	✓	Area Kx, Ky, Kz:	kip/in^3	~	#.000	~	✓
Rotation	rad	\sim	#.000E+00	\sim	✓						
Temperature:	Fahrenheit	\checkmark	#.0	\checkmark	~	Save as defaults fo	r future use				

Define load cases from Loads | Load Cases

	Case No	La	abel	Туре
1	1	Default		Dead-D 🗸
2	2	Dead		Dead-D
3	3	Live		Live-L

 Define the load combination from Loads | Load Combinations: make sure "Perform Steel Design using this Load Combination" is checked.

Load Combination	×
Label: Default	
Case	Factor
1 Default	0
2 Dead	1.2
3 Live	1.6
	-
•	•
Deufeuru D. Delte Anelusie en this Load Combinetia	
Penorm P-Delta Analysis on this Load Combinatio	iri
Perform Steel Design using this Load Combination	1
Perform Concrete Design using this Load Combine	ation
Sustained load factor: 0	
Check Total Load Deflection	
Check Live Load Deflection	
Print Save	OK Cancel

 Define the material from Geometry | Materials using the standard steel Steel-A992--Fy50. Steel properties such as Fy and Fu are set automatically.

	Material Id	Label	E [kip/in^2]	Poisson Ratio	Density [lb/ft^3]	Tc [1/F]
1	1	Default	29000	0.3	489.024	6.5e-006
2	2	Steel-A992Fy50	29000	0.3	489.024	6.5e-006
4	Ann	Denne				
•	New	Rows Std Material	-		Print.,	Save

• Define the section W18x97 from Geometry | Sections using the AISC table.

				M	ember Sec	ctions						×
	Section Id	Label	lz [in^4]	ly [in^4]	J [in^4]	A [in^2]	Ay [in^2]	Az [in^2]	b (in)	d (in)	tf [in]	tw [in]
1	1	Default	1	1	1	1	1	1	0	0	0	0
2	2	W18X97	1750	201	5.86	28.5	9.951	16.095	11.1	18.6	0.87	0.535
4												•
1	New F	Rows Regular Se	ction Al	SC Table	NDS Tal	ble I	Rigid Link			Print.		Save
					Assign	active section	to currently se	lected mem	pers	Apply	/	Cancel

• Define the two nodes from Input Data | Nodes.

		No	ode Data		
	Node Id	× [ft]	Y [ft]	Z [ft]	Status
1	1	0	0	0	Normal 🧹
2	2	50	0	0	Normal
1					•
•	New Rows	Print	Save		OK

• Define the one beam from Input Data | Members

					Men	nber Data				×
[_	Member Id	Node-1	Node-2	Material	Section	Local Angle (deg)	Nonlinear	Status	-
	1	1	1	2	2: Steel-A992Fy50 🗸	2: W18X97 🗸	0	Linear 🗸	Normal 🤜	
	4								4	
	1	New F	Rows	Print	Save			OK	Cance	I

• Define the two supports from Input Data | Supports

				Su	pport Dat	а				×
	_	Node Id	6-DOFs Fixity Flag [0=free; 1=fixed; 2=unavailable]	Dx [in]	Dy [in]	Dz [in]	Dox [rad]	Doy [rad]	Doz [rad]	^
	1	1	111000	0	0	0	0	0	0	
	2	2	011000	0	0	0	0	0	0	
4	•									*
1		New R	cows Cut Selecte	d Rows	Print	Save		ОК	Cancel	

• Define both the dead and live line loads from Input Data | Line Loads

			Li	ne Load Dat	а			x
Load Cas	se: 3: Li	ve			~]		
	Member Id	Coordinate System	Direction	Start Value [kip/ft]	End Value [kip/ft]	Start Dist [% Length from member start]	End Dist [% Length from member start]	
1	1	Local 🗸	ΥΥ	-1	-1	0	1	
								-
4							•	
1	New R	ows Cut Selec	ted Rows	Print	Save	ОК	Cancel	

• Define the self-weight from Input Data | Self Weight. Make sure the self-weight acts in the negative global Y direction.

Self Weight	×
Consider self weight as load case:	
2: Dead	~
Self weight acts in global direction:	Global Y 🗸 🗸
Self weight multiplier (negative to reverse direction):	-1
OK	Cancel

 Set structural model as 2D Frame from Analysis | Analysis Options. Run Static Analysis to make static analysis results available for steel design.

Analysis Options			×
Structural Model:	2D Frame (X, Y, OZ)		~
Non-Linear Converge	nce Control		
Maximum iterations (P-Delta or nonlinear elements): 10	
Axial force tolerance	between P-Delta iterations:	0.5	%
Consider shear defo	rmation on members		
Number of segments fo	r member output:	20	
Use cracked section	n properties (Icr) for members	and finite elemen	ts
Stress averaging mode nodes of finite element	st Stress averaging fo	r all adjacent eler	ments 🗸
Use Kirchhoff thin pl (Uncheck this box to	ate bending formulation for re o use MITC4 thick plate bend	ctangular shells. ing forumlation fo	r shells)
Use incompatible for (Uncheck this box to	mulation for shell membrane a o use standard compatible for	actions or bricks. mulation for shells	s or bricks)
Solver Type			
 Double-precision 	Skyline solver (standard)		
Quad-precision 9	ikyline solver (for numerically	sensitive models)	
O Double-precision	Sparse solver (for large mode	els)	
Use Out-of (Use hard-o	-core solver drive space when there is not	enough RAM)	
🕑 Consider rigid diaph	ragm actions		
Run Static Analysis		ОК	Cancel

Define the steel member design criteria from Steel Design | Design Criteria | Member Design Criteria. Use "W" as the section prefix as we want to find the light W section. We could also use "W12, W18" for the section prefix if we would want to use either W12 or W18x sections. Make sure Cb = 0 so we will have the program calculate it automatically. Important: If 0 is entered for Lb for non-continuously braced, then Lb is taken as the member length. If the member is fully braced laterally, you must enter 0 for Lb.

				St	eel Men	nber	Design Cr	iteria							_ □
lote: En lote: En	iter 0 for Lux iter 0 for Lb	c Luy or Luz if you if the member is n	want to use the membe ot continuously braced	r length as laterally ar	any of ther nd you war	n. Ente it to use	er 0 for Cb if yo e the member	u want the length for	e program Lb, or if th	n to calcu ne memb	late it auto er is conti	omatica nuousl	ally. y brac	ed late	rally.
	Steel Criteria Id	Label	Section Prefix (e.g. W12, W14)	X-Sway?	Y-Sway?	Lb (ft)	Continuously Braced?	Сь	Lux [ft]	Luy (ft)	Luz [ft]	Кх	Кy	Kz	Max Unity Check Ratio
1	1	Default	W	Yes 🗸	Yes 🗸	25	No 🗸	0	0	0	0	1	1	1	1
															•
	#Ne	w Rows	#Print #Save	9			Ass	sign activ	e criteria t	o selecte	d membe	ers	#A	pply	#Cancel

• Define the steel member input from Steel Design | Design Input | Steel Members Input.

			Steel Member Inp	out			×
Steel desi	gn criteria:	1: Default		~	Apply to Sel	ected Rows	
	Membe	erld	Design Criteria		Exclusion		•
1	1			1		Included 🗸	
							-
•							
Print.	. Sav	/e			ОК	Cancel	

- Perform the steel design from Steel Design | Perform Design.
- View the steel design results from Steel Design | Design Result. By default, up to 10 candidate sections are available. The W18x97 happens to be the lightest section. Also notice that Cb is calculated automatically (Cb = 1.3). If desired, we could now update the member with a different section candidate, reanalyze the model and perform the steel design again.

You can also view the detailed step-by-step calculation procedures for the most critical load condition on each member.



Example 17: Design of Steel Column

Problem Description

Select an ASTM A992 W-shape with a 10-in nominal depth to carry the following load effects: Pu = 30 kips, Mux = 90 kip-ft, Muy = 12 kip-ft.

The unbraced length is 14 ft and the ends are pinned. Cb = 1.14. The member is non-sway. [Ref 32, Example H.4].

Suggested Modeling Steps

• Set proper units from Settings | Units & Precisions.

	ngintoreacha	meto	CONVERCEXIST	ng ui		Ciclea with that arric		ALCON /		eui /	
Geometry:						Properties					
Length:	ft	\sim	#.00	~	✓	Modulus (E, Fy, etc.):	kip/in^2	\sim	#.000E+00	\sim	✓
Dimension:	in	\sim	#.00	\sim	✓	Weight density:	lb/ft^3	\sim	#.0	\sim	✓
oads						Reinforcement. area:	in^2	~	#.00	~	✓
Force:	kip	\sim	#.000	\sim	✓	Stress:	lb/in^2	\sim	#.000E+00	~	✓
Linear force:	kip/ft	\sim	#.000	~	✓	Spring constants					
Moment	kip-ft	\sim	#.000	~	✓	Node Kx, Ky, Kz:	lb/in	~	#.000	~	✓
Linear moment:	kip-ft/ft	\sim	#.000	\sim	✓	Node Kox, Koy, Koz.:	lb-in/rad	\sim	#.000	~	✓
Surface force:	lb/ft^2	\sim	#.000	\sim	✓	Line Kx, Ky, Kz:	kip/in^2	~	#.000	~	✓
Displacement:	in	\sim	#.000E+00	~	✓	Area Kx, Ky, Kz:	kip/in^3	~	#.000	~	✓
Rotation	rad	\sim	#.000E+00	~	✓						
Temperature:	Fahrenheit	\sim	#.0	\sim	✓	Save as defaults fo	r future use				

 Define the material from Geometry | Materials using the standard steel Steel-A992--Fy50. Steel properties such as Fy and Fu are set automatically.

	Material Id	Label	E [kip/in^2]	Poisson Ratio	Density [lb/ft^3]	Tc [1/F]
1	1	Default	29000	0.3	489.024	6.5e-006
2	2	Steel-A992Fy50	29000	0.3	489.024	6.5e-006
•						•

Define the section W10x12 (or any W-shape) from Geometry | Sections using the AISC table.

					M	ember Seo	ctions						×
		Section Id	Label	lz [in^4]	ly [in^4]	J [in^4]	A [in^2]	Ay [in^2]	Az [in^2]	b [in]	d [in]	tf [in]	tw [in]
	1	1	Default	1	1	1	1	1	1	0	0	0	0
	2	2	W10X12	53.8	2.18	0.0547	3.54	1.8753	1.386	3.96	9.87	0.21	0.19
•													×
0		New F	Rows Regular Sect	ion Al	SC Table	NDS Tal	ble F	Rigid Link	lected mem	hers	Print.		Save
						iooigii				I	whhi		Cancer

• Define the two nodes from Input Data | Nodes.

		No	ode Data		
	Node Id	×[ft]	Y [ft]	Z [ft]	Status
1	1	0	0	0	Normal 🗸
2	2	14	0	0	Normal
•					•
1	New Rows	Print	Save		ОК
Round	d-off Coordinates	Epsilon = 1e-01	10		Cancel

• Define the one beam from Input Data | Members

				Men	nber Data				×
	Member Id	Node-1	Node-2	Material	Section	Local Angle (deg)	Nonlinear	Status	
1	1	1	2	2: Steel-A992Fy50 🗸	2: W10×12 🗸	0	Linear 🗸	Normal 🧹	
									v
u	New F	lows	Print	Save			OK	Cance	I

Define the one supports from Input Data | Supports. Please note the first node has X, Y
 Z, and OX DOFs fixed. The second node has Y and Z DOFs fixed. The fixity in OX
 direction at the first node is needed to ensure the stability of the 3D Frame.

			Sup	port Data	9			
_	Node Id	6-DOFs Fixity Flag [0=free; 1=fixed; 2=unavailable]	Dx [in]	Dy [in]	Dz [in]	Dox [rad]	Doy [rad]	Doz [rad]
1	1	111100	0	0	0	0	0	0
2	2	011000	0	0	0	0	0	0
1								
	New R	ows Cut Selected	Rows	Print	Save		OK	Cancel

Define the nodal loads from Input Data | Nodal Loads. Please note we enter the load effects as nodal loads as we do not have the exact load condition in the original example. We need to enter Cb manually later instead of letting the program to calculate it for us automatically.

	Node Id	Global Direction	Value [force: kip; moment:
1	1	OZ 🗸	
2	1	• OY	-12
3	1	×	30
4	2	oz	-90
5	2	OY	12
6	2	×	-30

 Define the load combination from Loads | Load Combinations. Make sure the "Perform Steel Design using this Load Combination" is checked.

Label: Case Factor Case Factor Perfound Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Perform Concrete Design using this Load Combination Check Total Load Deflection Check Live Load Deflection	x
Case Factor I Default I Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
 Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: Check Total Load Deflection Check Live Load Deflection 	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
 Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: Check Total Load Deflection Check Live Load Deflection 	
Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: Check Total Load Deflection Check Live Load Deflection	
 Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: Check Total Load Deflection Check Live Load Deflection 	-
 Perform P-Delta Analysis on this Load Combination Perform Steel Design using this Load Combination Perform Concrete Design using this Load Combination Sustained load factor: Check Total Load Deflection Check Live Load Deflection 	
Perform Concrete Design using this Load Combination Sustained load factor: O Check Total Load Deflection Check Live Load Deflection	
Sustained load factor: 0 Check Total Load Deflection Check Live Load Deflection	
Check Total Load Deflection	
Check Total Load Deflection	
Uneck Live Load Deflection	
Print Save OK Cancel	

• Set structural model as 3D Frame from Analysis | Analysis Options. Run Static Analysis to make static analysis results available for steel design.

Analysis Options						×		
Structural Model:	3D Fran	ne & Shell (6-D	OF)			\sim		
Non-Linear Converge	nce Cont	trol						
Maximum iterations (P-Delta c	or nonlinear ele	ements):	10				
Axial force tolerance	Axial force tolerance between P-Delta iterations: 0.5 %							
Consider shear defo								
Number of segments fo	or membe	r output:		20				
Use cracked section	n properti	ies (Icr) for me	mbers a	nd finite elemen	ts			
Stress averaging mode at nodes of finite elements: Stress averaging				all adjacent eler	ments	\sim		
Use Kirchhoff thin pl (Uncheck this box to	late bend b use MIT	ling formulation FC4 thick plate	n for rec e bendir	tangular shells. Ig forumlation fo	r shells]		
Use incompatible for Uncheck this box to	rmulation o use sta	for shell meml ndard compat	orane ac ble form	tions or bricks. ulation for shell:	s or bric	ks)		
Solver Type								
 Double-precision 	Skyline	solver (standa	rd)					
O Quad-precision S	Skyline so	olver (for nume	rically se	ensitive models)				
O Double-precision	Sparse :	solver (for larg	e model:	s)				
Use Out-of-core solver (Use hard-drive space when there is not enough RAM)								
Run Static Analysis				ОК	Cancel			

 Define the model design option from Steel Design | Model Design Criteria. Make sure to check the options "Consider moment magnification factor B1" and "Adjust deflection ratios for each member based on the ratio of analysis section Ix over design candidate section Ix".

	Model Steel Desig	gn Options			×					
	Design code:	AISC 360-22 (16th Editio	n) LRFD		~					
	🗌 Use Direct Ar	nalysis Method								
	Consider mor (P-delta effec	nent magnification factor l t associated with individu	B1 al member curvature)	I						
Always use 1.0 for Cm (Uncheck this box to compute automatically)										
	Check capacity at column ends only									
	🗌 Only use sec	tions defined in Steel Des	ign Design Criteria	Section Pool						
	Connector dista	nce for double		0	ft					
	Maximum numbe	er of steel section		10						
	Total load deflec e.g. 240 means	ction denominator the total deflection will be	limited to L/240:	240]					
	Live load deflec e.g. 360 means	tion denominator the total deflection will be	limited to L/360:	360						
	Adjust deflec section Ix ov	tion ratios for each memb er design candidate sectio	er based on the ratio on Ix	of analysis						
			ОК	Cancel						

Define the steel member design criteria from Steel Design | Design Criteria | Member Design Criteria. Use "W10" as the section prefix as we want to find the lightest W10 section. For this example, we manually enter Cb = 1.14 (The program would calculate Cb automatically if Cb is entered 0.0). Also, since we set Lb, Lux, Luy and Luz to be zero, the program will use the member actual length for each of them.

• Define the steel member input from Steel Design | Design Input | Steel Members Input.

		Steel Member Input	
Steel desi	gn criteria: 1: Default		✓ Apply to Selected Rows
	Member Id	Design Criteria	Exclusion
1	1	1	Included 🗸
•			•

- Perform the steel design from Steel Design | Perform Design.
- View the steel design results from Steel Design | Design Result. By default, up to 10 candidate sections are available. The original section W10x12 is not adequate with critical ratio = 9.64318 (> 1.0). The first section that is adequate is W10x33 with critical ratio = 0.978576 (< 1.0). At this point, you can update the member section to be W10x33, reanalyze the model and perform steel design again.

You can also view the detailed step-by-step calculation procedures for the most critical load condition on each member.

Seel Drugs Reuk	-		×
Memberin Length (M) Status Citical Radio Load Carebination Distance/ (x000) Status Status Citical Radio Status Status Citical Radio Status Status Status Citical Radio Status Status Citical Radio Status Status Citical Radio Status Status <td>Cb Cmx</td> <td>Day</td> <td>1</td>	Cb Cmx	Day	1
1 1 1 14 W1042 NG 964318 Defaul 1 964318 0 0 0 0 30 30 30 40 112 0 0 0 0 174668 124346 645753 55.259 443064 0.7 0.466667	1.14	1 1	
0			•
Tyre: Serve: Procedure in Vited Procedure in V			- 1
See Deign Result	-		×
Member D Lengh (H) Section Status Critical Load Combination Detector Analytics Status (1000) ng/Rate Plants Status (1000) ng/Rate St	Cb Cmx	Cmy	-
1 1 14 V10422 0K 0978576 Default 1 0978576 0 0 0 0 20 90 -12 0 0 0 0 25252 13659 525 64651 19638 0.7 046667	1.14	1 1	
e		•	v

Steel Calculation Procedure

General Info

File Name	C:\temp2\build\cgiSol\output\UnicodeReleasex64\Examples\Example-17
Member Id	1
Design Code	AISC 360-22 (16th edition) LRFD
Using Direct Analysis Method	No
Consider Multiplier B1 for P-delta Effect	Yes
Total Load Deflection Limit	1 / 240
Live Load Deflection Limit	1 / 360
Date & Time	11/27/2023 19:26

Section Property - W10X33

Property	Value	Unit	Property	Value	Unit	Property	Value	Unit
A = Ag	9.71	in^2	bf	7.96	in	tf	0.435	in
tw	0.29	in	d	9.73	in	h / tw	27.1	
Cw	791	in^6	h0	9.3	in	rts	2.2	in
Zx	38.8	in^3	Sx	35	in^3	lx	171	in^4
rx	4.19	in	Zy	14	in^3	Sy	9.2	in^3
ly	36.6	in^4	ry	1.94	in	J	0.583	in^4

Design Input

Input	Value	Unit	Input	Value	Unit	Input	Value	Unit
Pu = Pr	30	kips	Mux = Mxr	-90	kip-ft	Muy = Myr	-12	kip-ft
Cmx	1		Cmy	1		Vux	0	kips
Vuy	0	kips	Fy	50	ksi	Cb	1.14	
Lb	14	ft	Kx	1		Ку	1	
Kz	1		Lx	14	ft	Ly	14	ft
Lz	14	ft	Total Dy	0	in	Live Dy	0	in
			Analysis			Deflection		
L	14	ft	Section W10X12 Ix	53.8	in^4	Adjustment Ratio	0.31462	

* Lcx = Kx * Lx; Lcy = Ky * Ly; Lcz = Kz * Lz

Axial Capacity Calculation

Step	Equation	Value	Note				
Checking flange slenderness	Checking flange slenderness						
	b = bf / 2	3.98 in					
	b / tf	9.1494					
	$\lambda_r = 0.56 \sqrt{\frac{E}{F_y}}$	13.487					
The section has non-slender flange e	The section has non-slender flange element						
Checking web slenderness							
	b / t = h / tw	27.1					

$\lambda_r = 1.49 \sqrt{\frac{E}{F_y}}$	35.884							
The section has non-slender web								
Compressive strength to account for flexural buckling								
$\frac{K_x L_x}{r_x}$	40.095							
$\frac{K_y L_y}{r_y}$	86.598							
$\frac{KL}{r} = \max\left(\frac{K_x L_x}{r_x}, \frac{K_y L_y}{r_y}\right)$	86.598							
$F_e = \frac{\pi^2 E}{\left(\frac{KL}{r}\right)^2}$	38.167 ksi	Eq.E3-4						
$4.71\sqrt{rac{E}{F_y}}$	113.43							
$\frac{KL}{r} \le 4.71 \sqrt{\frac{E}{F_y}}$								
$F_n = \left(0.658^{\frac{F_y}{F_e}}\right) F_y$	28.896 ksi	Eq.E3-2						
$P_n = F_n A_g$	280.58 kips	Eq.E3-1						
Compressive strength to account for torsional and flexural-torsional buckling								
$F_e = \left(\frac{\pi^2 E C_w}{L_{cz}^2} + GJ\right) \frac{1}{I_x + I_y}$	70.092 ksi	Eq.E4-2						
$\frac{F_y}{F_e}$	0.71335							
$\frac{F_y}{F_e} \le 2.25$								
$F_n = \left(0.658^{\frac{F_y}{F_e}}\right) F_y$	37.094 ksi	Eq.E3-2						
$P_n = F_n A_g$	360.18 kips	Eq.E4-1						
Flexural buckling controls: Pn	280.58 kips							
$\phi_c P_n$	252.52 kips							

Moment Magnification Calculation

Step	Equation	Value	Note

Moment magnifier B	1 for P-delta effects	in local x direction
--------------------	-----------------------	----------------------

5		
$P_{e1} = \frac{\pi^2 E I^*}{(K_1 L)^2}$	1734.1 kips	Eq.A-8-5
$B_1 = \frac{C_m}{1 - \alpha P_r / P_{e1}} \ge 1$	1.0176	Eq.A-8-3
Magnified Mux = Mux * B1	-91.584 kip-ft	
Moment magnifier B1 for P-delta effects in local y direction		
$P_{e1} = \frac{\pi^2 E I^*}{(K_1 L)^2}$	371.16 kips	Eq.A-8-5
0		

 Magnified Muy = Muy * B1	-13.055 kip-ft	
$B_1 = \frac{C_m}{1 - \alpha P_r / P_{e1}} \ge 1$	1.0879	Eq.A-8-3

Major Flexure Capacity Calculation

Step	Equation	Value	Note
Web compactness:	L		
	$\lambda = \frac{h_c}{t_w}$	27.1	
	$\lambda_{pw} = 3.76 \sqrt{\frac{E}{F_y}}$	90.553	
	$\lambda_{rw} = 5.70 \sqrt{\frac{E}{F_y}}$	137.27	
Web is compact			
Flange compactness:			
	$\lambda = \frac{b_f}{2t_f}$	9.1494	
	$\lambda_{pf} = 0.38 \sqrt{\frac{E}{F_y}}$	9.1516	
	$\lambda_{rf} = 1.0 \sqrt{\frac{E}{F_y}}$	24.083	
Flange is compact			

N	Mnx to account for yielding					
	$M_n = M_p = F_y Z_x$	161.67 kip-ft	Eq.F2-1			
N	Inx to account for flange local buckling					
	$\lambda < \lambda_{pf}$					
	$M_n = M_p$	161.67 kip-ft				
N	Inx to account for lateral-torsional buckling					
	$L_p = 1.76 r_y \sqrt{\frac{E}{F_y}}$	6.8525 ft	Eq.F2-5			
	For I section, c	1				
	$L_{r} = 1.95r_{ts}\frac{E}{0.7F_{y}}\sqrt{\frac{Jc}{S_{x}h_{o}} + \sqrt{\left(\frac{Jc}{S_{x}h_{o}}\right)^{2} + 6.76\left(\frac{0.7F_{y}}{E}\right)^{2}}}$	21.776 ft	Eq.F2-6			
	$M_n = M_p = F_y Z_x$	161.67 kip-ft	Eq.F2-1			
s	Since Lp < Lb < Lr					
	$M_n = C_b \left[M_p - (M_p - 0.7F_y S_x) \left(\frac{L_b - L_p}{L_r - L_p} \right) \right] \le M_p$	151.77 kip-ft	Eq.F2-2			
	Controlling nominal flexural strength Mnx	151.77 kip-ft				
	$M_{cx} = \phi_b M_{nx}$	136.59 kip-ft				

Minor Flexure Capacity Calculation

Step	Equation	Value	Note
Mny to account for yielding			
	Fy * Zy	58.333 kip-ft	
	Fy * Sy	38.333 kip-ft	
	$M_n = M_p = F_y Z_y \le 1.6 F_y S_y$	58.333 kip-ft	Eq.F6-1
Mny to account for lateral-torsional bu	uckling		
	$\lambda < \lambda_{pf}$		
	$M_n = M_p$	58.333 kip-ft	
	Controlling nominal flexural strength Mny	58.333 kip-ft	
	$M_{cy} = \phi_b M_{ny}$	52.5 kip-ft	

Flexural and Axial Interaction Calculation

Step	Equation	Value	Note
	$\frac{P_r}{P_c} = \frac{P_u}{\phi_c P_n}$	0.1188	
	$\frac{P_r}{P_c} < 0.2$		
	$\frac{P_r}{2P_c} + \left(\frac{M_{rx}}{M_{cx}} + \frac{M_{ry}}{M_{cy}}\right) \le 1.0$	0.97858	Eq.H1-1b
Axial-flexural strength: OK			

Major Shear Capacity Calculation

Step	Equation	Value	Note
	$A_w = dt_w$	2.8217 in^2	
Computing Cv for major axis using G	2.1		
	$k_v = 5.34$		
	h/t_w	27.1	
	$2.24\sqrt{E/F_y}$	53.946	
	$h/t_w \le 2.24 \sqrt{E/F_y}$		
	$C_{v1} = 1.0$		Eq.G2-2
Major shear strength			
	$V_n = 0.6F_y A_w C_{v1}$	84.651 kips	Eq.G2-1
	$h/t_w \le 2.24 \sqrt{E/F_y}$		
	$\phi_v = 1.00$		
	$\phi_v V_n$	84.651 kips	
	$\frac{V_u}{\phi_v V_n}$	0	
Shear strength (major axis): OK			

Minor Shear Capacity Calculation

Step	Equation	Value	Note

$A_w = 2b_f t_f$	6.9252 in^2	
Computing Cv2 for weak axis using G2.2		
$k_v = 1.2$		
$h/t_w = b/t_f$	9.1494	
$1.10\sqrt{k_v E/F_y}$	29.02	
$1.37\sqrt{k_v E/F_y}$	36.143	
$h/t_w \le 1.10\sqrt{k_v E/F_y}$		
$C_{v2} = 1.0$	1	Eq.G2-9
Minor shear strength		
$V_n = 0.6F_y b_f t_f C_{v2}$	207.76 kips	Eq.G6-1
$\phi_v = 0.90$		
$\phi_v V_n$	186.98 kips	
$\frac{V_u}{\phi_v V_n}$	0	
Shear strength (minor axis): OK		

Total Load Deflection Check

5	Step	Equation	Value	Note
	Tota	I Deflection Limit = L / (Total Deflection Denominator)	0.7 in	
	Total Deflection Ratio = (Tota	al Dy * Deflection Adjustment Ratio) / (Total Deflection Limit)	0	
1	Fotal Load Deflection: OK			

Live Load Deflection Check

s	tep	Equation	Value	Note
	Liv	ve Deflection Limit = L / (Live Deflection Denominator)	0.46667 in	
	Live Deflection Ratio = (Live Dy	* Deflection Adjustment Ratio) / (Live Deflection Limit)	0	
L	ive Load Deflection: OK			

Example 18: Response Spectrum Analysis of a Beam

Problem Description

A simply supported beam (L = 20 ft) [Ref 25, Problem.4.8] is subjected to a response spectrum in the vertical direction at both supports. The beam section is of size 1.458 in x 14 in. Material: E = 30 e6 psi, density = 6538.08 lb/ft³ Damping: 0.0



Spectrum Definition:

Period (sec)	Spectral Acceleration (g)
0.125	1.45300
0.143	1.42860
0.164	1.63990
0.167	1.66670
0.200	2.00000

Suggested Modeling Steps

• Set proper units from Settings | Units & Precisions.

IECK INE DOX IO INE	ngni oreach u	nicio	convert existi	ng ua	ila assi	Joialed with that unit.		лески		earr	-511
Geometry:						Properties					
Length:	ft	\sim	#.00	\sim	✓	Modulus (E, Fy, etc.):	kip/in^2	\sim	#.000E+00	\sim	✓
Dimension:	in	\sim	#.00	\sim	✓	Weight density:	lb/ft^3	~	#.0	\sim	✓
oads						Reinforcement. area:	in^2	~	#.00	~	✓
Force:	kip	\sim	#.000	\sim	✓	Stress:	lb/in^2	~	#.000E+00	~	✓
Linear force:	kip/ft	~	#.000	\sim	✓	- Spring constants					
Moment	kip-ft	~	#.000	\sim	~	Node Kx, Ky, Kz:	lb/in	\sim	#.000	\checkmark	✓
Linear moment	kip-ft/ft	~	#.000	\sim	✓	Node Kox, Koy, Koz.:	lb-in/rad	~	#.000	~	✓
Surface force:	lb/ft^2	~	#.000	\sim	✓	Line Kx, Ky, Kz:	kip/in^2	~	#.000	\checkmark	✓
Displacement	in	~	#.000E+00	\sim	✓	Area Kx, Ky, Kz:	kip/in^3	~	#.000	$\mathbf{\vee}$	✓
Rotation	rad	\sim	#.000E+00	\sim	✓						
Temperature:	Fahrenheit	\checkmark	#.0	\sim	~	Save as defaults fo	r future use				

Define the material from Geometry | Materials

			Materials					
_	Material Id	Label	E [kip/in^2]	Poisson Ratio	Density [lb/ft^3]	Tc (1/F)		
1	1	Default	30000	0.3	6538.08	6.5e-006		
							•	
•						•		
	New	Rows Std Material]		Print	Save	_	
New Rows Std Material Print Save								

• Define the section from Geometry | Sections using the Regular Section button.

				Me	mber Sect	tions							×
	Section Id	Label	lz [in^4]	ly [in^4]	J [in^4]	A [in^2]	Ay [in^2]	Az [in^2]	b [in]	d [in]	tf [in]	tw [in]	1
1	1	Default	0.999999	0.999999	0.999999	1	1	1	0	0	0	0	
2	2	Rect37x355.6	333.096	3.60621	13.4793	20.3937	16.9947	16.9947	1.45669	14	0	0	
•												ł	•
1	New R	ows Regular Section	on AIS	CTable	NDS T	able	Rigid Lin	k		Print.		Save	
		Export AISC Ta	ble Import	AISC Table	Assign	n active sectio	n to currently s	elected memi	pers	Apply	/	Cancel	

• Define the two nodes from Input Data | Nodes.

		No	de Data		
	Node Id	×[ft]	Y [ft]	Z [ft]	Status
1	1	0	0	0	Selected
2	2	20	0	0	Selected 🗸
1	New Rows	Print	Save		OK
Round	l-off Coordinates	Epsilon = 1e-01)		Cancel

• Define the one beam from Input Data | Members. Make sure the correct material and section are used for this beam.

						Member [Data					×
		Member Id	Node-1	Node-2	Material	Section	Local Angle (deg)	Nonlinear	Activation	Self Weight	Status	^
	1	1	1	2	1: Default 🧹	2: Rect37x355.6 🗸	0	Linear 🗸	Active 🗸	Include 🗸	Normal 🧹	
	(•
1		New	/ Rows	Print	Save					ОК	Cancel	

• Select the beam we just created. Use Edit | Split Members to split it to 10 elements of equal lengths.

	Split Selected	d Members	×
 Divide selected mer Segments: 10 	nbers into segment	s of equal length	
O Divide selected mer Enter distance list (e divided at these dist	nbers by specifying .g. 12, 3@20, 2@15 ances:	g a distance list). Selected member	s will be
Distance list:			ft
 Merge nodes and a 	lements (recomme	nded)	
Note: It is also recom running analysis in oro Edit -> Renumber -> P	nended that you rei ler to miminze mem enumber Nodes	number nodes in the ory usage. You can	model prior to do that from
		OK	Cancel

• Use Assign | Supports to assign supports to node 1 and 2

	Assign	Supports	
Pinned	Fixities Global DOE	Enforced o	lisplacement
) Fixed	√ ×	0	in
ORoller	✓ Y	0	in
Others	✓ Z	0	in
	OX	0	rad
	OY	0	rad
	OZ	0	rad
	🖌 Assign en	tries to current	ly selected nodes
		Assign	Cancel

• From Loads | Response Spectra Library, define the spectrum.

		R	esponse Spectra Lil	brary		l
Spectrun	n Name			Number of Points	Add	
Sample I	Inple Response Spectrum 10					
_nopra-t	Example-13.	.11		8	Moully	
JBC 91	_0.4g 94 SOIL T	YPE1		2	Delete	
Sap-Exa	mple1-022			33		
Abaqus-	1.4.8			5		
					Generate	
		Resp	onse Spectrum Dat	ta	×	
	Spectrum	Name: Abaqus-1	.4.8			
		Period (sec)	Spectral Acceleration (g)	Spectral Acceleration (in/sec^2)	^	
	1	0.125	1.45300	560.989		
	2	0.143	1.42860	551.568		
	3	0.164	1.63990	633.149	OK	
	4	0.167	1.66670	643.496		
	5	0.200	2.00000	772.180	Canaal	
_					Cancer	
				r		
	1	New Rows C	ut Selected Rows F	Print Save		

We will convert self-weight to calculate masses. So from Loads | Self Weights, define the self-weight multiplier as -1 in Global Y direction. By default, self-weight will be of load case "Default", which is included in the default load combination "Default".

Self Weight		×
Consider self weight as load case:		
1: Default		\sim
Self weight acts in global direction:	Global Y	~
Self weight multiplier (negative to reverse direction):	-1	
ОК	Cancel	

• Set structural model as 2D Frame from Analysis | Analysis Options. We will not consider shear deformation on members.

Analysis Options			×
Structural Model:	2D Frame (X, Y, OZ)		\sim
Non-Linear Converge	nce Control		
Maximum iterations (P-Delta or nonlinear elements):	10	
Axial force tolerance	between P-Delta iterations:	0.5	%
Consider shear defo	rmation on members		
Number of segments fo	r member output:	20	
Use cracked section	n properties (lcr) for members ar	nd finite element	's
Stress averaging mode nodes of finite element	s: Stress averaging for	all adjacent elen	nents 🗸
Use Kirchhoff thin pl (Uncheck this box to	ate bending formulation for rec ouse MITC4 thick plate bendin	tangular shells. g forumlation fo	r shells)
Use incompatible for (Uncheck this box to	mulation for shell membrane ac o use standard compatible form	tions or bricks. ulation for shells	or bricks)
Solver Type			
 Double-precision 	Skyline solver (standard)		
Quad-precision S	kyline solver (for numerically se	ensitive models)	
O Double-precision	Sparse solver (for large models	5)	
Use Out-of- (Use hard-o	core solver drive space when there is not e	nough RAM)	
🗹 Consider rigid diaph	ragm actions		
Run Static Analysis		ок	Cancel

• Frequency analysis must be run prior to response spectrum analysis. So run frequency analysis from Analysis | Frequency Analysis. We will compute the first 10 modes.

Frequency Analysis	×
Load combination for frequency analysis:	
1: Default	~
Convert loads to masses (only forces in gravity direct masses and applied to all available translational mas	ion will be converted to ss DOFs)
Note: If model response is nonliear under this load comb will be performed for stiffness modification prior to freque	ination, a static analysis ncy analysis.
Number of modes (eigenvalues and eigenvectors):	10
Number of iteration vectors (use larger value for better convergence but longer solution time)	18
Tolerance of eigenvalues: (typically 0.001 or smaller)	0.001
Maximum number of subspace iterations permitted (typically 18 or greater)	18
Run Frequency Analysis Ol	K Cancel

• Run response spectrum analysis from Analysis | Response Spectrum Analysis. Make sure we use the correct spectrum and apply directional factor only in Y direction.

Mode Combine	ition Method:	SRSS	~		
Critical Dampin	g Ratio:	0			
		Spectrum		Directional Factor	
<direction:< td=""><td>Sample Resp</td><td colspan="2">Sample Response Spectrum</td><td>0</td><td></td></direction:<>	Sample Resp	Sample Response Spectrum		0	
r' Direction:	Abaqus-1.4.8	Abaqus-1.4.8		1	
Z Direction: Sample Response		onse Spectrum	~	0	
]Use Domina	nt Mode in Each [lirection for Signage			
_			1		

 After the response spectrum analysis is done, we can then exam results such as Analysis Results | Eigen Values, Analysis Results | Modal Combinations | Nodal Displacements, Analysis Results | Modal Combinations | Member End Forces and Moments etc.

The following is a result comparison between Real3D and the reference [Ref 25].

	Real3D	Reference
First Mode Frequency	6.0979 Hz	6.098 Hz
Midspan Displacement Dy	0.5446 in	0.549 in
Midspan moment	9.40764e5 lb-in (78.397 kip-ft)	9.493e5 lb-in

_								
	Mode	Period (sec)	Frequency (cycle/sec)	Circular Frequency (rad/sec)	Eigenvalue (rad/sec)^2	Error Measure		
1	1	0.1640	6.0979	38.3144	1467.9969	2.7492e-012		
2	2	0.0410	24.3890	153.2407	2.3483e+004	2.0678e-013		
3	3	0.0182	54.8449	344.6005	1.1875e+005	2.7098e-013		
4	4	0.0103	97.3263	611.5194	3.7396e+005	8.6788e-013		
5	5	0.0087	114.7950	721.2783	5.2024e+005	1.1761e-015		
6	6	0.0066	151.3427	950.9145	9.0424e+005	3.6470e-014		
7	7	0.0046	215.4529	1353.7302	1.8326e+006	2.7169e-013		
8	8	0.0044	226.7634	1424.7963	2.0300e+006	1.8767e-014		
9	9	0.0035	285.9684	1796.7921	3.2285e+006	1.3637e-013		
10	10	0.0030	333.1481	2093.2311	4.3816e+006	5.4848e-013		
			Show selected only Print Save				Close	
---	---------	------------	-------------------------------	------------	------------	------------	------------	--
	Node Id	Dx [in]	Dy [in]	Dz [in]	Dox [rad]	Doy [rad]	Doz [rad]	
1	1	0.000e+000	3.649e-011	0.000e+000	0.000e+000	0.000e+000	7.129e-003	
2	2	0.000e+000	3.649e-011	0.000e+000	0.000e+000	0.000e+000	7.129e-003	
3	3	0.000e+000	1.683e-001	0.000e+000	0.000e+000	0.000e+000	6.780e-003	
1	4	0.000e+000	3.201e-001	0.000e+000	0.000e+000	0.000e+000	5.767e-003	
5	5	0.000e+000	4.406e-001	0.000e+000	0.000e+000	0.000e+000	4.191e-003	
6	6	0.000e+000	5.180e-001	0.000e+000	0.000e+000	0.000e+000	2.204e-003	
,	7	0.000e+000	5.446e-001	0.000e+000	0.000e+000	0.000e+000	2.515e-017	
3	8	0.000e+000	5.180e-001	0.000e+000	0.000e+000	0.000e+000	2.204e-003	
э	9	0.000e+000	4.406e-001	0.000e+000	0.000e+000	0.000e+000	4.191e-003	
0	10	0.000e+000	3.201e-001	0.000e+000	0.000e+000	0.000e+000	5.767e-003	
1	11	0.000e+000	1.683e-001	0.000e+000	0.000e+000	0.000e+000	6.780e-003	

	Member End Results - Response Spectrum Modal Combinations									
		Show selected only Print Seve							;	
	Member Id	Distance (%L)	Fx (Axial) [kip]	Fy (Major Shear) [kip]	Fz (Minor Shear) [kip]	Mx (Torsion) [kip-ft]	My (Minor Moment) [kip-ft]	Mz (Major Moment) [kip-ft]		
1	1	0.000	0.000	12.154	0.000	0.000	0.000	0.000		
2		1.000	0.000	12.154	0.000	0.000	0.000	24.307		
3										
4	2	0.000	0.000	10.927	0.000	0.000	0.000	24.307		
5		1.000	0.000	10.927	0.000	0.000	0.000	46.119		
6										
7	3	0.000	0.000	8.711	0.000	0.000	0.000	46.119		
8		1.000	0.000	8.711	0.000	0.000	0.000	63.396		
9										
10	4	0.000	0.000	5.688	0.000	0.000	0.000	63.396		
11		1.000	0.000	5.688	0.000	0.000	0.000	74.533		
12										
13	5	0.000	0.000	2.012	0.000	0.000	0.000	74.533		
14		1.000	0.000	2.012	0.000	0.000	0.000	78.397		
15										
16	6	0.000	0.000	2.012	0.000	0.000	0.000	78.397		
17		1.000	0.000	2.012	0.000	0.000	0.000	74.533		
18										
19	7	0.000	0.000	5.688	0.000	0.000	0.000	74.533		
20		1.000	0.000	5.688	0.000	0.000	0.000	63.396		
21										
•								•	F.	

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